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A MICRO Potpourri

While cleaning out my desk, as part of adding office space to MICRO, I uncovered a vast cache of notes that I had written to myself: little things which I wanted to pass on to MICRO's readers.

Canadian Mail: There seem to be problems with the Canadian mail service. In recent months we have been receiving more reports of non-delivery from our northern neighbors than from all of the US subscribers. We hope that the service gets better, and for now can only counsel patience. If you magazine does not reach you by the middle of the month, then complain to your postal service.

Mailing Date: MICRO is always in the mail before the first of the issue month. The actual mailing date varies as a function of the month, but is generally between the 24th and 28th. The Second Class mail, in the US, is *supposed* to get to all points within a week.

Limerick Contest: Since I have been declared ineligible by my staff to officially enter the MICRO limerick contest [a most unfair rule I think], I am going to excercise editorial perogative, if not editorial judgment, and present it here!

> A clever programmer named Mike Rowe, Said, "I get double use from each MICRO. First I learn what to do With my Sixty-Five-Oh-Two, Then I use it to paper train my crow!

[Now, don't you just know that you can do better than that? Only a few weeks left to get your entry in.] Mike Rowe: The first issue of MICRO, in October 1977, contained the following 'biographical' notes about Mike Rowe: 'He prefers hexadecimal notation since he has eight fingers on each hand', and is a 'Computer consultant for the Starship Enterprise'. Apparently some readers missed the first issue, and/or have never said the name out loud and discovered the hidden meaning. Mike Rowe is, of course, the name used to indicate that an article has been prepared by one or more members of the MICRO Staff from material supplied by others. The Software Catalog is an example. We have been surprised at the amount of mail we get addressed to Mike Rowe. Since 1977 we have discovered at least three others: Michael Roe - a subscriber; Mike Rowe Productions - also a

subscriber; and Mike Rowe who, according to the newspaper, is the best stock car driver in Maine. If you happen to know of any other 'Mike Rowe', we would like to hear about him.

MICRO Advertising and Advertisers: Advertising is very important to MICRO for two reasons: first, it provides some very important and timely information about what is available, and, second, it supports the magazine. The reason that MICRO has been able to grow from 28 to 84 pages, has been due to the terrific support of the advertisers. We hope this will continue to grow. You can help. All it takes is informing an advertiser that you 'Saw it in MICRO'. That's all. Advertisers do not generally have any simple way to determine the effectiveness of a particular ad. Feedback from the buying public is the most effective way of telling an advertiser that his ad is working. So, when you place an order, please mention MICRO.

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Pubert M. Trip



Cover Artist Terry Spillane

Graphic Data Retrieval Systems

This month's cover shows one type of Graphic Data Retrieval System: a fire department system to keep track of the equipment available for meeting various emergency conditions. While the concept is not new or specific to micros, it is a technique which can have broad application and which is quite suited to the display oriented microcomputers.

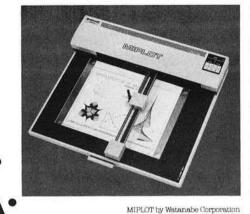
A GDRS basically combines graphic data, such as a map, with alphanumeric data. In the cover example, a map of the section of the city which contains an emergency condition, in this case a fire, is displayed to quickly show the operator the locations of relevant resources: a fire station, hospital, police, ambulance, etc. The status of each potential resource is given as alphanumeric information. As the operation progresses, this information can be continually updated either manually via a keyboard or, in a fancy system, automatically via various devices which would track the vehicles. This is a very dramatic example of the technique. Many other less dramatic but nonetheless important uses can be conceived for GDRS technique. The flow of material through any process, from an oil pipe line to a auto production facility, can be tracked and displayed. The operator can 'zoom in' on any particular part of the operation which is of interest. The program can automatically display whatever portions of the process are most critical at any time.

One of the nice aspects of performing a GDRS task on a micro is that the graphics do not generally have to be very fancy. A simple set of character graphics: horizontal, vertical, and diagonal lines, can usually provide all of the detail necessary.

The GDRS method can be used to solve many different types of problems. Think about it application in your areas of interest. It can be an effective and efficient method.

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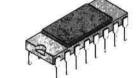




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SYM-1 Memory Search and Display

Add these two new commands to your SYM Monitor. They make it easy to locate any string in memory and provide a means to display data as ASCII when desired.

Nicholas Vrtis

Here are two more extensions for the SYM monitor. They are relocatable, and do not use any memory other than that normally used by the monitor. I decided to write these two software "tools" because I kept needing them and no one else seemed to be writing anything close to what I needed. The memory search routine was written because I needed some easy way to find locations in programs after I have relocated them. I don't have a printer, so after I have made a couple of patches and moves, it is sometimes difficult to find a particular place in the program. The command has also turned out to be helpful when you have to find references to a particular address so you can change it, as I had to do when I got the new monitor ROM.

The memory display routine was developed because I needed some easy way to look at messages, source lines, and other character type data in memory. This was especially true when I started working on a Tiny Basic Intermediate Language Assembler some time ago. The SYM monitor just doesn't have any way of displaying memory as characters instead of hex digits, and I have trouble recognizing ASCII as two hex digits.

The memory search routine will handle up to an eight byte search argument. This is normally entered in hex after the prompt from the routine. If you want, you can enter a slash instead of the two hex digits. This indicates a "wild" character to

the program. The definition of a "wild" character is that the position is counted, but any character is a valid match. This does not mean that you can't search for a slash character. The program will look for a slash if you enter it in hex as \$2F. This means that the search argument "20/OC" will find the first occurance of any jump to a subroutine on page \$OC, but "202FOC" would only find a jump to the subroutine at \$C2F. This neat little programming trick is accomplished with a "byte used bit map" (how's that for a three dollar phrase?). In simple terms, each bit is SCPBUD corresponds to one byte in SCPBUF where the search key is saved. If the bit is on, it indicates that a "wild" character was entered in that position. A zero indicates a normal character. The distinction between a slash and \$2F is actually made by INBYTE. The slash is non-hex, so INBYTE returns with the carry set. If the overflow is set, then the second character was the non-hex and it is an error. If the equal is set the character was the carriage return, and the program uses that to mean the end of the search argument. Finally, if none of the above is true, then the character that was entered is compared to a slash (INBYTE conveniently leaves the character in 'A'). For the slash, the carry is rolled into the bit map, setting the bit to a one. For normal hex bytes entered, the carry is clear on return from INBYTE, so when the rotate is done, a zero is set into the bit. The only other check made on input is to watch for more than eight bytes being entered. The beeper is

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beeped, and the character is ignored once eight have been accepted.

To perform the search, the program moves the bit map to a work area, since it will be destroyed in the process of the search. Each time we want to make a comparison between the key and memory, we first rotate one bit from the bit map work area into the carry. If the carry is set after the rotate, then the bit was on, and the program just pretends it got an equal compare. If the carry wasn't set, then the search byte is compared to memory for an equal. Simple, isn't it? Each time an unequal is found, the search address is incremented, and the search starts from position one of the key again.

Once the search argument is found, it is simple to output the address and then the data from memory (not from the search key, since it has the slashes in it).

There are a couple of not so obvious points to mention. The input search key, the key length, and the bit map are retained in the SYM RAM scope buffer area. This means some good news, and some bad news. The good news is that provided you don't do any output to the LED's, the argument will still be there the next time you use the routine. Since the U4 option with no parameters entered starts at the last used location plus one, using this option and entering a carriage return immediately for the search key will find the next occurance of that string. The bad news is that the routine won't work if you

are using the hex keypad for entry. Actually, the three parameter option will work since it doesn't do any I/O until after it has hit the end of memory, or found the string. The problem is that any time you do output to the LED's, that character also gets rotated into the scope buffer area, so the process of entering the search key shifts it over. If you are using the hex keypad and want to use the search routine, you will have to supply a 10 byte work area someplace else.

Finally, the value of "end of memory" is set to \$0F at location \$211 for my 4K system. If you have more or less memory, set this to the highest page number in your system.

As I mentioned earlier, the memory display routine is primarily designed for displaying ASCII type information. It has also turned out to be somewhat useful as a normal memory display since it displays more bytes per line than does the Verify command. Another advantage is that it ends with the "OLD" address pointing to the next location after the last one displayed. This means that repeated calls to the command without any argument will continue displaying memory.

The display format is a typical dump format. Sixteen bytes of data are displayed, first in hex, and then as alpha. Before the alpha is output, though, it is checked to make sure that it is a displayable character. As written, this program translates control characters, lower case character, and anything with the high order bit on, to an underscore. On some terminals this will display as the backarrow. The purpose is to occupy a position with displayable characters so you can count how many characters in you are from the start of the line. If your terminal will display lower case, you may want to change location \$30C to the highest displayable character for your terminal (lower case z is \$7A). I would not recommend by-passing the translation of the control characters. At best, most terminals don't even print a space in their place, and at worst, they do unexpected things which make reading the line difficult.

For those of you who have put up the other monitor extensions from my article in the August issue, these routines can be added very easily. Simply change the address in the JMP U1 instruction that was at \$237 in the listing, to a JMP U4 where U4 is the address that the new routines are moved to. Then change this program at \$2AE to insert a JMP U1 in place of the SEC-RTS-NOP, and presto!-you have two new extensions. Both routines U4 and U5 are relocatable, so you don't have to bother running them through Relocate. Just block move them to where you want them. I moved them to the front of the Execute setups so I wouldn't have to learn a new starting address.

For those of you who didn't read the article, I will review some of the comments about how to extend the SYM monitor. First let me say that these routines are relocatable, with the only provision being that they must be in the same relative position to each other, or the branch at \$268 will have to be adjusted. If you decide to only use U4, change the above location to a SEC-RTS (\$3860). The U5 routine will operate by itself without any changes. As I mentioned before, these routines use only those memory locations normally reserved for the monitor, so they shouldn't conflict with your existing programs. Nor will they affect the operation of any of the SYM commands, with the exception that the 'OLD' address that is referred to in the manual will get changed by these commands in additon to the standard commands.

The SYM monitor vectors all "unrecognized" commands via a RAM vector located aat \$A66D. The monitor considers anything it isn't programed for as unrecognized. Normally, \$A66D points to an SEC-RTS sequence. This indicates to the routine ERMSG that the ER xx message should be printed. By the way, the xx is the hex digits for what is in 'A' when ERMSG is called, so this makes a handy error routine for your oun programs. Since SYNERTEK was nice enough to put this vector in Ram, it can be changed. Specifically in our case if it is changed to point out the starting address of U4, the monitor will branch there instead of to the SEC-RTS. If you will note, these routines execute and SEC-TRS whenever they encounter an error, or the command is not the cash value for U4 or U5. For a normal return, they have to

make sure the carry is clear or the error message would get printed.

The monitor routines used in these programs are normal labels as defined in the cross reference listing for the monitor. In order to possibly save some of your sanity when you look at the code. I will mention that the parameter input areas are not numbered the way you would expect. The monitor always accepts input into the P3 area, and each time a new parameter is entered, it shifts the whole area up 16 bits. This means that if only one parameter is entered, it ends up in the P3 area, not in P1 as you would expect. For two parameters, the first parameter is in P2, and the second in P3. For three parameters, the numbers come out right. It gets sort of confusing the first time you try to figure it out, and those are not memory locations you can use any of the commands to look at, since the monitor zeros them out at the start of each command.

These routines were written for version 1.1 of the SYM monitor, which is a little different from version 1.0. In V1.0, both unrecognized commands and syntax errors (i.e. non-hex digits) were vectored through \$A66D, not just the unrecognized commands as in V1.1. This means that if you have V1.0 you have to check to make sure that you are not there because of a syntax error. In order to make these work for version 1.0, insert the following just before U4 and make it the address that goes into \$A66D:

CD 57 A See if co			LSTCOM nated properly
F0 02			Branch if OK
38	SEC	Else s	et the error flag
60	RTS	and ret	urn to the monitor

This will take care of things for both U4 and U5. People who already have my other extensions up won't have to bother, since UO already check for this condition before it does anything else.

The sixteen bit checksum for \$200-\$31F is \$8F1B.

μ

SUAM -	V2.1 (03/79)	65 STMT	02 ASSEMBLER - SUAM	II VERSION
		00002 * SYM-1 USER MC 00003 * U4 - MEMORY 3 00004 * U4 - MEMORY 3 00005 * 0 PARMS 00007 * 2 PARMS 00007 * 2 PARMS 00009 * U5 - DISPLAY 00010 * 0 PARMS 00011 * 1 PARM 00012 * 2 PARMS	DNITOR FUNCTION EXTEN SEARCH FROM 'CURAD+1 SEARCH FROM PARM 1 TI SEARCH FROM PARM 1 T SEARCH FOR PARM 1 AS ALPHA MEMORY DISPLAY 1 LINE FROM DISPLAY 1 LINE FROM DISPLAY FROM PARM 1	* TO 'END OF MEMORY' * O 'END OF MEMORY' * O PARM 2 * ADDRESS FROM PARM 2 TO PARM 3 * 'CURAD' * PARM 1 *
LDC 0000 0000 0200	OBJECT		NITOR EXTENSION ROUT	INES SYM-1 MONITOR EXTENSIONS *******
00 FF		00021 * PAGE ZERD ADD 00022 *********************************	SFE SFC	**************************************
OOFC		00026 PZSCR FQU		
LOC 0200	OBJECT	00028 TEXT	*******************	SEARCH SYS-1 EXTENSION ************************************
		00031 **********************************	- LSI/CCSD DS ON NUMBER OF PARM SEARCH FROM 'CURAD+' SEARCH FROM PARM I SEARCH FROM PARM I SEARCH FOR PARM I SEARCH FOR PARM 1 AS T FOR THE 3 PARM OPT' AD OF HEX 2F WILL BE SEARCH ARGUEMENT IS BE USED. ROUTINE USES THE SYS' SO IT WILL ONLY WOR! CH ARFA IS PROVIDED.	S ENTERED
0200	C9 19 DC 64	00052 U4 CMP	#\$18 TOU5	CHECK FOR 'U4' COMMAND TRY NEXT COMMAND IF NOT THIS ONE
0204 0208 0208 0208 02010 0212 0215 0218 0219 0219 0219	E0 01 90 08 00 17 92 20 A7 92 20 BE 32 49 0F 46 CE 44 46 20 92 F0 20 90 1E 18	00054 * 00055 CPX 00055 BCC 00057 BNE 00058 JSR 00059 NOPRMS LDA 00060 NOPRMS LDA 00061 DEC 00062 DEC 00063 JSR 00065 BCC 00065 BCC 000667 RTS	#1 NDPRMS TRYNXT DECCMP #\$0F P3H P3L INCCMP GETARG GETARG	SEE HOW MANY PARMS BRANCH IF ZERO PARMS OR IF MORE THAN 1 MOVE STARTING ADDRESS TO "CURAD" BACKUP 1 SO INC COMES OUT OK ZERO PARMS - USE HIGHEST RAM ADDR. MAKE LOW ORRDER = \$FF BUMP CURAD BY ONE GET SEARCH IF NOT AT END DONE IF ALREADY TO END OF MEMORY RETURN TO MONITOR
0221 0222 0225 0227	BA 20 9C 82 C9 02 F0 14	00068 TRYNXT TXA 00069 JSR 00070 CMP 00071 BEQ	P2SCR #2 Getarg	PRESERVE # OF PARMS ENTERED P2 AREA HAS 'FROM' FOR 2 & 3 PARMS CHECK WHICH GET ARGUEMENT IF 2 PARMS
0229 0220 0227 0237 0235 0237 0237	AD 4F 46 8D 00 A6 AD 4F A6 9D 01 A6 A9 00 85 FC A2 02	00072 * 00073 LDA 00075 LDA 00076 STA 00077 LDA 00078 STA 00079 LDX	P1L SCPBUF P1H SCPBUF+1 #\$00 PZSCR #2	ELSE MOVE PARM1 TO SEARCH KEY INDICATE BYTES USED MAKE X=2 AS LENGTH
LOC	OBJECT			· · · · · · · · · · · · · · · · · · ·
0238 0230 0241 0244 0246 0246	DO 2D A2 00 86 FC 83 49 3F 20 47 8A 20 09 81 80 00 81	00080 BNE 00081 * 00082 GETARG LDX 00083 STX 00084 JSR 00085 LDA 00086 JSR 00086 RCS 00089 CPX	GOTCR #0 PZSCR CRLF #>> OUTCHR INBYTE NONHEX	AND WE HAVE THE PARM IN NOW NUMBER OF BYTES ENTERED STAT TO ALL BYTES USED START ON A NEW LINE DISPLAY PROMPT GET SEARCH INPUT NEED TO CECH FOR / IF NON-HEX SEE IF GOT ENOUGH ALREADY
024E 0257 0257 0257 0257 0258	BO 20 EO 28 BO 10 97 02 46 26 FC E8 DO EF	00088 BCS 00089 CPX 00090 BCS 00091 STA 00092 ROLLIN ROL 00093 INX 00094 BNE	#8 BADY SCPBUF+X PZSCR GALDOP	CAN'T HANDLE ANY MORE Else Save The Byte Roll Carry Into Bytes Used Bump for Next One Unconditional
02554 02556 0255 0255 0255	70 06 F0 0C C9 2F F0 F3	00045 NDNHEX BVS 00046 BEQ 00097 CMP 00097 REQ	BADY GOTCR Rollin	IF SECOND IS NON-HEX IT IS BAD, BRANCH IF IT WAS CARRIAGE RETURN ELSE CHECK FOR A SLASH IF YES - CARRY IS SET FOR ROLLIN

0262	20 18	72	99	00039	BADY	JSR	BEEP	ERROR CHARACTER BEEP THE BEEPER
0266	90 00	E1 40		00101 00102 00103 00104	*	BCC	GALOOP US	TO FORCE BRANCH JUST PASSING THROUGH ON WAY TO US
026A	CA	20123		00105	SOTCR	DEX		SEE IF GOT ANY SEARCH CHARACTERS
0268 0260 0270	30 8F 45	09 15 50	16	00106		BMI STX LDA	EACHST SCPSTL PZSCR	BRÂNCH IF NOT Else save string length Move bytes used to hold area
0272	80	۱E	16	00109	*	STA	SCPBUD	
0275 0278 0278	AC AD 85	IF FC FC	46	00111 00112 00113	EACHST		SCPSTL SCPBUD PZSCR	START OF TAIL END OF STRING Move bytes used map to work area
0270	64 80	FC 07		00114	EACHCH	BCS	PZSCR	ROLL 1 BIT OF MAP INTO CARRY IF ON IT WAS A SLASH AND IS MATCHED
0291	R1 09	FF 00	46	00116		LDA	(CURAD),Y SCPBUF,Y	COMPARE SEARCH KEY TO THIS BYTE
0286 0288 0289	DC 88 10	19 F2		00118 00119 00120	ISMTCH	BNF	NOMTCH EACHCH	COMPARE SEARCH KEY TO THIS BYTE BRANCH IF NOT A MATCH Got a match - Next Search Char Continue IF More in String
028B	20	16	93	88131	*	JSR	CRLFSZ	ELSE OUTPUT ADDRESS OF START
029E 0291 0297	20 C8 51	42 FE	83	00123	OUTLOP	J SR I NY L DA	SPACE (CURAD),Y	PUT Y BACK TO ZERO LIST THE CHARACTERS FOUND
0294	20	FA	82	00126	001204	J SR	OUTBYT	
0298	202 202	1F F5	A6	00127 00128 00129		CPY BCC	SCPSTL	DONNET FORCET THE LAST BYTE
029D 029F 02A0	F0 18 60	F3	8-1 2-1	00130 00131 00132		BÉQ CLC RTS	OUTLOP	DON'T FORGET THE LAST BYTE Clear Carry And Return to Monitor
CONTRACTOR OF ST		82	82	00133			TNCCMP	NO MATCH -BUMP TO NEXT START ADDRESS
0241 0244	20 90 F0	B2 CF	36	00136	NOMTCH	J SR BCC BEQ	INCC MP EACHST EACHST	CONTINUE SEARCH IF MEMORY LEFT
0248 0249	18			00137		RTS		ELSE RETURN TO MONITOR Play memory sym-1 extension ******
0244				00140 00141 00142	******** * U5 MON	TEXT *******	****************	**************
				00144	*			-1 DISPLAY ALPHA MEMORY *
				00145	*		- LSI/CCSD	IFY', EXCEPT 'OLD' POINTS TO NEXT *
				00148	* 0 PARM		SIMULAR TO SYM VER ADDRESS AFTER THE CO DISPLAY 1 LINE FROM DISPLAY 1 LINE FROM	OMMAND. *
				00150 00151 00152	* 1 PARM * 2 PARM	s	DISPLAY I LINE FROM DISPLAY FROM PARM 1	PARM 1 TO PARM 2
					*******	** ****	******	**********
0244	C9 F0	19		00155	U5	CMP	#\$19 U5STRT	CHECK FOR US HASH CODE BRANCH IF YES
224F	38	50		00157	*	SEC		RAISE THE ERROR FLAG
028F	60 EA			00159 00160 00161	*	NOP		AND RETURN TO MONITOR So above can become a JMP
0281	FO	02		00162	USSTRT	CPX	#2 PRMS2	CHECK FOR 2 PARMS BRANCH IF YES
0285 0287 0289	BO ED FO	F7 21		00164 00165 00166		BCS CPX BEQ	USERR #1 PRMS1	NORE IS TOO MANY PARMS HOW ABOUT 1 PARM BRANCH IF YEP
0288	45	FE	1212	00167	*	1 DA	CURAD	GEE - MUST BE O PARMS
0280	80 85 80	44 FF 48	46	00169		S TA L DA S TA	P3L CURAD+1 P3H	MOVE CURRENT ADDRESS TO P3 AND FALL THROUGH AS TE 1 PARM
0205	20 18 45	A7	82	00172 00173 00174	PRMS1	J SR C LC L DA	P3SCR	AND FALL THROUGH AS IF 1 PARM MOVE STARTING ADDRESS TO P.Z. COMPUTF 1 BYTE PAST ENDING ADDRESS
0209	45 69 80	FE 10		00175		L DA A DC S TA	CURAD #16 P3L	***** BYTES PER LINE HERE ********
02CD 0200 0202	90 EF	4A 0B 4B	46 46	00176 00177 00178		BCC	POOUT	DONE IF NO CARRY ELSE TAKE CARE OF CARRY
0205	20	06 90	82	00179	PRMS2	I NC BNE JSR JSR	DODUT P2 SCR	AND THEN DONE 2 PARMS HAS STARTING IN P2 - END=P3 BUMP FND BY 1 FOR COMPARE
0204	20 20	93 16	82 83	00181 00182 00183	*	J SR	INCP3 CRLFSZ	
02E0 02F2 02E4	42	10 FE		00184	2.12.24 2 .1	LDX	#16 CURAD	START ON A FRESH LINE ***** BYTES PER LINE HERE ******** SAVE STARTING ADDRESS
02E4 02E5 02F7	48 45 48	FF		00186 00187 00188		PHA LDA PHA	CURAD+1	WILL NEED IT LATER
02E8	20	42	83	00189	* ANOTHR	JSR	SPACE	SPACE BETWEEN CHARS
OZEB	A 0 B1	22 FE	225.01	80191		LDX	fO (CURAD) . Y	MAKE SURE REGISTER IS ZERO GET A BYTE OF DATA
02FF 02F2 02F5	20 20 80	FA B? 03	82 82	00193		J SR J SR	OUT BYT I NCCMP	THIS TIME IT IS OUTPUT AS HEX BUMP TO NEXT BYTE
02F8	CA	EE		00195		J SR BCS DEX BNE	LASTPT ANOTHR	DO ASCII PARTIF TO END ELSE COUNT BYTES THIS LINE DO ANOTHER IF ROOM LEFT
N2FA	28	3F	83	00198	* LASTPT	JSR	SPC 2	2 SPACES BEFORE ASCII STARTS RESET CURAD BACK TO START
02FE 0300	85	FF		00200		STA	CURAD+1	RESET CURAD BACK TO START
0301	85	FF 10		00203	1999 - V ²¹	S TA	CURAD #16	***** BYTES PER LINE HERE ********
0305 0307 0309	A2 B1 79	FE 20 04	#1	00205	ASCOUT	LDA	#16 {CURAD} +Y #\$20 MAKSPC	***** BYTES PER LINE HERE ******* GET CHARACTER TO GO AS ASCII MAKE SURE NOT CONTROL MAKE IT SPECIAL IF SO AS SHOULD DO FOR LOWER CASE
030B 0300	90	5B		00208		BCC CMP BCC	#\$58 0KD0	
0305	49	5F		00210	MAKSPC	LDA	#\$5F	INSERT FILLER CHARACTER
0.511	20	47	8 A	00211	UKUU	J SR	OUTCHR	OUTPUT THE ASCII

0314 20 0317 B0 0319 CA	82 82 0 05 0	0212 0213 0214	JSR INCCU BCS USDO	NE BUMP TO NEXT BYTE NE DONE IF NOW TO THE END
031A DO 1	E9 0 BF 0	0215	BNE ASCO	NE DONE LE NOW TO THE END Else Next Byte UT Same line if not to end T Else Start a New Line
031F 18 031F 60 031F	Ō	0218 U5DONE 0219	CLC RTS EQU *-1	CLEAR ERROR FLAG AND RETURN TO MONITOR END OF PROGRAM ADDRESS MARKER
LOC0	BJFCT	STMT	SYM SYST	EM ADDRESS AND ROUTINES
	00	0222 ********** 0223 * SYM SYST 0224 ********	ME ROUTINE	**************************************
8109 8293 82947 8285 8785 8785 8755 8755 8755 8755 875		0227 INCP3 0229 P2SCR 0229 P3SCR 0230 INCCMP 0231 DECCMP 0233 CRLESZ 0233 CRLESZ 0234 SPC2 0234 SPC2 0235 SPACE 0236 CRLE 0237 BEEP 0238 OUTCHR	QU \$81D9 QU \$8293 QU \$8293 QU \$8293 QU \$8282 QU \$8282 QU \$8282 QU \$8282 QU \$8316 QU \$8342 QU \$8342 QU \$8342 QU \$8342 QU \$8342 QU \$8342	INCREMENT P3 BY 1 PUT PARM3 INTO "CURAD" PUT PARM3 INTO "CURAD" BUMP 'CURAD' & COMPARE TO PARM3 SUBTRACT 1 FROM 'CURAD' PRINT A (2 HEX DIGITS) OUTPUT CR/LF AND 'CURAD' OUTPUT 2 SPACES OUTPUT 1 SPACE OUTPUT CR/LF TOOT THE ONBOARD BEEPER OUTPUT AS'LI FROM 'A'
4600 461F 46448 46448 46440 46440 46440 464F 464F		0240 SCPBUF 0241 SCPBUD 0242 SCPSTL 0243 P3L 0244 P3H 02445 P2L 0246 P2H 0246 P2H 0247 P1L	QU \$A600 QU \$A61E QU \$A61F QU \$A64F QU \$A64B QU \$A64C QU \$A64C QU \$A64F QU \$A64F	SCOPE OUTPUT BUFFER AREA Bytes Used Bit Map Search String Length Input Parameter Values
END DE PASS	2-EPROPS= 00	000 *********	********	***************************************

Microcomputing is Nick Vrtis' hobby. He is employed by Lear Siegler, Inc. as a Senior System Software Specialist. For this, he works mainly on operating systems on the company's IBM computers, but he also delves into CICS and communication somewhat.

His system at home is a SYM-1. It has 5K RAM, soon to

be expanded to 8K. He also has Synertek BASIC and has played with Tom Pitman's Tiny Basic, which he has disassembled and modified. His current terminal is an old Datapoint 3300, and he also has a Radio Shack Quick Printer II hooked up through the TTY pot on the SYM. The assemblies that he gets are done with a cross assembler that he wrote to run on the IBM gear.

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Sorting Revealed

A truly fresh approach to understanding the basics of sorting. In addition to a particularly lucid discussion of various sorting methods, programs are presented which demonstrate the sorting algorithms in action.

Richard C. Vile, Jr.

It has often been said that a picture is worth a thousand words. Sadly, this maxim is frequently ignored by professional educators, especially when dealing with such bone-dry subjects as mathematics and computer science. This article will present a detailed example of the use of a simple, yet effective, visual technique for giving insight into the basis for certain algorithms. Our approach will be to show the algorithm in action. Our medium will be the Apple II personal computer, but any computer which provides a memorymapped display will do. The vehicle for the demonstration will be one of the staples of the computer science curriculum - the joy of pedants and the bane of poor benighted students viz. sorting algorithms.

Sorting Theory

Unfortunately, we must stoop to pedantry to begin with. The reader who is already well-versed in sorting lore may skip directly to Sorting Implemented.

Sorting is such a varied and vast topic that large portions of entire books have been devoted to it. Perhaps the best known compendium of sorting facts and theory is to be found in Knuth's robust volume Sorting and Searching (The Art of Computer Programming Vol. 111, Addison Wesley, 1973). Our demonstration will be limited to just a few of the better known sorting algorithms, although the techniques could be applied to others as well. We shall provide programs that allow the visualization of five different sorting algorithms: bubble sort, Shell sort, insertion sort, selection sort, and quicksort. Of these, we shall discuss the bubble sort and quicksort in some detail prior to the presentation of the programs. Details of the others may be found in almost any good introductory computer science text, as well as in most texts on data structures.

Apart from the specific details of the algorithms used, the theory connected with sorting deals with efficiency. When people who are "in the know" discuss sorting, they will frequently bandy about certain terminology which they don't bother to explain. In hopes of increasing the number of cognoscenti involved in such discussions, we shall now attempt to lay out some of the more common terms for you.

To simplify matters somewhat, let us assume that all of our sorting will take place entirely in memory. Sorting methods that involve storing intermediate stages on disk files or magnetic tape, so-called external sorts, will be beyond our scope, although presumably not beyond our ken. The objects to be sorted will be assumed to be numbers, either integer or floating point, stored in memory in an array of one dimension and of a given size. The size of the array being sorted will be a hit personality throughout the discussion, so we give it a name. It will be denoted by N.

Number of elements to sort = N

In order to fully comprehend one

of the definitions to be given later, it is necessary to indulge in a bit of mathematics. We shall need to understand two functions. In particular:

 $Log_2 x = base 2 logarithm of x$ $[x_1] = floor of x$

Actually, we are interested in the combination of these functions as applied to the friendly value N:

llog₂ NJ

i.e. the floor of the base 2 logarithm of N. Before you run screaming to the nearest math anxiety clinic, at least read the next few sentences of explanation.

Suppose you have a pile of N coconuts (why coconuts, you ask? Why not, we reply!). Think about the following process:

1. Subdivide the pile into two piles which are as nearly equal in size as possible.

2. Take the smaller of the two piles from step 1. If it consists of one coconut, then stop. Otherwise, repeat from step 1.

Now how many times did you do step 1? The answer is the value of $[log_2 N]!$ So, without worring about picky details, the floor of the base 2 logarithm of N is the number of times you can divide N by 2 and still retain a non-zero quotient. Figure 1. pictures a simple case.

An alternate way of thinking about

the situation involves collecting coconuts. The procedure is as follows:

1. Begin with a single coconut.

2. If doubling the number, k, of coconuts which you already have would cause your total to exceed N coconuts (2k is greater than or equal to N), then stop.

3. Collect k more coconuts, giving you 2k, and repeat step 2 now thinking of the new total as the value of k.

Now how many times did you execute step 3? The answer will again be [log₂ N]. Before you go on, try to convince yourself (without flying to Tahiti to collect real coconuts),the two procedures yield the same result.

We shall return to this value, the "coconut number", later.

In order to talk about the efficiency of any algorithm, we need some quantities that we can measure. For sorting algorithms, we concentrate on two: the number of comparisons and the number of interchanges.

A comparison occurs whenever a member of the collection of numbers is compared to something else. The something else could be a value fished out of a hat, or it could be another member of the collection. Thus, a statement such as IF A(I) > A(I + 1)THEN...counts as a comparison, as well as IF A(I) > MAX THEN...

An interchange occurs whenever a member of the collection of numbers is moved from one place to another in the computer's memory, and possibly some other number takes its place. The classic interchange may be described by the seguence of three statements:

$$\begin{array}{l} \mathsf{TEMP} = \mathsf{A}(\mathsf{I}) \\ \mathsf{A}(\mathsf{I}) = \mathsf{A}(\mathsf{J}) \\ \mathsf{A}(\mathsf{J}) = \mathsf{TEMP} \end{array}$$

(assuming, of course, that $I \neq J$). Not all sorting algorithms use this classic form, but there is usually an easily identified interchange step whose repetition we can count.

Trying to count the number of comparisons and/or interchanges which take place during the course of execution of a sorting algorithm will give an approach to measuring the efficiency of that algorithm. In addition to comparisons and interchanges, there will also be overhead involved in a sorting algorithm: i.e. the computing time used in loop control, recursion, etc. This is more difficult to measure theoretically and is therefore usually deduced from empirical observations.

N

5

2

1

Starting Pile

Therefore,

Being armed with a few terminological weapons, we may now attack some of the more familiar sorting buzz phrases. Assume we are speaking of the number of comparisons made during the execution of some sorting algorithm. Then we may speak of an N² sorting algorithm (pronounced N-squared). This means that "on the order of" N times N comparisons will be made in the course of sorting an array of size N. Well, that was relatively painless - at least as a definition! The interesting (painful) part comes when we try to prove that a given algorithm is an N^2 algorithm. We shall get to that in the next section.

Another phrase which is frequently encountered when casually "talking sorts" is: that's an N log N sort (pronounced N log N!). What that actually means is that the expected number of comparisons in carrying out the sorting algorithm for an array of size N is:

N * ([log₂ N])

That is, N multiplied by the coconut number. Again, this is easy enough to say, but perhaps a_bit harder to appreciate than the N^2 description. After all, why should we be concerned with these numbers, and what is the significance of the difference between them?

Pile 1

STOP

Figure 1

Step 1. was performed 2 times.

 $\lfloor \log_2 5 \rfloor = 2$

Pile 2

Consider briefly, Table 1. It shows values for N, N² , [log₂ N], and N* [log₂ N].Assuming that overhead is relatively constant, or at least negligible from one algorithm to the next, we see that there is an ever increasing difference between N² and NlogN (from now on, we assume that logN means [log2 N]). To make the comparison more concrete. let us assume that a comparison costs .001[¢], and that we need to sort an array containing 1,048,576 numbers. Using an N^2 \$10,995,116.27, sort will cost whereas using an NlogN sort will only put us out \$209.72 Of course, a single comparison of two numbers on today's monster computers-or "big iron" as they are sometimes referred to in the trade- costs considerably less than. .001*. But even at .0000001^e per comparison - a rate of 10,000,000 comparisons per penny- the cost differential will be 2* for the NlogN sort-\$1,099.51 for the sort! With that kind of com-N2 parison, you can see why no commercially viable sorting package is going to use the N^2 sorting approach.

Some Sorting Algorithms

We now present two of the more well known sorting algorithms in some detail. We will attempt informally to prove that the first is an N^2



algorithm. The second algorithm discussed is an example of an NlogN algorithm, but we shall spare the reader any attempts at proof.

Bubble Sort

This algorithm is probably the most widely known and loathed by students of introductory computer science. Many an instructor has droned on about its properties to unwilling students of FORTRAN! For many of these students, it is their only taste of the vast menu of sorting techiniques.

We assume that N elements, which we shall denote by A(1), A(2),..., A(N), are to be arranged in ascending order; in short, sorted. The bubble sort operates by making repeated "sweeps" through the array, causing various elements to "bubble - up" in the process. We shall see that for each sweep, at least one element is guaranteed to be positioned in its correct final slot in the array.

The heart of each sweep is the idea of comparing two adjacent entries in the array: A(I

If A (I) has a greater value than A(I + 1), then the two elements are known to be out of correct order and need to be swapped. This is accomplished by the use of the classic interchange, which we illustrate here in BASIC and Pascal:

	N log N	ł	log N	1	N ²	1	N	1
1		1		1		1		1
1	384	1	6	1	4096	1	64	1
	896	1	7	1	16,384	1	128	1
	2,048	1	8	1	65,536	1	256	1
	4,608	1	9	1	262,144	1	512	1
	10,240	1	10	1	1,048,576	1	1,024	
	22,528	1	11	1	4,194,304	1	2,048	1
	49,152	1	12	1	16,777,216	1	4,096	
	106,496	1	13	1	67,108,864	1	8,192	1
	229,376	1	14	1	268,435,456	1	16,384	
	491,520	1	15	1	1,073,741,824	1	32,768	1
	1,048,576	1	16	1	4,294,967,296	1	65,536	1
	2,228,224	1	17	1	17,179,869,184	1	131,072	1
	4,718,592	1	18	1	68,719,476,736	1	262,144	
	9,961,472	1	19	1	274,877,906,944	1	524,288	1
	20,971,520	1	20	1	1,099,511,626,776	1	1,048,576	

Table 1

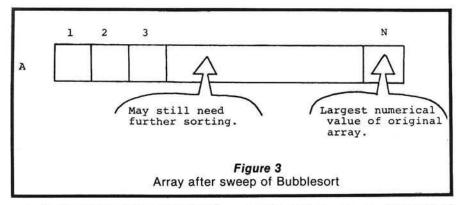
Now consider the iterations of this fundamental step which are necessary in order to bring the entire array into sorted order. First, suppose we are just beginning. Then we can make no assumptions about the sizes of the array elements, relative to their positions in the array. Thus, suppose we iterate the fundamental comparemaybe-swap step over values of I ranging from 1 to N-1 (why not 1 to N?). That is, we will successively compare A(1) and A(2),A(2) and A(3), and so on, until we reach A (N-1) and A(N). Positions of various elements will change through swapping. In particular, the largest numerical value in the orignal array is guaranteed to wind up in A(N). Positions of various elements will change through swapping. In particular, the largest numerical value in the original array is guaranteed to

wind up in A(N) after the sweep is completed. To convince yourself. that this is true, ask;"If the largest value is originally in A(J), then what other array entries will it be swapped with?"

The last paragraph has indicated that we can reach a picture such as that shown in Figure 3, after one sweep of the array. What has been accomplished? We have partially sorted the original array. How much of the resulting array is now in correct order? One element - the last. Note that this is the same as the number of sweeps we have made. Now suppose we make a second sweep through the array, comparing A(1) and A(2), A(2) and A(3), etc. until we reach A(N-2) and A(N-1). It is not necessary to compare A(N-1) and A(N), since we know that A(N) is already in its correct final position. Moreover, A(N-1) is now also guaranteed to be the second largest element in the array, and therefore in its correct final position. Thus the original array has been divided into two pieces: the elements A(1), A(2), ... A(N-2), still possibly unsorted, and the elements A(N-1) and A(N), both where they 'should be'. We have made two passes and put two elements in their correct positions.

Continuing this process by making passes through less and less of the array will cause more and more of the 'tail end' of the array to be in correct final order and leave less and less of the beginning of the array to still be sorted. Altogether it will take N-1 passes through the array to guarantee that it is totally sorted. The reason that it does not require N passes is that the last pass causes two elements to wind

	BASIC
100 110 120 130 140	IF $A(I) \leq A(I+1)$ THEN 140 TEMP = $A(I)$ A(I) = A(I+1) A(I+1) = TEMP
	if A[I] > A[I+1] then begin
	Temp := A[I]; A[I] := A[I+1]; A[I+1] := Temp;
	end;
	Figure 2 The "Classic Interchange"



up in their correct places, instead of just one. Figure 4 gives both a BASIC and a Pascal version of the complete bubble sort algorithm.

Now let us see if we can count the number of comparisons that will be made. Each sweep through the array corresponds to one pass through the inner loop of the algorithm. The number of comparisons made will be the same as the value of the upper limit of this loop, which according to Figure 4. is N-I. The value of I is varried by the outer loop and runs from 1 to N-1. Thus, there will be: N-1 comparisons the first time through the loop.

N-2 comparisons the second time through the loop.

N-3 comparisons the third time through the loop.

N-(N-2) = 2 comparisons the (N-2)nd time through the loop N-(N-1) = 1 comparisons the (N-1)st time through the loop. The total number is therefore: (N-1) + (N-2) + ... + 3 + 2 + 1 This number is known in mathematics as a 'triangular' number, and by a formula from algebra may be expressed solely in terms of N as 1/2 (N² - N). Consequently, there are about N² comparisons made.

The inefficiency of the bubble sort is compensated for by its simplicity, especially from a pedagogical point of view. It is totally trivial to program, as we have seen. Consequently, it is quite acceptable for sorting tasks that only involve 'small' values of N.

Quicksort

Quicksort, invented by C.A.R. Hoare, is probably the most 'elegant' of the sorting techniques yet devised. It is an NlogN sort, which is based on a very simple idea and in its most compact form may be programmed in very few lines of code. In fact, probably the greatest difficulty in grasping how it works involves understanding the administrative details of how to apply the basic step which motivates its

	BASIC	
10 20 30 40 50 60 70 80	FOR I = 1 TO N-1 FOR J = 1 TO N-I IF A(J) <= A(J+1) THEN 70 TEMP = A(J) A(J) = A(J+1) A(J+1) = TEMP NEXT J NEXT I	
f	Pascal For I := 1 to N-1 do for J := 1 to N-I do if $A[J] > A[J+1]$ then begin Temp := $A[J]$; A[J] := A[J+1]; A[J+1] := A[J]; end; Figure 4 Bubble sort algorithm in both BASIC and Pascal	

operation. One has the tendency to say, 'You mean, that's all there is to it?', or 'But what do you mean by simply apply the same procedure to both halves?'. Nonetheless, once appreciated, it is an algorithm you will never forget. That should be reward enough for the effort expended in understanding it in the first place.

The basic idea underlying Quicksort is to perform interchanges of non-adjacent array elements in hopes of bringing order to the array more quickly (bubble sort has already demonstrated the inefficiency of interchanging adjacent entries). The idea is applied using the concept of a *partition* of the array elements.

To partition the elements A(P), A(P+1), ..., A(Q) of the array A, where $P \ge 1, P \le Q, Q \le N$, requires that some value X which actually occurs as one of the entries A(P), A(P + 1),...,A(Q) be placed into its correct final position, say K, and that the remaining elements are arranged so that $A(I) \le A(K)$ for O < K and $A(J) \ge A(K)$ for J > K. The results are pictured in Figure 5.

For convenience in implementation (although this may not be the optimal choice in theory), we shall always choose A(P) as the value X, which is to be inserted into its correct final resting place. To accomplish our end result, we adopt the following 'double-barreled' scan:

Start with I=P+1 and J=Q. Scan forward from I (i.e. in increasing I-value order) until we find A(I) for which $A(I) \ge X$. Scan backward from J (i.e. in decreasing J-value order) until we find A(J) for which $A(J) \leq X$. Then interchange A(I) and A(J), since they are both in the 'wrong half' of the partition according to the above definition. Continue this procedure until $J \leq I$. As a final act, interchange A(P) and A(I), where I now has its 'final' value. This puts X = A(P) into its correct final position in the array. You should convince yourself that it also achieves the picture shown in Figure 5. Actually, there is one case which fails. See if you can discern what it is - we'll come back to it later on.

An example may make things a bit clearer. Figure 6 shows an un-

sorted array of 16 elements, which is to be partitioned for P = 1, Q = 16. Shown are the first values of I and J for which an interchange of the partitioning process will take place. See if you can draw the final picture: showing the array with the partition complete and the value of K. The answer is shown in Figure 7.

When one gets down to programming the partitioning process, several details that may not have been previously obvious suddenly force themselves into the spotlight. In order to highlight these, we present in Figure 8 a Pascal procedure for the partition step. The first item which may catch your eye is that array A is indicated in the parameter list to be of size N + 1, instead of N. The reason may be seen by studying the second repeat statement of Figure 8:

> l := l + 1 until A(l)≥Value;

As with all loops, the programmer should be sure that there is a way out! In this case, if the elements A(1), A(2), ..., A(N) of the array are assumed to be randomly distributed

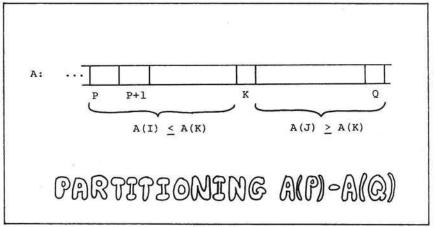
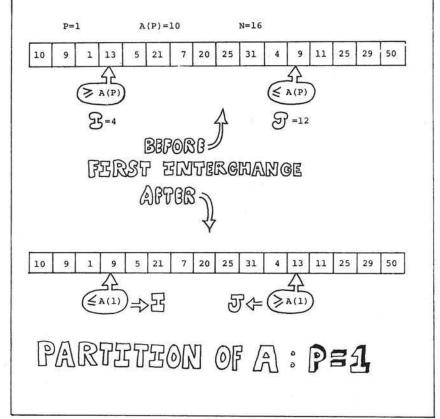


Figure 5

among all possible values, then there is no guarantee that any of them satisfies the condition $A(I) \ge$ Value. Thus, we have extended the array and stored a value in A(N + 1)which is guaranteed to be greater than or equal to any other value that could occur in the original array. In Pascal, the predefined identifier Maxint serves the purpose, and we may assume that the assignment A[N + 1] := Maxint; has occurred in the calling routine. Now, even if all elements of A are strictly less than A(1), the repeat loop will terminate



repeat

Figure 6

when it bumps into the Maxint value stored in A[N + 1]. Such a value, which is not part of the data being manipulated, but instead serves to protect against some dire circumstances, is known as a *sentinel*.

This approach raises two further questions: first, do we face a similar problem with J; and second, do we face the possibility of erroneously swapping A(N + 1) with some element of A. The first question is easily answered by realizing that Value := A [Lower]. Thus, if J is decreased so far that J :=Lower, then $A[J] \le$ Value is automatically true. Thus, the first repeat loop is guaranteed to stop because of this choice. To answer the second question, let's look closely at what happens when N = Upper and A(I) < Value for all I, $I = 2,3, \dots, N$. The repeat statement: repeat

$$J := J - 1$$

until A[J]≤Value

immediately succeeds. J starts at N+1, J-1 = N and A(N) < Value byour assumption. Thus, J stops at the value N after the first time through the loop. On the other hand, the repeat statement for I will continue to fail, again by our assumption, until I = N + 1. Now I + N + 1 and J =N. This means that the test I < J will fail. Therefore, the interchange shown inside the while loop will be skipped. Aha!, you say - caught you -nothing happens and Quicksort is a sham !! Fortunately, that is not true. The last two statements in the procedure:

$$A[Lower] := A[J];$$

A[J] := Value; will be carried out, causing A[Lower] and A[N] to be swapped.

To assimilate the code of the pro-

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cedure, simulate its action on the array of Figure 6. As a final note, the procedure protects itself from funny initial values for Lower and Upper, by first checking to make sure that Lower < Upper. This will turn out to be necessary in one version (the recursive one) of the complete Quicksort algorithm, but must be moved back to the caller for the other version (the 'straight' or iterative one).

Now that we have studied the innards of the Quicksort algorithm, it is time to investigate how the partition step fits into the larger scheme of things. Once the original array A has been partitioned, we are left with one element in its correct final resting place and two subarrays that remain to be sorted. The beauty of Quicksort is that that is all that remains to be done. Once the two subarrays are both sorted, the entire array is automatically sorted. This is true because of the condition guaranteed by the partition step that all elements in the first half of the array arre less than or equal to all the elements in the second half of the array. Not convinced? Think about it! Or, consider the following analogy: a school teacher wishes to arrange test papers in alphabetical order. The papers are divided into two piles (partitioning step) with all papers in the left-hand pile belonging to students whose names begin with letters A to M, and all papers in the right-hand pile belonging to students with names beginning with letters N to Z. Now, if the left-hand pile is arranged (by whatever method) into alphabetical order and likewise the right-hand pile, then all that remains to put the whole collection into alphabetical order is to place the left-hand pile on top of the right-hand pile.

To continue the Quicksort algorithm, one applies the basic step to both subarrays obtained from the first partitioning step. That will produce in each case two new subarrays (or better, sub-subarrays), to which the partitioning process is applied in turn. Since we started with a finite number of elements in array A, sooner or later this will produce sub-sub...subarrays with 0 elements. Such subarrays are sorted by default. Thus, they need not be partitioned any further. Morever, when both subarrays of a

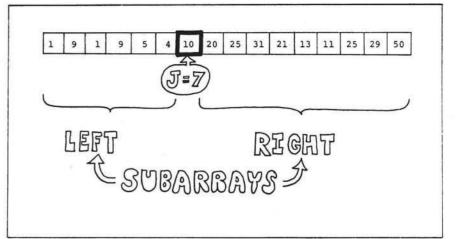


Figure 7 Partition step complete A(7) in correct position.

procedure

Partition(

var	A: array[1N+1]	of	integer;
	Lower, Upper:		integer;
var	J:		integer);

```
var
```

Value, Temp: integer;

```
begin
```

if Lower < Upper then begin

{Lower bound in A for partition step} I := Lower; J := Upper; {Upper bound in A for partition step} {Comparison value for partitioning} Value := A(Lower); while I < J do begin {Partitioning loop} {Find element in right half to switch} repeat J := J-1 until A(J) <= Value; repeat {Find element in left half to switch} I := I+1 until A(I) >= Value; if I <= J then begin {Perform the switch} Temp := A(J); A(J) := A(I);A(I) := Temp end {of if I <= J} end {of while I < J} A(Lower) := A(J);{Insert A(Lower) into its A(J) := Value; {correct final position in A} end {of if Lower < Upper} end {of Procedure Partition};

```
Figure 8
```

procedure

Sort(

```
var A: array[1..N+1] of integer;
Lower,Upper: integer );
```

var

```
J: integer;
```

begin

```
Partition(A,Lower,Upper,J);
```

Sort(A,Lower,J-1);
Sort(A,J+1,Upper);

end {of Procedure Sort};

Figure 9

given subarray reach this state, they form together with their partition element a sorted subarray, which may then be ignored while the remaining unsorted subarrays are processed. Eventually, the original two subarrays will have been sorted and voila!, A will have been sorted. Figure 9 shows the implementation of this scheme as a Pascal procedure must be invoked from outside itself with initial values for Lower and Upper, which are presumably 1 and N, in most cases. Once it gets going, it calls itself on behalf of the subarrays, and the sub-subarrays, etc. until it completely sorts A. Figure 10 shows the progress of the sort as applied to a small array, with N=8. Study it carefully. Figure 11 presents the calling structure to Sort for the array in figure 10. The root of the tree represents the original call to Sort from outside. The interior nodes of the tree represent calls to Sort from within itself. Each node is labeled with the values of Lower and Upper which were passed on the corresponding call. The leaves of the tree represent calls to Sort in which the passed values of Lower and Upper correspond to subarrays with 0 elements. Such subarrays are already sorted and "nothing" will happen on these calls.

EXERCISE: Determine whether or not the Partition procedure may be modified to return whenever the passed array has either 0 or 1 elements. If so, make the necessary changes to the code.

The recursive implementation of Quicksort is without a doubt one of the most "beautiful" algorithms yet devised in any branch of computer science. Unfortunately, the performance of Quicksort in such an implementation, even though superior to most N^2 algorithms, is still not quite as good as it could be. We shall not attempt to explain the technical reasons for this, other than to say that recursion involves more than a modicum of overhead. However, we shall attempt to formulate the algorithm in a nonrecursive or iterative fashion for comparison.

{Partition A between

{A(Lower) and A(Upper)

{Sort the "left" subarray

{Sort the "right" subarray }

Now look back at the recursive implementation of Quicksort shown in Figure 9. Since Sort calls itself, this means that the variable J, which is used locally within Sort, must be given a different "incarnation" on each call. Otherwise, the recursive calls would cause its former value to be lost, which in turn would mean that the procedure would get mixed up about where the subarrays began and ended. In languages, such as Pascal, which support recursive procedures, the uniqueness of J on each call is guaranteed. In a language like BASIC, there aren't even procedures, let alone recursive ones! Thus, in such a language, we must "fake it" in some way or another.

What is it about the variable J that's so important? It remembers the dividing point between the two subarrays determined by any partition step. This enables the two halves to be sorted separately by successive calls to Sort. Another way to approach matters would be to save information about subarrays that still need sorting and retrieve it as necessary. An appropriate data structure for preserving such information is a stack. The Lower and Upper values for one "half" of a partition may be saved by pushing them onto the stack, while the other "half" is being sorted. When the other half has been completely sorted, the Lower and Upper values for the saved half may be popped off the stack and the sorting of that half commenced. Of course while sorting a given half, new pairs of bounds for smaller subarrays will be determined and bounds for one subarray of each such pair will in turn be pushed onto the stack. If a point is reached at which we try to pop the bounds of a subarray from the stack, and find that the stack is empty, then we will know that the original array is completely sorted. As a performance enhancement, we shall always sort the smaller of any given pair of subarrays first. This is in distinction to the algorithm of Figure 9, which always sorts the left subarray first. Sorting the smaller subarray first will cause a minimum number of entries to be saved on the stack

The actual code of an iterative implementation of the Quicksort algorithm is presented in Listing 5, using APPLE Integer BASIC.

Sorting Implemented

The APPLE II Integer BASIC programs of Listings 1-5 provide implementations of visual sorts for the following five methods: Bubble sort, straight insertion sort, selection sort, Shell sort, and Quicksort. The visual display arranges the array to be sorted as a table of up to 100 positive two digit integers - the user may request fewer if so desired to speed up the completion of the algorithm. The basic table using the random number generator for IN-TEGER BASIC. For skeptical viewers, the values 0 to N may be generated in a permuted order and filled into the first N+1 slots of the tableau. The modification needed in order to accomplish this is shown in Figure 12. Figure 13 shows a typical tableau, this one prior to the beginning of Shellsort. Notice that extra information is displayed in the small area surrounding the display. By studing the listing and carefully

				<u>A</u>	Q.			Call
10	9	1	13	5	21	7	20	<pre>Partition(A,1,8);</pre>
10	9	1	7	5	21	13	20	
5	9	1	7	10	21	13	20	
5	9	1	7	10	21	13	20	<pre>Partition(A,1,4);</pre>
5	1	9	7	10	21	13	20	
1	5	9	7	10	21	13	20	
1	5	9	7	10	21	13	20	<pre>Partition(A,1,1);</pre>
1	5	9	7	10	21	13	20	
1	5	9	7	10	21	13	20	<pre>Partition(A,3,4);</pre>
1	5	7	9	10	21	13	20	
1	5	7	9	10	21	13	20	<pre>Partition(A,3,3);</pre>
1	5	7	9	10	21	13	20	<pre>Partition(A,5,4);</pre>
1	5	7	9	10	21	13	20	Partition(A,6,8);
1	5	7	9	10	20	13	21	
1	5	7	9	10	20	13	21	<pre>Partition(A,6,7);</pre>
1	5	7	9	10	13	20	21	
1	5	7	9	10	13	20	21	<pre>Partition(A,6,6);</pre>
1	5	7	9	10	13	20	21	<pre>Partition(A,8,7);</pre>
1	5	7	9	10	13	20	21	Partition(A,9,8);
							Figure	e 10

Figure 10 Complete trace of Quicksort for N = 8 boxed entries are known to be in the correct slot.

monitoring this information, extra insight into the nature of the algorithms may be gained.

All values generated are positive and less than 100. This is done because of horizontal space constraints in the display and does not reflect any inherent limitations in the algorithms themselves.

The programs each carry out one of the sorting algorithms.As the array is sorted, the values displayed on the screen are modified to reflect the changes taking place internally. Various devices are used to highlight this: some visual and some aural. The audio effects are programmed using the Programmer's Aid ROM. Thus, you may have to remove or modify certain statements in order to run the programs, if you don't own PA.

Each time a number is moved from one place to another in the array, that value is highlighted in the display. This is accomplished by momentarily displaying the value in reverse video, then switching back to normal mode. If your APPLE has been modified for lower case, this probably won't work. You can get a good idea of how each algorithm does its job just by watching the pattern of flashes on the screen.* In addition to this, as mentioned above, each sort prints on the border of the display some additional imformation about what is happening. Each program begins with a prologue giving the name of the sort and prompting the user for the number of elements to be sorted. The value of PDL(1) is used by the programs to control the speed at which the display is generated. Thus to slow down the

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progress of the program, simply turn up the PDL(1) control.

While each algorithm is in progress, two tones will be sounded periodically. One tone is generated each time an array element is copied from one place to another, that is, for each interchange. A different tone is sounded whenever an array element is compared to another or to a fixed value, that is, for each comparison. Listening to the pattern of sounds thus produced gives a very definite auditory tattoo to each algorithm. The calls to Programmer's Aid which produce these tones are localized in subroutines to facilitate their removal or replacement should you not have the PA ROM. For example, in the bubble sort demo, you may defeat the sounds by inserting the two statements:

901 RETURN 951 RETURN

Even if you do have PA, you may want to use these statements in order to (a) speed up the program a little or (b) hear only comparisons or only interchanges.

*NOTE: If you stop the program with a Control-c at just the right (or wrong — depending on your point of view) moment, you may find that everything is being displayed in reverse video. To return to normal display mode, simply type:

POKE 50,255

and all should be well.

I hope that these demonstrations will enhance your understanding and enjoyment of sorting algorithms you may wish to implement similar demos for other sorting algorithms, or if you are very ambitious, how about a way of having the various algorithms swap in and out while the same array is sorted in stages? Happy viewing!

A complete package of twenty demonstration programs, including the ones listed here and variations upon them may be obtained for \$14.95 on a single diskette by writing to the author.

> 3467 Yellowstone Drive Ann Arbor, MI 48105

μ

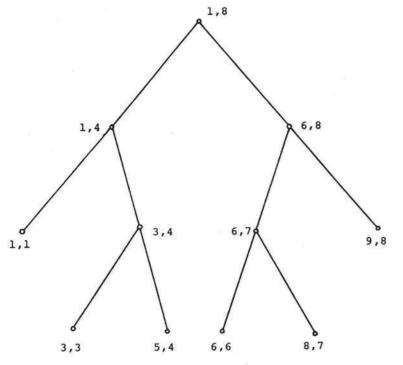


Figure 11 Call tree for Figure 10. Each node is labelled with the values of Lower, Upper for the corresponding call. The levels of the tree correspond to the depth of the recursion.

	ø	l	2	3	4	5	6	7	8	9
ø:	12	72	14	68	54	23	32	3	56	24
1!	44	26	41	ø	87	67	8	81	39	39
2!	3	26	60	64	35	2ø	39	78	65	26
3!	16	17	99	69	81	88	65	32	5	68
4!	37	44	32	89	65	37	2ø	38	84	77
5!										
6!										
7!										
8!										
9!										
		1		LL S AN S			1	J: A(J	= 1.)=4	

Figure 13 Just before the start of the shell sort. Fifty elements are being sorted.

80	For I =	= 0 T	ON	: A(I)	=:	NE:	XT I
90	For I =	= 0 T	O N	50			
100	L =	RNI	A) C	+ 1	L)	: IF	A(L)
				>=	0 T	HEN	1 100
105	A(L)	=	1:	X =	L:	GO	SUB
					1	DISF	LAY
110	NEXT	1					

Figure 12

Modification to Display generation: will seed the initial array with exactly the numbers 0 to N in some permuted order.

.....

Richard Vile was educated in mathematics, earning a B.S. degree from Michigan State University and a Ph.D. from Cornell University.

Richard taught mathematics at Eastern Michigan University from 1970 - 1977. While at Eastern, he became interested in computers and began studying and teaching computer science.

In early 1978, he took a leave of absence from, E.M.U. in order to work for SYCOR, Inc. and Ann Arbor manufacturer of distributed data processing computer systems. He enjoyed the work so much that he did not return to the academic world. He is currently employed by the same company, known as Northern Telecom Systems Corporation, where he is engaged in the development of languages and language related software: compilers, assemblers, linkage editors, etc.

Richard owns an APPLE II computer, which he puts to good use preparing articles for MICRO and other personal computing journals.

> Richard C. Vile, Jr 3467 Yellowstone Dr. Ann Arbor, Michigan 48105



Continued on page 24...

Software for the Apple II

SUPER CHECKBOOK—a program designed to be an electronic supplement to your checkbook register. It's disk oriented and allows information to be displayed on the video screen or printer. It's super fast in sorting and retrieving information and totals. As an added bonus the program can optionally provide bar graphs to screen and/or printer. The program performs all standard check register operations, i.e. reconciliation. Minimum requirements are Disk II and only 32K RAM memory if Applesoft is in ROM; \$19.95.

ADDRESS FILE GENERATOR—a program that gives you complete control over a name and address file at a very low price. The power and flexibility of this software system is unmatched even in programs costing much more. You are allowed up to eleven fields in each record and you can search and sort on any of these fields. In fact you can sort up to three fields at once. The program contains a powerful print format routine which allows you to print out any field in any format you wish. Minimum requirements are Disk II and only 32K RAM memory if Applesoft is in ROM; \$19.95

WORLD OF ODYSSEY — an adventure game to which all others must be compared. It's by far the most complex game for the Apple II. It will probably drive you crazy and take several months of play to completely traverse this world. You have 353 rooms on 6 different levels to explore with myriads of treasures and dangers. The program allows you to stop play and to optionally save where you are so that you can resume play at a later time without having to repeat previous explorations. It's been called the best adventure game yet! Minimum requirements are Disk II with 48K RAM and Applesoft II in ROM; \$19.95.

REAL ESTATE ANALYSIS PROGRAM—The Real Estate Analysis Program provides the user with three features. a) A powerful real estate investment analysis for buy/sell decisions and time to hold decisions for optimal rental/commercial investments. b) Generation of complete amorization schedules. c) Generation of depreciation schedules. All three features are designed for video screen or printer output. In addition, the program will plot; cash flow before taxes vs. years, cash flow after taxes vs. years, adjusted basis vs. years, capital gains vs. years, pre-tax proceeds vs. years, post-tax proceeds vs. years, and return on investment (%) vs. years. Minimum requirement Applesoft II, 16K; \$14.95.

DYNAMAZE — a dazzling new real-time game. You move in a rectangular game grid, drawing or erasing walls to reflect balls into your goal (or to deflect them from your opponent's goal). Every ball in your goal is worth 100 points, but you lose a point for each unit of elapsed time and another point for each time unit you are moving. Control the speed with a game paddle: play as fast as ice hockey or as slowly and carefully as chess. Back up and replay any time you want to; it's a reversible game. Integer Basic (plus machine language); 32K; \$9.95

ULTRA BLOCKADE—the standard against which other versions have to be compared. Enjoy Blockade's superb combination of fast action (don't be the one who crashes) and strategy (the key is accessible open space—maximize yours while minimizing your opponent's). Play against another person or the computer. New high resolution graphics lets you see how you filled in an area—or use reversibility to review a game in slow motion (or at top speed, if that's your style). This is a game that you won't soon get bored with! Interger Basic (plus machine language); 32K; \$9.95.

What is a REVERSIBLE GAME? You can stop the play at any point, back up and then do an "instant replay", analyzing your strategy. Or back up and resume the game at an earlier point, trying out a different strategy. Reversibility makes learning a challenging new game more fun. And helps you become a skilled player sooner.

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'Sorting' continued from page 22

:11:40 :L157 5 DIM A(100) 6 KBD=-16304;CLR=-16360;TITLE= 500:INTRU=1000 7 DISPLAY=300:WAIT=800:COMPARE= 900:INTERCHANGE=950 9 MUSIC=-10473;TIME=766;TIMBRE= 765:PITCH=767 10 TEXT : CALL -936 20 GOSUB INTRO 530 RETURN 50 GOSUB TITLE 90 FOR R=0 TO 100:4(R)=32767: NEXT R 100 FOR 1=0 TO N 105 A(I)= RND (100):X=I: GOSUB DISPLAY 640 RETURN 108 IF N=0 THEN 150 800 110 NEXT I 805 150 FOR I=1 TO NUM-1 810 152 FLAG=0 ">" ; 155 FOR J=0 TO N-I 150 FOR T=0 TO PDL (1); NEXT T 159 GOSUB COMPARE 160 IF A(J)<=A(J+1) THEN 200 n n ‡ 133 X=100: POKE 50,127:A(100)=A(J): GOSUB DISPLAY 900 REM 165 KEEP=A(J): GOSUB INTERCHANGE: X=.J 170 POKE 50,63 173 A(J)=A(J+1): GOSUB DISPLAY: GOSUB INTERCHANGE: POKE 50 ,255 910 RETURN 175 GOSUB DISPLAY:X=J+1: POKE 50 103 180 A(J+1)=KEEP: GOSUB DISPLAY; * GOSUB INTERCHANGE: POKE 50 ,255 185 GOSUB DISPLAY 190 FLAG=1 195 KEY= PEEK (KBD): IF KEY<128 960 RETURN THEN 200 196 POKE CLR,0: GOSUB WAIT 200 NEXT J 202 IF FLAG=0 THEN 208 205 NEXT I 208 VTAB 24: TAB 21: PRINT "FINISH 1) 4 IF PEEK (KBD)<128 THEN 210 210 220 POKE CLR,0: CALL -936; GOTO 1015 TAB 10 20 500 TEXT : CALL -936 510 VTAB 1: FOR I=0 TO 9: TAB 7 1000

+3*I! PRINT I:: NEXT I 515 VTAB 2: TAB 7: FOR I=0 TO 9 "---";: NEXT I : PRINT 520 FOR J=0 TO 9: VTAB 3+2*J: TAB 4: PRINT J;"! ";: NEXT J 525 VTAB 23: TAB 1: PRINT "TEMP=" \$1 TAB 20 528 PRINT "BUBBLE SORT" 600 COL=X MOD 10 610 ROW=X/10 620 VTAB 2*ROW+3: TAB 7+3*COL 630 IF A(X)<10 THEN PRINT " "; 635 PRINT A(X); IF KEY<> ASC("Q") THEN 810 TEXT : CALL -936: END VTAB 2*ROW+3: TAB 6+3*COL: PRINT 815 KEY= PEEK (KBD): IF KEY<128 THEN 810 817 VTAB 2*ROW+3: TAB 6+3*COL: PRINT 820 POKE CLR,0: RETURN *** TO REMOVE SOUND FOR COM PARISONS - INSERT 901 RETURN *** 902 POKE PITCH, 10: POKE TIME, 5: CALL MUSIC 905 FOR DE=1 TO PDL (1); NEXT DE 950 REM *** TO REMOVE SOUND FOR INT ERCHANGES - INSERT 951 RETURN ** 952 POKE PITCH,49: POKE TIME,3: CALL MUSIC 955 FOR DE=1 TO PDL (1); NEXT DE 1000 VTAB 10: TAB 5: PRINT "I WILL SO RT UP TO 100 POSITIVE" 1001 TAB 5: PRINT "INTEGERS INTO ASCE NDING" 1002 TAB 5: PRINT "ORDER USING THE BU BBLE SORT." 1008 VTAB 15: TAB 10: INPUT "VALUE OF N PLEASE", NUM: N=NUM-1 1010 IF NUM<=100 THEN RETURN 1020 PRINT "TOO BIG!!!!!"; GOTO

Listing 2 **INSERTION SORT**

>FR#0 >LIGT 0 1=J=Y=N 5 DIM A(99) 6 KBD=-16384;CLR=-16368;TITLE= 500:INTR0=1000 7 DISPLAY=600:WAIT=800:COMPARE= 900:INTERCHANGE=950 8 MUSIC=-10473:TIME=766:TIMBRE= 765: PITCH=767 9 DELAY=975:ERASE=650 10 TEXT : CALL -936 20 GOSUB INTRO 50 GOSUB TITLE 90 FOR R=0 TO 99:A(R)=32767: NEXT R 100 FOR I=0 TO N 105 A(1)= RND (100):X=1: GOSUB DISPLAY 108 IF N=0 THEN 150 110 NEXT I 150 FOR I=1 TO N 151 IF I>N THEN 206:Y=A(I) 152 VTAB 23: TAB 32: PRINT "I=" : IF I<10 THEN PRINT " ";; PRINT I 153 VTAB 24: TAB 32: PRINT "Y=" ;: IF Y<10 THEN PRINT " ";: PRINT Y# 154 GOSUB INTERCHANGE 155 FOR J=I-1 TO 0 STEP -1 156 GOSUB DELAY:KEY= PEEK (KBD) : IF KEY<128 THEN 159 158 POKE CLR,0: GOSUB WAIT 159 GOSUB COMPARE 160 IF Y>A(J) THEN 202 A(J+1) = A(J)163 166 GOSUB INTERCHANGE 168 POKE 50,63 X=J: GOSUB DISPLAY: GOSUB DELAY 175 X=J+1: GOSUB DISPLAY: GOSUB 173 DELAY 180 POKE 50,255: GOSUB DISPLAY: GOSUB DELAY 185 X=J: GOSUB ERASE 200 NEXT J 202 A(J+1)=Y 203 POKE 50,63:X=J+1: GOSUB DISPLAY GOSUB INTERCHANGE 204 205 POKE 50,255: GOSUB DISPLAY 206 NEXT I VTAB 24: TAB 15: PRINT "FINISHE 1012 TEXT : CALL -936: END 208 13 1 210 IF PEEK (KBD)<128 THEN 210 220 POKE CLR:0: CALL -936: GOTO 20

500 TEXT : CALL -936 510 VTAB 1: FOR I=0 TO 9: TAB 7 +3*I: PRINT I:: NEXT I 515 VTAB 2: TAB 7: FOR I=0 TO 9 : PRINT "---";: NEXT I 520 FOR J=0 TO 9: VTAB 3+2*J: TAB 4: PRINT J;"! ";: NEXT J 525 VTAB 23: TAB 13: PRINT "INSERTIO N SORT" 530 RETURN 600 COL=X MOD 10 610 ROW=X/10 620 VTAB 2*ROW+3: TAB 7+3*COL IF A(X)<10 THEN PRINT " "; 630 635 PRINT A(X); 640 RETURN 650 COL=X MOD 101ROW=X/10 655 VTAB 2*ROW+3: TAB 7+3*COL 360 PRINT " **670 RETURN** 800 IF KEY<> ASC("Q") THEN 810 805 TEXT : CALL -936: END 810 KEY= PEEK (KBD): IF KEY<128 **THEN 810** 320 POKE CLR,0: RETURN *** TO REMOVE SOUND FOR COM 900 REM PARISONS - INSERT 901 RETURN *** 902 POKE PITCH, 10: POKE TIME, 5: CALL MUSIC 905 GOSUB DELAY 910 RETURN *** TO REMOVE SOUND FOR INT 950 REM ERCHANGES - INSERT 951 RETURN ** × 952 POKE PITCH,49: POKE TIME,3: CALL MUSIC 955 GOSUB DELAY 960 RETURN 975 FOR DE=1 TO PDL (1); NEXT DE RETURN 980 VTAB 10: TAB 5: PRINT "I WILL SO 1000 RT UP TO 100 POSITIVE" 1001 TAB 5: PRINT "INTEGERS INTO ASCE NDING" 1002 TAB 5: PRINT "ORDER USING THE IN SERTION SORT." 1008 VTAB 15: TAB 10: INPUT "VALUE OF N PLEASE", NUM: N=NUM-1 1010 IF N>=0 THEN 1013 1013 IF NUM<=100 THEN RETURN 1015 TAB 10 1020 PRINT "TOO BIG!!!!!": GOTO 1000

	SELEC	TION SO	
>F'R#0			
SLIST			
· • • • • •	Y Y Y SI	515	VTAB 2: TAB 7: FOR I=0 TO 9
0	I=J=Y=N DIM A(99)		PRINT "";: NEXT I
			TOR J=0 TO 9: VTAB 3+2*J: TAB
చ	KBD=-16384;CLR=-16368;TITLE=	020 P	(A = 0 + 0 + 0 + 0 + 0 + 0 + 0 + 0 + 0 + 0
	500:INTRO=1000		4: PRINT J;"! ";: NEXT J
7	DISPLAY=600:WAIT=800:CMP=900	525 \	JTAB 23: TAB 13: PRINT
	\$INT=950	1	"SELECTIO
Q	MUSIC=-10473:TIME=766:TIMBRE=	ę.	N SORT"
U	765:PITCH=767	570	
0		1 12 Mil 34	RETURN
	DELAY=975:ERASE=650		COL=X MOD 10
	TEXT : CALL -936		ROW=X/10
	GOSUB INTRO	620	VTAB 2*ROW+3: TAB 7+3*COL
50	GOSUB TITLE	630	IF A(X)<10 THEN PRINT " ";
	FOR I=0 TO N	1 - 201 - 20101 - CMI - 1	PRINT A(X);
	A(I)= RND (100):X=I: GOSUB		RETURN
100	DISPLAY		
	and the second se		IF KEY# ASC("Q") THEN 810
110	NEXT I		TEXT : CALL -936: END
150	FOR I=0 TO N-1		IF PEEK (KBD)<128 THEN 810
151	MAX=0	815	POKE CLR,0
152	VTAB 23: TAB 32: PRINT "I="	849	RETURN
	;: IF I<10 THEN PRINT " ";:		REM *** TO REMOVE SOUND FOR COM
	PRINT I	0.00	PARISONS - INSERT 901 RETURN ***
1 11 12	FOR J=1 TO N-I		TRUENT TRUENT AT RETORN 444
4 5 4	FOR DELLARDEN TE NEW MOD	040	DOLLE DETOIL AS & DOLLE TELED
100	KEY= PEEK (KBD): IF KEY<128	702	POKE PITCH, 10: POKE TIME, 5:
00000200000	THEN 158		CALL MUSIC
	POKE CLR,0: GOSUB WAIT	905	GOSUB DELAY
158	GOSUB DELAY	910	RETURN
159	GOSUB CMP	950	REM *** TO REMOVE SOUND FOR INT
1.60	IF A(J)<=A(MAX) THEN 200		ERCHANGES - INSERT 951 RETURN **
	MAX=J		*
	VTAB 24: TAB 32: PRINT "M="	050	
4 W W		7	POKE PITCH,49: POKE TIME,3:
	IF MAX<10 THEN PRINT " "		CALL MUSIC
1.10	S: PRINT MAX;	1111	COSUB DELAY
	POKE 50,63	960	RETURN
	X=J: GOSUB DISPLAY	975	FOR DE=1 TO PDL (1); NEXT DE
178	POKE 50,255	999	RETURN
185	X=J: GOSUB DISPLAY		VTAB 10: TAB 5: PRINT "I WILL SO
	NEXT J		RT UP TO 100 POSITIVE"
	TEMP=A(MAX): GOSUB INT	1001	TAB 5: PRINT "INTEGERS INTO ASCE
	A(MAX)=A(N-I):X=MAX: POKE 50	TAAT	
4., V 3./		1 6 5 10	NDING"
	<pre>,63: GOSUB DISPLAY: GOSUB INT:</pre>	1002	TAB 5: PRINT "ORDER USING THE SE
	POKE 50,255: GOSUB DISPLAY		LECTION SORT."
204	A(N-I)=TEMP:X=N-I: POKE 50,	1008	VTAB 15: TAB 10: INPUT "VALUE OF
	63: GOSUB DISPLAY: GOSUB INT:		N PLEASE",N
	POKE 50,255: GOSUB DISPLAY	1010	IF N>0 THEN 1013
212	NEXT I		TEXT : CALL -936: END
	VTAB 24: TAB 15: PRINT "FINISHED		
A	";		
710			TAB 10
	IF PEEK (KBD)<128 THEN 218	1020	PRINT "TOO BIG!!!!!": GOTO
220	POKE CLR, 0: CALL -936: GOTO		1000
	20		
500	TEXT : CALL -936		
	VTAB 1: FOR I=0 TO 9: TAB 7		
- 589258 (S	+3*I: PRINT I;: NEXT I		
	TATAT INANG 174 KEAL 1		

>PR#0 >LIST	Listin SHELL		
100	DIM A(99), INCS(5)		140
105	MUSIC=-10473:PITCH=767:TIME=	400	TEXT : CALL -936 VTAB 1: FOR I=0 TO 9: TAB 7
	766:TIMBRE=765: POKE TIMBRE, 32	12.0	+3*I: PRINT I;: NEXT I
110	KBD=-16384:CLR=-16368:TITLE= 400:INTRO=1000		VTAB 2: TAB 6: FOR I=0 TO 9 : PRINT "";: NEXT I
120	DISPLAY=500:WAIT=800:CMP=900	440	FOR J=0 TO 9: VTAB 3+2*J: TAB
105	:INT=950	450	4: PRINT J;"! ";: NEXT J VTAB 23: TAB 10: PRINT " SHELL S
	DELAY=975:ERASE=550 TEXT : CALL -936	400	ORT"
140	GOSUB INTRO		RETURN
	GOSUB TITLE		COL=X MOD 10 ROW=X/10
	FOR I=0 TO N A(I)= RND (100):X=I: GOSUB		VTAB 2*ROW+3: TAB 7+3*COL
1.70	DISPLAY	530	IF A(X)<10 THEN PRINT " ";
	NEXT I		PRINT A(X);
120	INCS(1)=10:INCS(2)=6:INCS(3))=4:INCS(4)=2:INCS(5)=1		RETURN COL=X MOD 10:ROW=X/10
200	FOR $I=1$ TO 5		VTAB 2*ROW+3: TAB 7+3*COL
	SPAN=INCS(I)		PRINT " "
	IF SPAN>N THEN 370 VTAB 24: TAB 12: PRINT "SPAN="	1.200 A.M. H. NOL	RETURN IF KEY<> ASC("Q") THEN 810
2.1.5	WIND 24. THD 12. PRIMI SPAR-	805	TEXT : CALL -936: END
216	IF SPAN<10 THEN PRINT " "#:	810	KEY= PEEK (KBD): IF KEY<128
C) (C) /.	PRINT SPAN	070	THEN 810 POKE CLR:0: RETURN
	FOR J=SPAN TO N Y=A(J): GOSUB INT		REM *** TO REMOVE SOUND FOR COM
	VTAB 23: TAB 28: PRINT "J= "		PARISONS - INSERT 901 RETURN ***
	<pre>####################################</pre>	900	POKE PITCH,10: POKE TIME,3:
235	TAB 26: PRINT "A(J)=";: IF	101 102.200	CALL MUSIC
	A(J)<10 THEN PRINT " ";		GOSUB DELAY
236	POKE 50,63: PRINT A(J);: POKE 50,255	949	RETURN REM *** TO REMOVE SOUND FOR INT
240	FOR K=J-SPAN TO 0 STEP -SPAN	1.00	ERCHANGES - INSERT 951 RETURN **
245	GOSUB CMP	050	* POKE PITCH,49: POKE TIME,3:
	IF Y>A(K) THEN 320 POKE 50,63	YOAL	CALL MUSIC
	GOSUB INT		GOSUB DELAY
	A(K+SPAN)=A(K)		RETURN FOR DE=1 TO PDL (1); NEXT DE
	X=K+SPAN: GOSUB DISPLAY KEY= PEEK (KBD): IF KEY<128		RETURN
	THEN 290	1000	VTAB 10: TAB 5: PRINT "I WILL SO
	POKE CLR,0: GOSUB WAIT GOSUB DELAY	1010	RT UP TO 100 POSITIVE" TAB 5: PRINT "INTEGERS INTO ASCE
	POKE 50,255: GOSUB DISPLAY		NUING"
305	X=K: GOSUB ERASE	1020	TAB 5: PRINT "ORDER USING THE SH
	NEXT K POKE 50,63	1030	ELL SORT" VTAB 15: TAB 10: INPUT "VALUE OF
	GOSUB INT	10.2503	N PLEASE",N
	A(K+SPAN)=Y:X=K+SPAN: GOSUB	1040	IF N>0 THEN 1060: CALL -936
720	DISPLAY Gosub Delay	10.40	: END IF N<=99 THEN RETURN
	POKE 50,255: GOSUB DISPLAY		TAB 10
360	NEXT J	1080	PRINT "TOO MANY!!!!!": GOTO
	NEXT I VTAB 24: TAB 12: PRINT "FINISH	2000	1000 POKE CLR.0
380	II <u>5</u>	2010	KEY= PFFK (KBD): IF KEY<128 THEN 2010
390	IF PEEK (KBD)<128 THEN 390 POKE CLR;0: CALL -936: GOTO		THEN 2010 0 POKE CLR:0: RETURN
575	COLL DENVET GILL / DOT DOTO	S. MILSON MA	

QUICKSORT >LIST 5 DIM A(200), STACK(24) 6 KBD=-16384;CLR=-16368;TITLE= 510 Q=J-1 5000:INTRO=10000 7 DISPLAY=6000:CMP=6500:DELAY= 599 RETURN 6600 8 MUSIC=-10473;TIME=766;TIMBRE= 765:PITCH=767 10 TEXT : CALL -936 20 GOSUB INTRO 50 GOSUB TITLE 100 FOR I=0 TO N 105 A(I)= RND (100):X=I: GOSUB DISPLAY 110 NEXT I 115 A(N+1)=32767 1185 TEMP=A(I) 120 P=0:Q=N 125 TOP=0:MAXTP=0 130 IF P>=Q THEN 170 135 K=Q+1 137 VTAB 23: TAB 34: PRINT "P= " 1196 GOSUB 8000 ;: IF F<100 THEN PRINT " "; : IF P<10 THEN PRINT " "); PRINT 1199 GOTO 1160 P 138 TAB 34: PRINT "Q= ";: IF K< 100 THEN PRINT " ";; IF K<10 **1999 RETURN** THEN PRINT " "): PRINT K) 139 GOSUB 1145 140 IF J-P<Q-J THEN 150 143 GOSUB 400 144 GOTO 160 150 GOSUB 500 160 TOP=TOP+2 7 161 IF TOP>MAXTP THEN MAXTP=TOP 162 VTAB 24: TAB 23: PRINT (TOP/ 2); 163 IF PEEK (KBD)>=128 THEN GOSUB 8000 0" ý 165 GOTO 130 170 IF TOP=0 THEN 208 175 Q=STACK(TOP):P=STACK(TOP-1) :TOP=TOP-2 176 GOSUB 7500 177 VTAB 24: TAB 23: PRINT (TOP/ 2); 5099 RETURN 179 IF PEEK (KBD)>=128 THEN GOSUB 8000 6010 ROW=X/10 180 GOTO 130 6020 POKE 50,63 208 VTAB 24: TAB 4: PRINT "FINISHED" 209 TAB 15: PRINT "MAXTOP= ")(MAXTP/ 5050 PRINT A(X); 2); 210 IF PEEK (KBD)<128 THEN 210 220 POKE CLR,0: CALL -936: GOTO 20 400 STACK(TOP+1)=P 6090 PRINT A(X); 6100 REM 405 STACK(TOP+2)=J-1 410 P=J+1 415 GOSUB 7000 ** 6110 POKE PITCH,49: POKE TIME,3:

499 RETURN

Listing 5

500 STACK(TOP+1)=J+1 505 STACK(TOP+2)=Q 515 GOSUB 7000 1145 V=A(P):I=P:J=K 1160 J=J-1: IF A(J)<=V THEN 1170 1162 GOSUB DELAY 1165 GOSUB CMP: GOTO 1160 1170 I=I+1: IF A(I)>=V THEN 1180 1172 GOSUB DELAY 1175 GOSUB CMP: COTO 1170 1180 IF J<=I THEN 1200 1186 A(I)=A(J);X=I: GOSUB DISPLAY 1188 A(J)=TEMP:X=J: GOSUB DISPLAY 1195 IF PEEK (KBD)<128 THEN 1160 1200 A(P)=A(J);X=P: GOSUB DISPLAY 1202 A(J)=V:X=J: GOSUB DISPLAY 5000 TEXT : CALL -936 5010 VTAB 1: FOR I=0 TO 9: TAB 7 +3*I: PRINT I:: NEXT I 5020 VTAB 2: TAB 7: FOR I=0 TO 9 : PRINT "---";: NEXT I 5030 FOR J=0 TO 19: VTAB 3+J: TAB 5035 IF J<10 THEN PRINT " "): PRINT J;"! ";: NEXT J 5040 VTAB 23: TAB 3: PRINT "QUICKSORT PARTITION=====>" 5045 VTAB 24: TAB 15: PRINT "PENDING: 5050 VTAB 5: TAB 39: PRINT "S": TAB 39: PRINT "T": TAB 39: PRINT "A": TAB 39: PRINT "C": TAB 39: PRINT "K" 5060 FOR R=10 TO 22: TAB 39: PRINT ".": NEXT R 5000 COL=X MOD 10 6030 VTAB ROW+3: TAB 7+3*COL 5040 IF A(X)<10 THEN PRINT " "; 6060 POKE 50,255 6070 VTAB ROW+3: TAB 7+3*COL 6080 IF A(X)<10 THEN PRINT " "; *** TO REMOVE SOUND FOR INT ERCHANGES - INSERT 6101 RETURN *

CALL MUSIC

- 6199 RETURN 6500 REM *** TO REMOVE SOUND FOR COM PARISONS - INSERT 6501 RETURN ** 6510 POKE PITCH, 10: POKE TIME, 5: CALL MUSIC **6599 RETURN** 6600 FOR DE=0 TO PDL (1): NEXT DE **6699 RETURN** 7000 VTAB 21-TOP: TAB 37 7005 TOS=STACK(TOP+1):NOS=STACK(TOP+2) 7010 IF NOS<100 THEN PRINT " ";: IF NOS<10 THEN PRINT " ";: PRINT NOS 7015 TAB 37: IF TOS<100 THEN PRINT " ";: IF TOS<10 THEN PRINT " ";: PRINT TOS;
- 7499 RETURN
- 7500 VTAB 21-TOP: TAB 37: PRINT " ": TAB 37: PRINT " ";

7999	RETURN
8000	POKE CLR,0
8005	IF PEEK (KBD)<128 THEN 8005
8010	POKE CLR,0
8099	RETURN
10000	VTAB 10: TAB 5: PRINT "I WILL SO
	RT UP TO 100 POSITIVE"
10010	TAB 5: PRINT "INTEGERS INTO ASCE
	NDING"
10020	TAB 5: PRINT "ORDER USING HOARE'
	S QUICKSORT."
10030	VTAB 15: TAB 10: INPUT "VALUE OF
	N PLEASE" ,N
10040	IF N>0 THEN 10060
10050	TEXT : CALL -936: END
10060	IF N<=199 THEN RETURN
10070	TAB 10
10080	PRINT "TOO BIG!!!!!": GOTO
	10000



1

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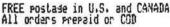
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REQUIREMENTS

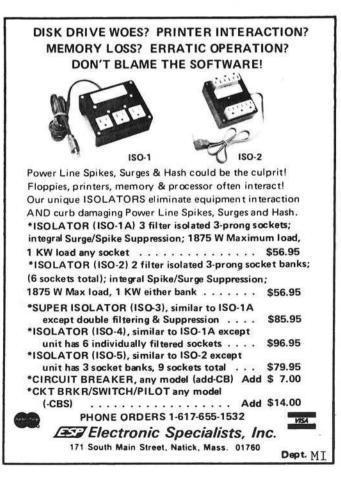
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A very inexpensive analog interface is presented that can be used with any microcomputer. Some PET oriented programs are provided, including a STAR ACE game, to show how the device may be utilized.

John Sherburne

When I bought my PET, one of the things I eventually wanted to do was to interface the computer to the outside world. Over the two years since then I have seen interface devices of one kind or another, but all of them have been fairly expensive, and most are designed for a single application. I have finaly found one interface, however, which is cheap, simple enough for even the laziest Sunday solderer to build, and is useful for a variety of real world applications. By plugging in a joystick or two, arcade-type games can be created. If the interface is used to dense switch settings, educational programs or game show recreations can be easily made. Adding a potetiometer or thermistor as a sensor permits measurement of temperature, wind direction or other external conditions. All in all, it is the best way I have found for the PET owner with a tight budget to branch out into new areas.

The interface uses a single integrated circuit — an NE555 timer. The principle of operation is to hook up the timer as in Figure 1 so that it emits a pulse when triggered by the PET. The duration of the pulse depends upon the magnitude of the resistance, R1, in the circuit. By timing the pulse duration with the PET internal clock, the resistance can be measured. Thus, any device which translates an external quality into a resistance can be used as a sensor. Using the circuit requires three elements: a 5 volt DC power supply, the 555-based timer and a sensor. If you don't already have a power supply there is no need to buy an expensive one just for this application. I found that a small kit such as the Jameco JE 200 is adequate, inexpensive (\$14.95) and can be put together in less than an hour.As for sensors, the cost and availability depend on what you want to do. A simple measure of displacement can be made with a potentiometer costing less than a dollar. Precision probes for temperature, on the other hand, may be expensive and hard to find. The third element, the NE555, costs about 60° and a four timer interface with board, wire, connectors and the like can be constructed for about \$10.

Interface to the PET is made through pins PA0 - PA7 of the parallel user port shown in Figure 2. These eight pins can be programmed for either input or output by changing the contents of memory location 59459 (E843). If bit n of that location is a zero, PAn will be an input pin. If bit n is a one, PAn will be an output pin. For example, POKE 59459,15 will make pins PA0 - PA3 output and pins PA4 - PA7 input. Once programmed, the pins are read or driven via location 59471 (E84F). In this way the user port can be programmed so that one pin is used as output to trigger a 555 and another pin is used as input to sense the duration of the timer pulse. Since there are eight pins, four 555s can be connected without resorting to encode/decode arrangements.

Figure 3 is a schematic of a four 555 interface. The interface is sufficient to handle two joysticks each of which has two potentiometers or four individual sensors. Two NE556s could also be used since the 556 is a dual 555. The pin by pin connection for each of the 555s is as follows:

- 1 Connect to ground.
- 2 Trigger.Connect to output pin of users port. This pin is normally high (+5V). When brought momentarily to ground, it starts the 555 output pulse.
- 3 Output. Connect to users port input pin. This pin is normally low (ground). During the output pulse it is high.
- 4 Connect to +5V.
- 5 Connect to ground through bypass capacitor C2
- 6 Connect to +5V through sensor R1 and connect to ground through timing capacitor C1.
- 7 Connect to pin 6.
- 8 Connect to +5V.

Each of the four 555s in Figure 3

is connected the same way. The four trigger pins (pin 2) are connected to PA0 — PA3 and the four output pins (pin 3) are connected to PA4 - PA7. The PET ground is connected through R2 to the IC ground (pin 1).

The output pulse duration of the 555 is dependent both on R1 and C1. As C1 is increased in capacitance, the pulse is longer. A .01 yf capacitor works well for moderate sensor resistances (50K to 1 meg ohm). For lower resistances, a higher capacitance is needed. Capacitors must be high quality mylar for stability. The duration of the output pulse also increases as R1 increases. If there is no resistance at R1, that is, pin 7 is shorted to +5V, the pulse duration will be essentially zero. An open circuit between pins 5 and 7 will cause an almost unending pulse.

To measure the duration of the pulse, one of the timers associated with the parallel user port is accessed. The timer is two bytes long and decrements with every cycle of the PET clock (every microsecond). The least significant byte of the timer is at location 59464 (E848). It starts at 255, counts down to zero and recycles. The most significant byte is 59465. It starts at 255 and counts down each time 59464 reaches zero. The speed of the timer requires that machine language rather than BASIC be used to access it. Program 1 is a simple assembly language program which drives one pin of the user port low then high, starts the timer and waits for the end of the output pulse of the 555. The pulse length is then stored in locations 42 and 43 (2A and 2B). The pins to be used for output and input are determined by memory locations 40 and 41 (28 and 29), respectively. For example, if bit 6 of location 41 is a one, then it takes 16 clock cycles to start the output pulse and check the input pin, 16 microseconds is the minimum pulse width that can be measured in increments of 7 cycles beginning at 16 (16,23,30...).

Once the interface has been constructed, Program 1 can be used to test its operation. First connect pin 6 of each 555 to +5V, then load Program 1 and key in the following:

10 POKE 59459,15

20 FOR I = 0 TO 3 30 POKE 40, 16*2 I:POKE 41,2 I;SYS(977) 40 A = 255-PEEK (42) + 256*(255-PEEK(43)) 50 PRINT A: NEXT

The result should be that A is about equal to the minimum 16 in each case. The program assumes that four 555s are present with pin 2 of each connected to one of the first four pins of the user port. Pin 3 of each 555 is connected to one of the last four pins of the user port. That is, if pin 2 of a 555 is connected to PAn, then pin 3 is connected to PAn + 4. If there is a mistake in wireing or software the result will probably be a list cursor type crash.

The easiest sensor to connect in the circuit is a simple switch. If a 50K resistor is connected across the poles of the switch, the switch will present no resistance in one position and a resistance of 50K resistor is connected across the poles of the switch, the switch will present no resistance in one position and a resistance of 50L in the other position. Connecting four such switches in series with a different resistance across each one enables the 555 to determine which of the four switches has been thrown. If normally closed pushbuttons are used with resistances of 50K, 150K, 300K and 600K as buttons are pushed, a resistance of 50K when button #1 is pushed, 150K for #2, 200K for #1 and #2, and so forth. This arrangement can be used as the basis for guiz or educational games where the players give their answers by pushing one of the buttons. Since only one 555 is required for each set of switches, up to four players can play at the same time.

Another useful switch arrangement is to connect a normally open pushbutton in place of R1 for each

"DOODLE"

10 RT=20:UP=12 20 POKE 59459,15 30 REM CALIBRATE JOYSTICK IN CENTER 40 PRINT "[clear]PLACE JOYSTICK IN CENTER. PRE SS ANY KEY WHEN READY." 50 GET A\$: IF A\$="" GOTO 50 60 POKE 40,16:POKE 41,1:SYS(977) 70 A=255-PEEK(42)+256*(255-PEEK(43)) 80 POKE 40, 32: POKE 41, 2: SYS(977) 90 B=255-PEEK(42)+256*(255-PEEK(43)) 100 AL=.6*A:AH=1.2*A 110 BL=.6*B:BH=1.2*B

555. If a 555 is triggered it will emit an output pulse which will continue until its pushbutton is pressed. A test of reflex speed can be constructed by triggering all four 555s, instruction the player to push one of the buttons and then measuring the time it takes him to respond.

Since the response time will be longer than the timer at 59464 can handle, the "jiffy" timer, TI, should be used. Program 2 is an example of how the timer can be used. The recheck procedure in lines 220 and 230 is needed to correct for poor pushbutton action. The value Z in line 165 should be set to yield Y50 when there is no time delay between asking for a response and pushing the button. The same principle used in the reflex test can be used along with CB2 sound to simulate the electronic games which require the duplication of a series of sounds.

One of the more useful applications of the 555 interface is the joystick. One 555 is used to sense the position of each of the two potentiometers in the joystick. There are two ways that the joystick position can be translated into cursor movement. One is to move the cursor relative to some fixed position such as the center of the screen. In this mode a given joystick position always moves the cursor to the same spot on the screen. The technique is useful in obtaining input for games like Checkers or Othello. The other mode is to use the joystick position to indicate movement relative to the current postion of the cursor. This technique is useful in manuevering through a maze or in other real-time games. In this mode moving the joystick in a given direction moves the cursor in that direction. As long as the joystick is held in that positsion the cursor will continue to move. Returning the joystick to the center stops the cursor. The following sequence illustrates this technique:

Of course, this routine must be used in conjunction with Program 1. The routine can easily be expanded to move the cursor more than one location at larger joystick displacements. With some checks to keep the print position on the screen added, the program can be used to draw pictures or "doodle". μ

John Sherburne is an operations research specialist with the Department of Defense. He has a number of years experience in mathematical computer programming. Microcomputing is his hobby.

······

REM SENSE JOYSTICK POSITION
POKE 40, 16: POKE 41, 1: SYS(977)
A=255-PEEK(42)+256*(255-PEEK(43))
POKE 40.32: POKE 41.2: SYS(977)
B=255-PEEK(42)+256*(255-PEEK(43))
REM CALCULATE NEW POSITION
R=-1:IF A>AL THEN R=0:IF A>AH THEN
U=-1:IF B>BL THEN U=0:IF B>BH:THEN
7
RT=RT+R:UP=UP+U:PRINT "[home]";

1090 FOR I=1 TO UP:PRINT:NEXT

1100 PRINTTAB(RT) "X":GO TO 1000

PROGRAM 1			Asse	mbly	Languag	e	
03D1 03D3 03D5 03D8 03D8 03D8 03D8 03D8 03D8 03D8 03D8	A5 A6 B0 84 88 88 88 88 80 80	229F0A389FFFF889A8	E8 E8 E8 E8 E8 E8 E8 E8 E8 E8	WAIT	LDA LDX STX LDY STY STY STY STY STY STY STX BNE LDX LDY STX STY	IFUT OPUT PORT # 00 ANSR ANSR+1 TIML TIML TIMM PORT PORT WAIT TIML TIML TIMM ANSR ANSR+1	:Load input mask :Load output mask :Set trigger high :Clear result :Clear timer :Clear & start timer :Bring trigger low :Return to high :Wait for end of pulse :Store result
03F9	60				RTS		

BASIC Program to Load Assembly Language

10 DATA 165,40,166,41,142,79,232,160,0, 132,42,132,43,140,72,232,140,73,232,140

20 DATA 79,232,142,79,232,44,79,232,208 ,251,174,72,232,172,73,232,134,42,132

30 DATA 43,96

40 FOR I=977 TO 1017

50 READ A: POKE I, A: NEXT

PROGRAM 2

10 POKE 59459,15:Z=9
20 N(0)=239:N(1)=223:N(2)=191:N(3)=127
25 L\$(0)="A":L\$(1)="B":L\$(2)="C":L\$(3)="D"
30 PRINT "[clear] THIS IS A TEST OF YOUR REA
CTION TIME"
31 PRINT "[down] WHEN YOU SEE A LETTER ON THE
SCREEN"
32 PRINT "[down] PRESS THE BUTTON WITH THE SA
ME LETTER"
33 PRINT "[2 down] PRESS ANY KEY WHEN YOU ARE
READY"

Program 2 cont.

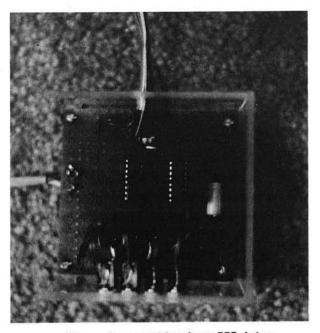
40 GET A\$: IF A\$="" GOTO 40 60 I=999+INT(500*RND(1)) 70 FOR K=0 TO I:NEXT 120 POKE 59471,15 122 I=INT(4*RND(1)) 130 TI\$="000000":E=0 140 POKE 59471,0 145 PRINT "[down]":L\$(I) 150 POKE 59471,15 160 WAIT 59471,255,255 170 R=PEEK(59471) 18C IF R(>N(I) GOTO 220 190 Y=INT(Y*100/60)/100 200 PRINT "YOU TOOK":Y: "SECONDS":END 220 IF E=0 THEN E=1:GOTO 170 230 IF E=1 THEN E=2:POKE 59471.0:GOTO 1 50 300 PRINT " [clear] WRONG BUTTON!":END

Notes:

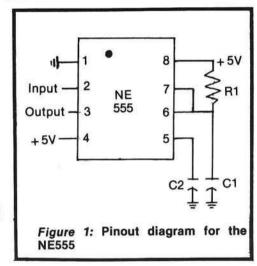
Line 140 and line 150 start timerpulse. Line 160 waits until one of the pins PA4 - PA7 goes low.Line 180 checks to see if proper button was pushed. Lines 220 and 230 recheck for errors caused by poor pushbutton action.

STAR ACE

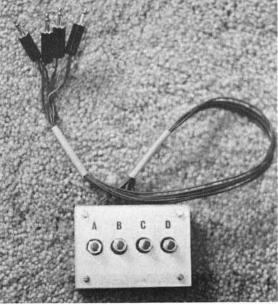


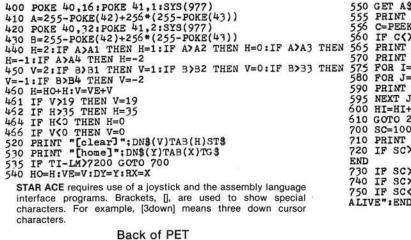


View of assembler four 555 interface device.



View of assembled reflex testing device.





							70.04					
		Π	Π	П	П		Π	П	П		Π	
-0		Ц										-
G	С	5		_		_	-		1	С	G	
N	B				047	' DA	^			Α	N	
D	2			8	PAI	- PA	0			1	D	

Figure 2: Rear view of the PET Parallel User Port. All pins are on the bottom of the edge card. PAO is to the right.

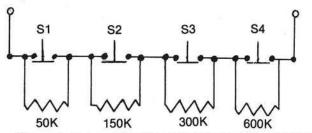
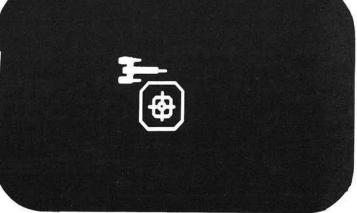
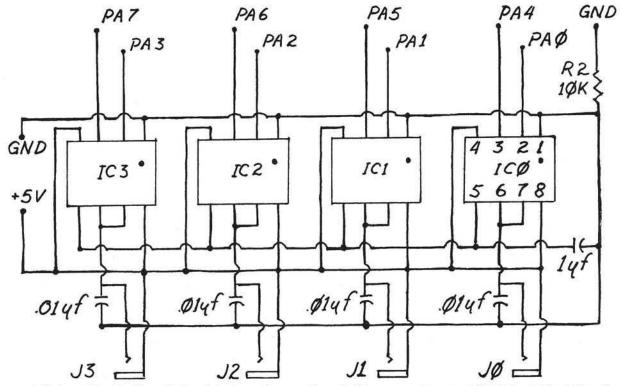


Figure 4: Schematic of a response sensing device.

550 GET A\$:IF A\$<>*F" GOTO 300 555 PRINT "[nome]":"LASER'S FIRED!":SH=SH+1 556 C=PEEK(32580+40*V+H) 560 IF C()98 AND C()254 GOTO 300 565 PRINT "[clear]";DN\$(Y)TAB(X)E\$(0) 570 PRINT "[clear]"; DN\$(Y)TAB(X)E\$(1) 575 FOR I=1 TO 4 580 FOR J=2_TO 5_ 590 PRINT "[clear]"; DN\$(Y+I)TAB(X)E\$(J) 595 NEXT J:NEXT I 600 HI=HI+1:PRINT "[clear]HITS ";HI:PRINT "SHOTS FIRED ";SH 610 GOTO 290 700 SC=100*HI-(10*SH) 710 PRINT "YOUR SCORE IS ";SC 720 IF SC>499 THEN PRINT "[3 down] ACE!!!! CONGRATULATIONS.": END 730 IF SC>249 THEN PRINT "[3 down]GOOD SHOOTING!":END 740 IF SC>0 THEN PRINT "[3 down]YOU NEED MORE PRACTICE":END 750 IF SC<1 THEN PRINT "[3 down]YOU'RE LUCKY TO STILL BE



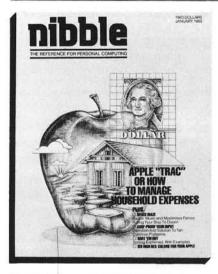
Screen display from STAR ACE game.



ALIVE": END

Figure 3: Schematic of a four device interface. Connections to the computer are at the top. Jacks J0 to J3 are phone jacks for connecting sensors. All capacitors are Mylar.

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Zoom And Squeeze

A short program for the Apple II which makes it easier to edit BASIC programs. ZOOM provides a fast way to copy over a program line; SQUEEZE changes the screen width to 33 characters and eliminates embedded blanks.

Gary B. Little

ZOOM and SQUEEZE is a short machine-language routine written for the APPLE microcomputer in order to facilitate the editing of BASIC programs. It recognizes two commands: CTRL-Q and CTRL-Z. The CTRL-Q command causes the screen window width to be automatically set to 33 and the CTRL-Z command causes the cursor to quickly copy over all text from its current position to the end of the line.

The ZOOM Feature

In order to edit a program line on the APPLE it is necessary to more than simply move the cursor directly to the area to be changed, make the changes, and then press RETURNthe required procedure is to position the cursor at the beginning of the line number, copy down to the area to be changed (by using the rightarrow and repeat keys, make the changes, and enter the edited line. If the line is a very long one, the copying-over part of this procedure takes up an enormous amount of time which can be better used for other purposes.

The 'ZOOM' part of the ZOOM and SQUEEZE routine can be used to speed up this copying tremendously. By simply pressing CTRL-Z the

cursor can be moved virtually instantaneously from its current position to the right edge of the current line while automatically copying over all the text on the screen in between. For example, to copy over a program line that takes up three lines on the video screen takes only six quick steps after the cursor has been positioned at the beginning of the line number: CTRL-Z, rightarrow, CTRL-Z, right-arrow, CRLT-Z, RETURN. This takes approximately 2 seconds to accomplish. By way of contrast, to copy over the line in the ordinary way by using the right-arrow key in conjunction with the repeat key takes aproximately 13 seconds (see the NOTE below!)

It is clear, then, that this feature could save hours of debugging time for a busy programmer.

The SQUEEZE Feature

When a line of a BASIC program is listed on the video screen with the window width set at its default value of 40 columns, the output is carefully formatted by the APPLE by embedding blanks on the left and right sided of the listing. That is to say, there is not a continuous 'wraparound' display of the information that you typed in to create the line. For example, if you enter the line 100 PRINT "THIS IN AN EXAMPLE OF A FORMATTED LISTING"

and then LIST it, the APPLE will respond with

100 PRINT "THIS IS AN EXAMPLE OF A F**

****ORMATTED LISTING"

where a '*' indicates an embedded blank. This formatting technique makes it very easy to read a LISTed line, but it can create a minor problem when it becomes necessary to edit the line.

The problem arises when, as in the example, the blanks are embedded between the quotation marks associated with a PRINT statement. If this line is to be edited without retyping it from scratch, the rightarrow key (in conjunction with the repeat key) must be used to copy over substantial portions of the line and by so doing all 6 of the embedded blanks between 'F' and 'ORMAT-TED' will mysteriously appear in the argument of the PRINT statement UNLESS they are skipped over by performing pure-cursor movements - i.e., repeated ESC-A commands or, for AUTOSTART ROM users, repeated K commands after ESC has been pressed. The need to perform these pure-cursor movements is annoying and inconvenient to say the least.

				2	******	*****	*******	****
				3	*			•
				4	* ZO0	M AND	SQUEEZE P	ROCRAM *
				5	*		ARY LITTL	
				6	* 1	101-20	44 W. 3RD	AVE. *
				7	*	VANC	OUVER, B.O	C. *
				8	*		DA V6J 11	L5 *
				9	*	JANU.	ARY 1980	*
				10	*			*
				11			3DOG' TO /	ACTIVATE *
				12		RUN FR	DI DISK).	
				13	*			anna R
				14			Z TO ZOOM	
				15			HE RIGHT-	
				16				(TEXT IS*
				17	* AUTOM	ATICAL	LY COPIED	OVER). *
				18				*
				19 20			TO SOUEL	CZE THE *
				21	* COLUM	N WIDT!	I TO 33.	*
				22		******		*
				23	WIDTH	EOU		
				24	CH		\$21	WINDOW WIDTH
				25	BASL	EQU	\$24	HORIZONTAL CURSOR POSITION
				26	KSWL	EQU	\$28	SCREEN BASE ADDRESS POINTER
				27	IN		\$38	INPUT HOOK (LO)
				28	KEYIN	EQU	\$200 \$FD18	INPUT RUFFER
				29	KL I I S	ORG	\$300	KEYPRESS ROUTINE
3	AO	09		30		LDA	# <inhk< td=""><td>SET INPUT HOOK</td></inhk<>	SET INPUT HOOK
		38		31		STA	KSWL	TO SINUK
		03		32		LDA	#>INHK	10 3100
		39		33		STA	KSWL+1	
	60			34		RTS	KAN LIT I	
	20	18	FD	35	INHK	JSR	KEYIN	GET A CHARACTER
		91		36		CMP		CTRL-O PRESSED?
	DO	07		37		BNE		IF NOT, CHECK FOR CTRL-Z
	A9	21		38		LDA	#\$21	CHANGE WINDOW VIDTH
	85	21		39		STA	WIDTH	TO 33
	A9	AO		40		LDA	#SAO	OUTPUT A SPACE
	60			41		RTS		
i,	C9	9A		42	CTRLZ.	CITP	#SOA	CTPL-Z PRESSED?
i.	DO	1F		43		BNE	RTS1	IF NOT, RETURN
	A4	24		44	LOOP	LDY	СЧ	TAKE A CHARACTER
	75.70	28		45		LDA	(BASL),Y	OFF VIDEO SCREEN
	48			46		PIIA		
		24		47		INC	СН	
		24		48		INC	CH	
	2022	24		49		LDA	CII	IF CURSOR POSITION IS
	C5			50		CMP	WIDTH	AT FAR RIGHT,
		OR		51		BCS	FIN	THEN FINISHED
		24		52		DEC	CH	
	68	192320	12121	53		PLA		STORE CHARACTER
		00	02	54		STA	IN,X	IN INPUT BUFFER
	E8	12243		55		INX		
	DO	E8		56		BNE	LOOP	GET ANOTHER CHARACTER OFF SCREEN
	CA			57		DEX		;BUFFER FULL,
	60			58		RTS	72	; SO RETURN
	68			59	FIN	PLA	122210	
	C6			60		DEC	Сн	SET PROPER CHARACTER
	C6	24		61 62	RTS1	DEC	CH	POSITION AND
						RTS		; RETURN

This problem can be avoided if the window width is 'squeezed' to 33 columns before LISTing the line and editing it. If this is done, the embedded blanks disappear and the line can be edited without worrying about the need to perform purecursor movements.

The window width can be changed to 33 be entering the command POKE 33,33 from BASIC immediateexecution mode. However, with the ZOOM and SQUEEZE routine in effect all that need be done is to press CTRL-Q. The width can be returned to its default value of 40 by simply entering the command TEXT from immediate-execution mode.

How ZOOM AND SQUEEZE Works

ZOOM and SQUEEZE can be activated by BRUNning it from disk or by loading it, entering the command 300G from the monitor, and then returning to BASIC. The routine resides from \$300 to \$33A.

After it has been activated, the APPLE's input hook at \$38 (low), \$39 (high) is set equal to the ZOOM and

SQUEEZE entry point at \$309. Thereafter, all keyboard input is checked to see whether CTRL-Q or CTRL-Z has been pressed; if not, then nothing special happens.

If CTRL-Q is pressed, the short subroutine beginning at \$310 and ending at \$316 is executed. All this subroutine does is store \$21 (decimal 33) at location \$21 — this is the location in the monitor that contains the current window width. A blank is then displayed on the screen to indicated that this has occurred.

If CTRL-Z is pressed, the subroutine beginning at \$317 is executed. What happens then is that the characters displayed on the screen from the current cursor position to the end of the line are placed in the input buffer one-by-one. If the buffer is overflowed, the program line will be backslashed and cancelled in the ordinary way.

Details of the programming algorithms involved can be easily deduced by inspecting the accompanying source listing for ZOOM and SQUEEZE.

NOTE: it is possible to speed up the repeat-key function by soldering a 100K resistor in parallel to the resistor at position R4 on the APPLE keyboard unit. For details, see the article 'REPEAT KEY SPEED-UP' by V.R. Little in the February 1980 edition of APPLEGRAM, the newsletter of the Apples British Columbia Computer Society, Vancouver, B.C.



Gary B. Little first became interested in computers by writing data analysis programs in FOR-TRAN on an IBM 370/168 for an M. SC. degree in Physical Chemistry (Microwave Spectroscopy). Ultimately he became interested in microcomputing and purchased an APPLE II micro 11/2 years ago.

He was past president of APPLES BRITISH COLUMBIA COMPUTER SOCIETY, an an APPLE user group located in Vancouver, B.C. Gary is currently the treasurer of this group.

0300:

0302:

0306.

0308.

0309: 030C:

030E :

0310:

0312:

0314:

0316:

0317: 0319: 031B:

031D:

031F:

0320:

0324:

0326:

0328:

032A:

032C: 032D:

0330:

0331:

0333:

0334: 0335:

0336:

033A:

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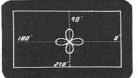
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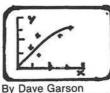
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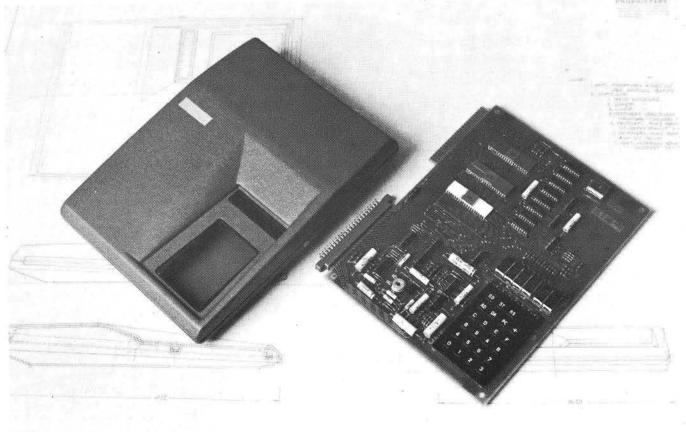
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OHIO SCIENTIFIC'S

Welcome to the second issue of the Ohio Scientific Small Systems Journal in Micro.

In this issue, Ohio Scientific is pleased to introduce a new concept in computer interfacing — the Sixteen Pin I/O BUS. The BUS concept as well as several boards and applications are covered in the following pages.

Also in this issue, a short, graphics oriented game in BASIC called 'FOO' is presented.

Reader suggestions on article content are welcome. Please submit them to:

Ohio Scientific, Inc. Small Systems Journal 1333 S. Chillicothe Rd. Aurora, Ohio 44202

The Ohio Scientific Sixteen Pin I/O BUS

Ohio Scientific is pleased to introduce a unique new product line — The 16 Pin I/O BUS. With this system it is possible to add up to eight special function boards while occupying only one backplane slot.

This is made possible by a novel BUS extension method which allows decoding, timing and eight bits of data to be carried on standard, inexpensive 16 pin ribbon cables.

Up to eight inexpensive 16 pin cables with standard DIP connectors may be attached to a single CA-20 board which in turn occupies one slot of the standard Challenger backplane. Alternately, one 16 pin I/O BUS cable may be attached to the CA-15 board at the rear of all C4P and C8P products. Note, in the case of the C4P-MF this allows system expansion beyond the normal four slot backplane.

Currently, five HEAD END CARDS are available for interconnection to the system via the CA-20 or CA-15 boards.

Computer Interface to Sixteen Pin I/O BUS

The 16 pin I/O BUS may be attached to your computer via two different boards — the CA-15 or the CA-20. The descriptions of these boards are as follows:

CA-15 Board

The CA-15 board is a standard accessory interface installed on the following Ohio Scientific systems: C4P-MF, C4P-DMF, and C8P-DF.

The CA-15 is mounted at the rear of the computer and contains the following interface connections:

Joystick and numeric keypad

Modem and serial printer

Sixteen PIA lines (normally used for the Home Security system — AC-17P) Sixteen Pin I/O BUS

The interconnect for the Sixteen Pin I/O BUS is simply a

16 pin DIP socket. To use the BUS, all that you have to do is attach one end of the 16 pin ribbon cable to the CA-15 board and the other end of the cable to one of the HEAD END CARDS. Please note that some of the HEAD END CARDS require more power than may be practically carried via the ribbon cable alone. Therefore, some of the cards require auxiliary power supplies.

CA-20 Board

The CA-20 board contains all the necessary logic to decode eight distinct HEAD END CARD interfaces. The actual interconnect, as with the CA-15, is via simple 16 pin DIP sockets and standard 16 pin ribbon cables.

The CA-20 board also requires one slot of your computer's backplane. But remember, from this one slot you gain access to a maximum of eight accessory boards.

The CA-20 is recommended for use in the Ohio Scientific C2 series and C3 series computers. It can also be installed in C4P and C8P series systems with some modification to the CA-15 interface.

Since the logic required for the I/O BUS interface is pretty simple, an additional feature was added to the CA-20 board — a crystal controlled 'time-of-day' clock (hardware) subsystem. The operation of the clock, excepting reading time and setting time, is totally independent of the host computer.As a matter of fact, with the included on-board, auto-recharging, battery back-up, your computer may actually be turned off for several months without losing time.

The features of the clock subsystem are as follows:

Hours, minutes, seconds and 1/10 seconds Day of week Day of month Month of year Four Year calendar

If you happen to own (or use) a C2 series or C3 series computer,the CA-20 board can actually control the power cycling of the entire computer when equipped with an optional power sequencer package. This means you can preset a time (month, day,hour,etc.) within the clock subsystem and that preset time agrees with the actual time, A.C. power is applied to the entire computer system through the power sequencer.At a later time, the system's A.C. power may also be removed and the system shut down under software/clock subsystem control.

For applications where the clock subsystem is not required, the CA-20A will perform all the Sixteen Pin I/O BUS functions associated with full-feature CA-20.

HEAD END CARDS

HEAD END CARDS is a general name used to describe any or all of the special function boards which attach to the Ohio Scientific Sixteen Pin I/O BUS. There are currently five such boards and, with the exception of the CA-22, they will only interface with the computer via the Sixteen Pin I/O BUS.

Please note, as detailed earlier, you must use a CA-15 or a CA-20 board at the 'computer end' of the Sixteen Pin I/O BUS to complete the interface.

In the following pages, a brief product and application

SMALL SYSTEMS JOURNAL

description of the currently available HEAD END CARDS will be presented.

Bit Switching and Sensing - The CA-21

The CA-21 is a 48 line parallel I/O board featuring three 6821 PIAs (peripheral interface adapters) and prototyping/interconnect areas.

The use of PIAs in the design allows for maximum interface versatility as you may configure any one of the 48 I/O lines as either an input or an output. As outputs, each line is capable of driving a minimum of one standard TTL load.

Additional versatility is added because 24 of the lines, when configured as outputs, may simultaneously function as inputs. This feature, although somewhat confusing, is extremely useful for applications such as switch matrix decoding.

Each of the 48 lines is brought out to two foil pads (suitable for wire wrap stakes) as well as a location on one of four 12 pin Molex-type female edge connectors. There are also eight 16 pin DIP socket locations which are intended for use as prototyping areas. Additionally, the 12 PIA 'hand-shaking' lines are brought to 12 single foil pads.

The CA-21, with proper buffering, may be used for virtually any computer controlled bit switching or bit sensing application that you can imagine. With a full complement of eight CA-21s interfaced via the CA-20, a total of 384 individually controllable I/O lines are possible!

An interesting application using one CA-21 board would be a complete, is somewhat slow, emulation of the standard Ohio Scientific BUS.

A more standard application might be augmenting the standard Home Security System (AC-17P) with 'hard-wired' sensors.

One type of sensor you could easily add is a standard windor 'perimeter detector'. This could be done with commercially available adhesive foil tape. You could then detect a break-in (through a broken window) by sensing a break in the foil tape.

Another useful application you could set up in concert with the AC-12P wireless A.C. Remote Control, might be sensing when a room is entered. You could accomplish this with pressure-switch door mats or door switches. When room entry is detected, the lights could be turned on or, turned off on exit.

If you are designing any sort of dedicated control system, the CA-21 is an ideal choice. You can easily sense innumerable types of input (pressure transducers, flow sensors, switches, etc.) while controlling outputs from a simple single LED display to a network of solid state relays controlling A.C. power.

EPROM Programmer — The CA-23

The CA-23 is an EPROM programmer designed for use with the growing families of 5 volt only EPROMS. With the CA-23 you can program and verify all 1K through 8K byte EPROMS of this type. Note these parts are often identified as 8K - 64K bit EPROMS.

The CA-23 can program (or verify) data in two basic modes — EPROM to/from EPROM or EPROM to/from computer RAM memory. Additionally, EPROM data may be read directly into the computer's RAM memory.

There are four LED indicators on the CA-23. The first is 'SOCKET UNSAFE'. This means that a programming voltage is present at the socket and if you insert or remove an EPROM it is likely to be damaged.

The second indicator is 'PROGRAMMING'. This means that your EPROM is currently being programmed.

The third indicator is 'ERROR'. This means that somewhere along the line your programming attempt was unsuccessful.

The final indicator is 'PROGRAM COMPLETE'. This means that your program and verification was successful.

The most intriguing application for this product is the creation of 'custom' parts for your computer or peripherals. This could range from a new system monitor to a new high level language. It could even include a new character generator for your CRT or printer. Note, however, tinkering around with the internals of computers and peripherals requires a fairly high degree of technical expertise. Also, most manufacturer's warranties are voided by these types of modifications.

Several OEM (original equipment manufacture) and Research/Development applications will be immediately obvious to those you involved in that work.

The CA-23, as previously mentioned, is designed for use with 1K through 8K byte EPROMS. These parts come in various package styles and have various product names. For example, Intel's 2Kx8 part is the 2716, Texas Instruments' part is known as the 2516.

The CA-23 has both 24 pin and 28 pin zero insertion force sockets for reading, programming and verifying the EPROMS.

Prototyping — The CA-24

The CA-24 is a solderless bread-board designed for proto-typing, experimental and educational applications.

The bread-boarding is made up of seven solderless plug-strips of the type manufactured by AP Products. Two of the plug-strips contain a connection matrix of 5 by 54, connecions and are used as signal distribution points. Another pair of 96 location plug-strips are for powering the bread-board area. The actual experimenter area is comprised of three plug-strips, each with a 10 by 64 location connection matrix. Additionally, sixteen LED indicators and sixteen DIP switch positions are provided for signal observation and control functions.

Board I/O is via TTL latches and bi-directional PIA ports as well as direct (buffered) data, signal and control lines from the computer BUS. This method allows you to directly interconnect devices such as 6850 ACIAs in addition to doing more 'isolated' and/or independent circuits.

OHIO SCIENTIFIC'S

The CA-24 also contains a 'clock' generator which is continously variable from approximately 25,000 Hz. through 70,000 Hz. You may also connect the clock to an on-board 16 stage divider chain. This allows division of the fundamental frequency by as little as 2' (2) to as much as 2'⁶ (65,536).

The applications for the CA-24 are primarily prototyping and experimenting. Parts may be inserted and removed from the terminal strip blocks over and over. Interconnection of parts is accomplished simply with solid, narrow guage wire jumpers. Errors in design or connection are extremely easy to correct.

The CA-24 lends itself very well to structured experiments that are common in the educational environment. It is an ideal tool to aid in the teaching of computer and computer interface fundamentals.

Accessory Interface - The CA-25

The CA-25 is designed to implement some of the functions normally associated with the CA-15 interface board.

It allows you to directly connect the Home Security System (AC-17P) and/or the Wireless A.C. Remote Control System (AC-12P) to C2 and C3 series computers. Additionally, if you own an older Ohio Scientific computer, you can now easily connect these systems to it.

An extremely useful application of the CA-25 is associated with small business systems. Using the CA-25 with the Home Security System, and perhaps a CA-15V (Universal Telephone Interface with speech synthesizer output), the computer could do payroll, inventory, etc. by day and 'guard' the shop by night.

Analog I/O - The CA-22

The CA-22 is a high speed analog I/O module. Although the CA-22 is classified as a HEAD END CARD, it differs from the rest of the family in that it may also be plugged directly into the computer's standard internal BUS. This allows for maximum flexibility in the use of the CA-22.

The analog input section of the CA-22 consists of a 16 channel analog multiplexer. This means that you may connect up to 16 separate signals directly to the CA-22. Also included is a sample and hold circuit followed by the analog to digital converter circuitry.

The A to D converter is capable of either 8 bit or 12 bit operation. You may select these options under software control.

The accuracy of the converter is plus or minus one in the least significant bit. The stability of the circuit is rated at one millivolt drift per degree Centigrade.

The A to D conversion is extremely fast. It is capable of digitizing up to 66,000 samples per second in the 8 bit conversion mode and 28,000 samples per second in the 12 bit mode. Shannon Sampling Theory states that signals should be sampled at twice their frequency. Therefore, it is possible for you to convert signals with a frequency greater than 30K Hz. Clearly, high fidelity audio is well within the spectrum of the CA-22.

The multiplexer has very high impedance inputs and is capable of accepting inputs in the range of -10 volts through +10 volts. The input is jumper selectable for other settings including a single sided range of 0 through +10 volts.

Due to the indeterminable nature of the actual inputs that you may actually apply to the CA-22, only the multiplexer inputs are brought out. However, a quad opamp is laid out in foil which you may populate in several different modes to handle some of the more 'common' input configurations.

The analog output section of the CA-22 consists of two identical high speed digital to analog converters. Each DAC can convert either 8 bits or 12 bits of data. Data input to the DACs is latched in such a manner that, when in the 8 bit conversion mode, the other four (of the total of twelve) bits are continuously output at a predefined value. You may, of course, define that value under software control.

The output of each DAC is buffered with a high speed op-amp capable of changing 20 volts every microsecond. The standard configuration of each output is bi-polar with a voltage swing of -10 volts through + 10 volts. This is jumper selectable to allow a uni-polar output of 0 through + 10 volts.

Some additional I/O capacity is provided on the CA-22. There are three TTL level inputs and six open collector logic outputs. These are strappable to be either standard TTL level outputs or high-voltage outputs.

You can use the CA-22 for a multitude of analog sensing and/or analog controlling applications.

Using the proper transducers and the 16 input channels, you can monitor the temperature in several zones of a home or office. By extending this system with a CA-21, you could maintain precise temperatures by switching the proper controls on and off.

Another interesting, if somewhat obvious application, is in audio processing. Reverberation, phase shifting and echoing are just a few of the uses you could implement.

If you used blocks of RAM for data storage, other applications such as frequency doubling, etc., could be experimented with.

If you apply more sophisticated software techniques, such as a fast Fourier transform, on stored input data, very elaborate signal processing becomes realizable. Projects such as sudio spectrum analyzers and speech recognition experiments are certainly practical. Note, in these types of applications you are likely to find some signal pre-processing in hardware is certainly beneficial if not totally necessary.

If you employ both DAC outputs and the on-board unblanking circuit, X-Y oscilloscope plotting is an interesting application. By using these techniques and one or more of the analog inputs, you can construct a digital storage scope. Note, both of these applications require that you have access to an oscilloscope capable of X-Y input as well as blanking.

SMALL SYSTEMS JOURNAL

Summarv

With the introduction of the 16 pin I/O BUS, Ohio Scientific has opened a new world on interfacing capabilities for both the large and the small computer user.

Systems ranging from totally automated sampling and control stations to complete R/D setups to educational lab stations are now available to you via standard building blocks and standard computer systems.

For pricing and availability, contact your nearest Ohio Scientific dealer.

FOO

This is an amusing graphics game that simulates a twisting road scrolling up from the bottom of the screen. You must avoid going off the road. Speed and road width are selectable. Pedestrians are also optional, with a bizarre twist. At your option pedestrians are to be avoided or run down for points. FOO runs on disk based C4P and C8P video systems. The tone generator is used to provide sound. The program is easily adapted to OSI BASIC-in-ROM computers.

- POKE 2893, 55: POKE2894, 8: POKE2073, 96 100
- BS=55040:SM=2:MS=1:KY=57088:ME=54144+15:MI=0:RN=0 110
- ML%=0 115
- 117 SN=255
- 120 LP=5
- 130 PL=2/LP
- 135 POKE57089,1
- POKE9680,32:POKE56832,2 140
- 150 C=226
- 155 KP=0
- 160 IFA\$='Y'THENME=EM:WI=WF:GU=UG:GOT0270
- 170 FORI=1T030:PRINT:NEXTI
- 180 PRINT'FOO'
- 190 PRINT: PRINT' RACEWAY'
- 200 PRINT: PRINT 'You run at your own risk!'
- PRINT:PRINT' <== LEFT=1 RIGHT=2 ==> ' 210
- 215 PRINT: PRINT 'OVERDRIVE=RUBOUT'
- 220 PRINT: PRINT'SUGGEST WIDTH=20, DELAY=20'
- 230 PRINT: INPUT'INITIAL WIDTH (0-30)':WI
- 240 PRINT: INPUT'DELAY (1-20)'; ME: EM=ME
- 245 PRINT
- GU=0: INPUT ' PEDESTRIANS 250
- (Y/N)';X\$:IFLEFT\$(X\$,1)='Y'THENGU=.3 255 UG=GU:PRINT
- 257 IFGU=OTHEN270
- KP=0:INPUT'KILLER FOO 260
- (Y/N)';X\$:IFLEFT\$(X\$,1)='Y'THENPK=1
- 270 PRINT: PRINT'Hidden wonders await
- the' PRINT'Masters!
- FORI=1T030:PRINT:NEXTI 280
- WD=WI:WF=WI:ME=55104+15-ME*64:WT=(30-WI)/2 290
- 295 IFA\$='Y'THENRETURN
- 300 FORM=1TOLP:GOSUB600:GOSUB500:ML%=ML%+1:NEXTM
- 350 WI=WI-1
- 360 LP=LP*1.14
- 370 IFWI > 4THEN300
- SM=SM+.2:MS=MS+.1 380
- 400 FORM=1TOLP:GOSUB600:GOSUB500:ML%=ML%+1:NEXTM
- 450 WI=WI+1
- 460 LP=LP*.85
- 470 IFWI < WDTHEN400

- 475 IFWD < 2THENWD=WF
- 480 WD=WD*.75
- 490 GOT0300
- 499 REM OUTPUT A FRAME
- 500 RN=RN+SM*RND(1)-MS
- 510 WT=WT+SGN(RN)
- 520 IFWT+WI>28THENWT=WT-1:RN=0:GOT0520
- 530 IFWT < OTHENWT=0:RN=0
- 540 IFWI > 8ANDRND(1) < GUTHENPOKEBS+WT+1+INT
- (WI*RND(1)),240 550 PRINTSPC(WT); '><'; SPC(WI); '><'
- 560 RETURN
- REM MOVE BALL. 599
- POKEKY, 128:K=PEEK(KY):KK=0:POKEKY, 64:K2=PEEK(KY) 600
- 610 IFKAND128THENME=ME-1:KK=-1+0*RND(1)
- 620 IFKAND64THENME=ME+1:KK=1
- 630 TFK2AND4THENME=ME+KK
- 640 IFPEEK(ME) <> 32THEN700
- 650 POKEME.C
- 660 RETURN
- GY=PEEK(ME): IFGY=240ANDPKTHENKP= 700 KP+1:GOSUB2000:GOT0650
- 710 POKE 2073,173
- FORI=100T0250STEP5:POKE57089,I:NEXTI 715
- 719 POKE57089,1
- 720 PRINT'YOU BLEW IT!!!'
- 725 PRINT
- 730 MI=ML%*PL
- 750 PRINT'AFTER ';MI;' MILES'
- 755 IFPKTHENPRINT'AND '; KP; ' KILLS'
- PRINT: PRINT ' TOTAL 757 POINTS: '; INT(MI+4*(1-PK)*MI+100*KP)
- 760 GOSUB1000
- 770 K=1
- 780 FORI=1T01000*K:NEXTI
- 790 IFPEEK(KY) <>1THEN790
- 800 POKE9680,95
- 805 POKE57089,1
- 810 GOT05000
- 1000 IFPKTHENWD=KP:GOT01030
- 1010 WD=MI/WF
- 1030 PRINT: PRINT'Congratulations!'
- 1040 PRINT'You may now call yourself'
- 1050 PRINT:PRINT'
- 1060 IFWD < 3THENPRINT'LITTLE';:GOT01200
- 1070 IFWD < 5THENPRINT 'TENDER';:GOT01200
- 1080 IFWD < 12.5THENPRINT'MEDIOCRE';:GOTO1200

1:

- 1090 IFWD < 25THENPRINT'BIG';:GOTO1200
- 1100 IFWD < 38THENPRINT'MASTER';:GOTO1200
- 1110 IFWD < 50THENPRINT'GRAND';: GOTO1200
- 1120 PRINT'CHEATER';

2003 IFSN=50THENSN=255

5010 IFA\$ <> 'Y'THEN6000

5025 IFA\$ <> 'Y'THENCLEAR

2005 POKE57089, SN

2010 POKE 57089,1

2020 RETURN

5030 GOT0100

6000 END

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- 1200 PRINT' FOO';
- 1210 IFGY=240THENPRINT' KILLER';

5000 INPUT'AGAIN';A\$:A\$=LEFT\$(A\$,1)

5020 INPUT'SAME';A\$:A\$=LEFT\$(A\$,1)

1220 PRINT'!' 1230 RETURN 2000 SN=SN-5



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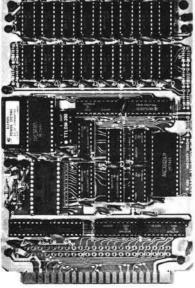
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VIZA — KIM

A KIM Monitor extension program which provides the automatic display of the important system parameters at each step. The discussion reveals some details of the 6502 interrupt handling mechanism.

Joel Swank

After reading George Lang's article on his U-PANEL project (MICRO-COMPUTING, January 1979), I decided to implement his idea on my KIM-1 system. U-PANEL is a front panel display for KIM. It uses an extension of the KIM single step circuit (SST) and a small routine to dump the processor registers in binary to a panel of discrete LEDs. This is done by connecting the KIM SST signal on pin E-17 to the IRQ interrupt line on pin E-44. The SST signal is generated every time the CPU SYNC signal is generated and the instruction being executed is not located in the KIM ROM. SYNC is generated with each opcode fetch. Normally during KIM single step operation the SST signal is switched to the nonmaskable interrupt (NMI) line. This causes an interrupt during the first cycle of each instruction. Since an instruction cannot be interrupted in the middle, the interrupt is recognized immediately after the instruction is finished. The NMI vector cannot be set to a routine outside the KIM ROM while the SST switch is on because the first instruction of that routine will also cause the NMI interrupt to be taken, resulting in a continuous loop. Instead of the NMI George switched the SST signal to the IRQ line, KIMs maskable interrupt. This allows the interrupt to be vectored to any routine anywhere in the system rather than just the KIM ROM. The IRQ vector was changed to the register dump routine which returns control to KIM after outputtine the registers to U-PANEL. This routine must run with interrupts disabled to prevent it from being interrupted.

Since I don't particularly care for reading binary lights, I decided to dump in HEX to my CRT terminal. This saves building the U-PANEL. and provides a more readable display. The changes to George's program were simple and I soon had my code ready to test, but I couldn't get it to work properly. I double checked everything and it all looked OK. So I started to analyze the problem.

The register dump to the CRT was working, but the CPU was not being interrupted after each instruction. It would execute a few insturctions and then stop. When I pushed GO it would execute a few more and stop. After a little thought I decided to see which instructions were being executed without being interrupted. Soon a pattern emerged. The CPU was being interrupted only after instructions whose execution time were two cycles. Any instruction whose execution time was 3 or more cycles was not being interrupted. Why? The answer lies in the MOS Technology hardware manual. The NMI interrupt is edge sensitive. That is, the interrupt is recognized by the change from high to low not just the presence of the low signal. Also, once the transition has occured the processor will be interrupted before the next instruction starts, no matter what. The IRQ is not edge sensitive. A low on the IRQ line must coincide with a zero in the processor interrupt flag and the last cycle of an instruction. If the IRQ line goes low and high again while the CPU is not ready to accept inter-



rupts, the interrupt will be missed. In this case the SST signal because it is driven by SYNC will be low during the first cycle of an instruction and because of propagation delay, slightly into the second cycle. Therefore any instruction that is 3 cycles or longer will cause the interrupt to be missed. So the interrupt occurs only after two cycle instructions (the 6502 has no one cycle instructions).

To fix this problem the SST pulse must be lengthened to last at least as long as the 6502's longest instruction. The circuit in figure one does this. It uses a one shot to extend the pulse. This circuit produces a pulse of about one millisecond, much longer than needed, but it doesn't matter as long as the pulse is long enough. This circuit will provide a properly operating U-PANEL

After resolving the pulse length problem I decided to add a slow motion feature. This would be a mode that would execute an instruction and then, after dumping the registers, instead of returning to KIM, would delay for a programmable amount of time and execute the next instruction. This would allow the execution of a program in slow motion without pushing GO between each instruction. The code needed to add this feature is fairly simple and it was soon ready to test. I implemented it with a time value at \$E9. This value is the delay time in in guarter seconds. Zero means slow motion not in effect. On first try I set the delay to two seconds and started the program. The first instruction was executed and the registers dumped, but there progress stopped. The delay was working properly and the display being updated every two seconds but the PC was not advancing. It was stuck on the second instruction. I stopped execution and started it again. This time the second instruction was executed and it stuck on the third. Once again the problem was in the non edge sensitive IRQ interrupt.

When in normal mode, each instruction in the dump routine generates a pulse. These pulses are ignored during execution of the dump routine because it runs disabled. The pulses stop once execution enters the KIM ROM. The RTI instruction that KIM executes as a result of pushing GO enables the IRQ and the first instruction in the object program generates a pulse that causes an interrupt immediately after it executes. The dump routine is then executed, and control is returned to KIM to wait for the next GO. In slow motion mode the GO routine is executed via a JMP instruction from the dump routine. If the pulse generated is longer than the time needed to execute the GO routine (about 38 microseconds) the IBQ line will still be low from the JMP instruction when the RTI instruction is executed. This will cause an interrupt immediately after the RTI instruction and no instruction of the object program will be executed. To solve this problem, the pulse must be shortened to less than the duration of the GO routine. This can be done by changing the resistor in figure one to 2K Ohms. This generates about a 35 microsecond pulse, longer than the longest 6502 instruction but shorter than the KIM GO routine.

I called my version of the program VIZA-KIM. The code for version 1 is included. It provides a formatted display on the CRT after each instruction is executed. Version 2 has been enhanced to display in large characters on my SWTPC GT-6144 graphics board. This display on my 19 inch TV can be read by an entire room of people. VIZA-KIM makes an execellent device for learning the operation of the CPU. The exact effect of each instruction can be seen.

The VIZA-KIM dump displays the program counter (PC) and the first three bytes of data at that location. A nice enhancement would be to include a line for a disassembled instruction. The next line is for the stack pointer (SP). The current stack pointer is displayed along with three bytes from the stack page. The first byte is where the next push operation will store its data. The 6502 stack pointer always points to the next available byte. The next two bytes are the data from the last two push operations, or the data that will be read by the next two pull operations. If the last push operation was a jump subroutine (JSR) instruction this will be the return address minus 1. Next are the index registers (X and Y) and the accumulator (A). Last is the processor status register (P). All data is displayed in HEX except for P. P is formatted in binary since its in-

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dividual bits have separate meanings.

To use VIZA-KIM set the IRQ vector (\$17FE) to the address of the dump routine and turn on the new SST switch. Be sure the use P register at location \$F1 has the interrupt flag (bit 2) set to zero, since the object program must run with interrupts enabled. To use slow motion mode set \$E9 to the number of quarter seconds of delay desired, enter the address of the object program and press GO. Instructions will be executed one at a time after the desired delay. To stop execution hold down any key on the KIM keyboard. To use normal mode clear \$E9 to zero and enter the address of the object program. Operation will be the same as in KIM SST mode.

VIZA-KIM makes one aware of each change of the state of the processor as each instruction is executed. This makes bugs more easily spotted as well as giving one a better understanding of how the 6502 works.

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Microbes & Updates

Bill Watts of Provincetown, Mass phoned in the following changes to Henk Wevers' article "Shorthand Commands for Superboard II and Challenger C1P BASICs" (24:25):

Page 26:

Line 028B Restore 14 68

Line 028F should be 67

0291 should be 65,

0292: 61

0295: 64

0298: 62

029A: 63

029E: 66

Page 27: Line 0236 should read A2 58, instead of A2 43.

With these changes, things should run smoothly.

Bill Crouch from California writes:

Line 63000 of the program XFILE.MAKER (23:11) was sent as "63000 REM XFILE.MAKER". The typesetter dropped the line number and used it as a title. The programs will not work unless there is a line 63000 in XFILE.MAKER so some of your readers might have problems with it.

Also, if you want to use REM KILLER on a program which has GOTO and GOSUB statements which refer to remark lines, you can change line 310 of REM KILLER to read:

310 PRINT ARRAY(Y);CHR\$(58)

This will replace the REM statements with a colon. Although it doesn't save as much space as a complete removal of the REMs, the program will still work as before.

From Robert and Jon Prall of Silver Spring, Maryland found a problem in "Apple II Speed Typing Test with Input Time Clock" in the December issue of 1979.

On page 19:69 line 8406 reads in the published version, subtracting 159 from ASCII numbers assigned to the individual characters does not correspond to the position of characters the A\$.

The inclusion of the quotation mark at position three in the string is logical, but impossible because it causes a "Syntax Error" message, and a blank space should be substituted for it.

The corrected line should read:

8406 A\$ = '' ! #\$%&'()* + ,-. /0123456789:; < = > ?@ABCDEFGHIJKLMNOPQRSTUVWXYZ''

The position of the spaces in the string is essential; the signs for greater than and less than must be included, as must the exclamation point. The author's inclusion of the slash, the small 'm' amd a space at the end of the string appear to be additional errors.

With the corrections noted, the program runs very well.

Rev. James Strasma sends this update to his article entitled "Lower Case Lister" (25:11):

A revised printer ROM is now available for CBM printers without charge. It improves lower-case listings. However, the 20 characters that failed to print correctly in lower-case mode before stil fail. "Lower Case Lister" is compatible with the new '04' printer ROM., and corrects all characters.

Challenger II Communications

Everything you need to turn your OSI with a 502 CPU board into a 'standard' communications terminal: hardware changes and the software to run it.

Peter Koski

As a college student, time becomes extremely valuable. A very poor use of this time is sitting waiting for a computer terminal. Corollary to Murphy's Law — there are never enough terminals; and who uses cards in this day and age?

Looking logically at the situation, there was only one answer, and my OSI Challenger II was it. Generously enough, Ohio Scientific has provided their 502 CPU board with all the foils needed for serial TTL/RS-232 input/output.

My answer was found. While others are sitting at terminals till the wee hours of the morning, I can be happily talking to Myron (our resident IBM) from the comfort of my room. Stereo in the background, fridge to the right ... what a life!

Of course this also opens up a whole horizon of dial-up bulletin board services as well as time-share systems. Options no computerist should live without.

Hardware

Before any software can be written, we'd better have some hardware to play with. Conveniently enough, the cassette port runs at 300 baud. No problem here. What about the -9 volts required by RS-232? Again we're allright: most modems only require a swing to zero level. Great!

First, let's start with the output side of the problem. Locate, using

OSI's 502 schematic package, the positions of U31,R55, R56, R57 and Q2. Some boards may or may not have U31 on them already. If not, install U31 using an I.C socket. The values for the parts may be summarized:

U31	7404	(hex inverter)
R55, 57	10KΩ	(1/4 watt)
R56	470Ω	(1/4 watt)
Q2	2N5226	

Carefully solder these to the board, confirming the positions. Check for any solder bridges which may crop up.

Input becomes only a bit more complicated. In order to maintain cassette capability, a switch must be inserted in the ACIA input line (the cassette input ciruit loads down the line). Any SPDT switch which fits on the rear apron will suffice (Radio Shack's paddle switches fit the 3/4 inch holes perfectly). Install the switch and we'll worry about wiring it later.

Again referring to the 502 layout sheet, locate U20, R61, R62, D3, and Q4. As with U31, U20 may or may not exist already. If not, be sure to use a socket when installing it. Once their positions are located, the following parts may be installed:

U21	7404	(hex inverter)
R61	10KΩ	(1/4 watt)
R62	4.7KΩ	(1/4 watt)
D3	1N914	
Q4	2N5225	

Be certain the board looks right before continuing on.

Going to pin 2 of the ACIA (U3) is the RX DATA foil. Cut this foil at some convenient point and solder the center terminal lead of the switch to the ACIA side of the cut. Solder one of the other leads to the other side of the break. In this switch position, cassette operation is as normal. Back to the newly installed U20. Locate the foil from pin 2 and cut it. To the U20 side of this foil, solder the remaining lead of the select switch. In this switch position, RS-232 input will be routed to the ACIA. A good thought would be to install a 3-pin in-line connector somewhere between the board and the select switch.

A standard RS-232 connector may also be added to the rear apron. The RX DATA is now at pin 1 of connector J3 and TX DATA at pin 7 of J3. All the even pins of J3 are ground. (-9 volts is bussed on the backplane, just add your supply if needed).

Unless you feel confident in your soldering abilities, you may want to let a trustworthy friend do the work for you. It only takes half an hour or so, but errors could be disasterous — and it's your own fault.

What you are now left with is an RS-232 port which resides at FC00 (same as cassette port). The input is selectable: cassette or 300 baud RS-232. Output is always there, allowing for convenient printer listings of programs being SAVEd to

.

tape. The uses and tricks that can be inplemented are too numerous to list; you'll find them yourself.

As for the modem, the Novation Cat is probably the top of the line if you can afford it. I have used it with excellent results over phone lines which would have made speech recognition rough, and I have not lost a bit. Plus it offers answer in addition to originate mode.

Software

Two options are now possible, and I've tried both. OSI's BASIC is fast enough to service the port via PEEKs and POKEs. However the draw-back is that it is very difficult to output BASIC control symbols (comma or colon). A BASIC routine is the easiest route if you wish to set up a system for down-loading locally-editted files. This is a very handy routine which works well. See the two BASIC programs below.

On the other hand, the following assembler routine turns your brilliant computer into an ignorant terminal. Running with this system, the Challenger II behaves like a standard ASCII terminal, except the obscure CTRL functions will appear as OSI graphics.

The package includes a protected field at the top of the screen to provide a 'touch of class' without taking too much screen space.

As written, the routine is loaded into 2000 hex. However, it could be relocated fairly easily. The only monitor routine called is the keyboard input routine, whose entry point in the 65V MONITOR is FEED hex (should be the same for all systems). The program continually polls both the port and the keyboard, then displays or output (as the case may be) whichever is requesting service at the time. Autoline feed is provided only on out-put (as the case may be) whichever is requesting service at the time. Autoline feed is provided only on out-put carriage return. Most dial-ups will provide line-feed with carriage return.

As an added note of interest, the RS-232 outputs from both the Challenger II and modem are able to handle two loads. This means that a printer could be used on one line (normally input) to provide hardcopy as desired. Certainly no computer system should be without RS-232 communications capabilities.

My system has behaved flawlessly through "mega-hours" of hard use. Good luck, and don't make Ma Bell too rich with your calls!

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Peter is a sophomore at Rensselaer Polytecnic Institute majoring in Biomedical Engineering — Electronics option. His minor is in Computer Systems. He has an Ohio Scientific Challenger C2-4P which he uses for both academic and hobby purposes. Pete started his programming in BASIC and recently added assembler capability to his machine's repetoire.

1999	REM TERMINAL OPERATING SYSTEM
1010	REM
1020	REM VERSION 3.2
1022	REN
1825	REM PETER KOSKI 12/79
1039	I REM
1035	REM STRIKING EITHER 'SHIFT' KEY ENTERS
1037	REM TRANSMIT MODE (? PROMPT)
1938	REM
1040	REM WHEN ENTERING A COMMA OR COLON, THE
1858	REM 'CTRL' MUST ALSO BE DEPRESSED
1060	REM
1090	REM - UNDERSCORE IS CONTROL HYPHEN
1100	REN
1110	REM - OR OPERATOR IS CONTROL 1
1120	
1130	REM NOT OPERATOR IS #
1140	KEM
2000	POKE 530,1: POKE 57083,1: POKE 64512,1
2010	IF (PEEK(64512)RWD1)THEN PRINT CHR#(PEEK(64513));
2020	IF (PEEK(57088)=1) THEN 2010
2839	INPUT TX\$
2640	FOR TX=1 TO LEN(TX\$)
2050	FOR DLA=1 TO 15: NEXT DLA
2969	IF RSC(MID\$(TX\$,TX,1))=122 THEN POKE 64513,58: GOTO 2100
2865	IF R5C(MID\$(TX\$,TX,1))=108 THEN POKE 64513,44: GOTO 2100
2970	IF R5C(MID\$(TX\$,TX,1))=109 THEN POKE 64513,95: GOTO 2100
2090	IF ASC(MID\$(TX\$,TX,1))=113 THEN POKE 64513,124:GOTO 2100
2090	IF ASC(MID\$(TX\$,TX,1))= 35 THEN POKE 64513,126: GOTO 2100
2995	PCKE 64513,ASC(MID\$(TX\$,TX,1))
2100	HEXT TX
2150	FOR DLA=1 TO 15: NEXT DLA: POKE 64513,13
2160	FOR DLA=1 TO 15: NEXT DLA: POKE 64513,10
2170	GOTO 2010
0K	

19941 REM VERSION 3.3 1002 REM 1003 REM 11/79 1994 REM - PETER KOSKI 1995 RFM 1996 REM - LOCAL FILE EDITOR / TERMINAL SYSTEM PACKAGE 1007 REM 1999 DIM LINE\$(60), TEMP\$(64) 1010 FOR CLS=1 TO 20; PRINT: NEXT CLS >>>> TOS VERSION 3.3 <<<<<" 1020 PRINT" 1839 PRINT: PRINT: PRINT: " --- LOHD (LOHD LOCAL FILE)" 1949 PRINT:PRINT " --- EDIT (EDIT LOCAL FILE)" 1059 PRINT: PRINT " --- THOD (ENHANCED TERMINAL MODE)" 1968 FRINT: PRINT: PRINT: INPUT MOD\$ 1970 IF LEFT\$(MOD\$,4)="LOAD" THEN ID=1 1080 IF LEFT\$(NOD\$,4)="EDIT" THEN ID=2 1890 IF LEFT\$(NOD\$,4)="TMOD" THEN ID=3 1100 ON ID GOSUB 2000, 3000, 4000 1110 GOTO 1010 2000 REM - LOAD LOCAL FILE 2010 FOR CLS=1 TO 14:PRINT:NEXT CLS 2015 FOR CH=1 TO 60: LINE\$(CH)=CHR\$(32); NEXT CH 2828 PRINT " >>> LOCAL FILE LOADER <<<<" 2025 PRINT: PRINT 2039 PRINT:PRINT * --- OR operator is CTRL-1* 2035 PRINT:PRINT * -- NOT operator is #° 2040 PRINT: PRINT " --- UNDERSCORE is CTRL HYPHEN" 2050 PRINT:PRINT * -- CTRL must be depressed when* 2660 PRINT " entering a COMMA or COLON" 2070 PRINT:PRINT " --- \$ENDFILE marks end-of-file" 2000 PRINT: PRINT: LN=1 2000 THEFT LINES(LN) 2100 IF LEFT\$(LINE\$(LN),8)="\$ENDFILE" THEN RETURN 2110 LN=LN+1: GOTO 2090 3000 REM -- EDIT LOCAL FILE 3010 FOR OLS=1 TO 14: PRINT: NEXT OLS 3960 PRINT " >>> LOCAL FILE EDITOR </// 3070 FRINT: PRINT 3099 PRINT:PRINT " --- INSERT , LINE NUMBER PRECEEDING INSERT" 3399 PRINT * LOCATION DESIRED* 3100 PRINT: PRINT " --- DELETE , LINE NUMBER TO BE DELETED" 3105 PRINT:PRINT " --- LIST 3110 PRINT: PRINT " --- DONE"

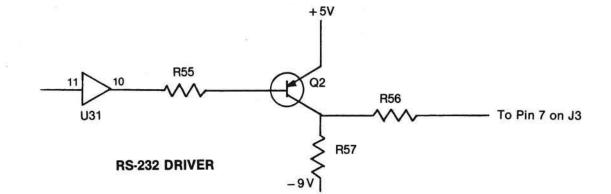
TERMINAL OPERATING SYSTEM

1000 RFM

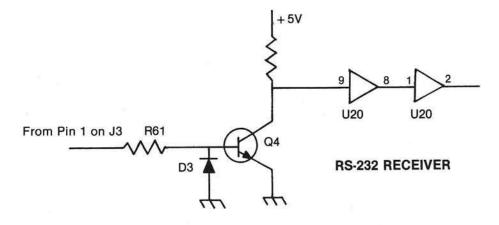
3120 PRINT: PRINT: INPUT "OPTION"; OPTN\$ 3148 IF LEFT\$(OPTN\$,4)="LIST" THEN ID=3: GOTO 3189 3150 IF LEFT\$(OPTN\$,4)="DONE" THEN RETURN 3160 INPUT " LINE";LINE 3170 IF LEFT\$(OPTN\$.6)="INSERT" THEN ID=1 3175 IF LEFT\$(OPTN\$,6)="DELETE" THEN ID=2 3189 ON ID GOSUB 3299, 3269, 3310 3199 6010 3129 3200 FOR B= (LN+1) TO (LINE+1) STEP -1 3218 LINE\$(B)=LINE\$(B-1) 3220 NEXT B 3230 PRINT: INPUT INSERT\$ 3249 LINEX(LINE+1)=INSERT\$ 3250 INH NHI: RETURN 3960 FOR CHINE TO LN-1 3270 LINE\$(C)=LINE\$(C+1) 3289 NEXT C 3290 LINE \$(LN)=CHR\$(32) 3360 UN=UN-1: RETURN 3310 PRINT: PRINT: FOR D=1 TO LN 3320 PRINT D. LINE\$(D) 3330 NEXT D: RETIEN 4000 KEN -- ENNEMLED TERMINEL OPERATING SYSTEM 4010 FOR CLS=1 TO 10: PRINT: NEXT CLS 4828 PRINT " >>> ENHANCED TERMINAL OPERATING SYSTEM <<<<* 4838 FRINT: PRINT 4032 PRINT:PRINT " --- Striking either SHIFT key enters" 4035 PRINT" TRANSMIT mode (? prompt)* 4040 PRINT:PRINT " --- OR operator is CTRL-1" 4050 PRINT:PRINT " --- NOT operator is #" 4055 PRINT: PRINT " --- UNDERSCORE is CTRL HYPHEN" 4960 PRINT:PRINT " --- CTRL must be depressed when" 4865 PRINT" entering a COMMA or COLON" 4075 PRINT: PRINT " --- DUMP (DUMPS LOCAL FILE)" 4976 PRINT: PRINT " --- DONE" 4078 PRINT: PRINT 4080 POKE 530.1; POKE 57088.1; POKE 64512.1 4882 IF (PEEK(64512)RND1) THEN PRINT CHR#(PEEK(64513)); 4083 IF (PEEK(57088)=1) THEN 4082 4084 INPUT TX\$ 4085 IF LEFT\$(TX\$.4)="DUMP" THEN 5000 4087 IF LEFT\$(TX\$,4)="DOME" THEN RETURN 4100 FOR TX=1 TO LEN(TX\$)

4110 FOR DUR=1 TO 15: NEXT DUR

26:55



4120 IF ASC(MID4(TX\$,TX,1))=122 THEN POKE 64513,58: GOTO 4200 4130 IF ASC(MID4(TX\$,TX,1))=108 THEN POKE 64513,44: GOTO 4200 4140 IF ASC(MID4(TX\$,TX,1))=109 THEN POKE 64513,95: GOTO 4200 4150 IF ASC(MID4(TX\$,TX,1))=113 THEN POKE 64513,124:GOTO 4200 4160 IF ASC(MID4(TX\$,TX,1))=35 THEN POKE 64513,126:GOTO 4200 4170 POKE 64513,ASC(MID4(TX\$,TX,1)) 4200 NEXT TX 4210 FOR DLA=1 TO 15: NEXT DLA: POKE 64513,13 4220 FOR DLA=1 TO 15: NEXT DLA: POKE 64513,13 4220 FOR DLA=1 TO 15: NEXT DLA: POKE 64513,10 4239 GOTO 4082 5009 REM — LOCAL FILE DUMP ROUTINE 5010 FOR CLS=1 TO 28: PRINT: NEXT CLS 5820 PRINT * >>> LOCAL FILE DUMP ROUTINE <<<<* 5060 FOR H=1 TO LENKLINE\$(G)) 5070 TEMP\$(H)=MID\$(LINE\$(G),H,1) 5080 IF TEMP\$(H)="1" THEN TEMP\$(H)="," 5090 IF TEMP\$(H)="1" THEN TEMP\$(H)=":" 5100 IF TEMP\$(H)="z" THEN TEMP\$(H)=":" 5110 IF TEMP\$(H)="m" THEN TEMP\$(H)=CHR\$(95) 5120 IF TEMP\$(H)="m" THEN TEMP\$(H)=CHR\$(95) 5120 IF TEMP\$(H)="q" THEN TEMP\$(H)=CHR\$(124) 5125 IF TEMP\$(H)="#" THEN TEMP\$(H)=CHR\$(126) 5130 MEXT H 5140 LT=LENKLINE\$(G)): LINE\$(G)=" " 5150 FOR I=1 TO LT: LINE\$(G)=LINE\$(G)+TEMP\$(I): MEXT I 5155 FOR WT=1 TO 1200: MEXT WT 5166 POKE 517,255: PRINT RIGHT\$(LINE\$(G),LT): POKE 517,0 5180 NEXT G 5190 GOTO 4000



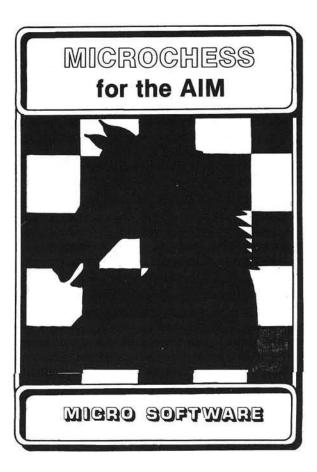
5050 FOR 6=1 TO LN

0010:	CHALLENGER II	0540: 2030 59	= 'Y
0020:	TERMINAL OPERATING SYSTEM	0550: 203D 53	= 'S
0030:	BY PETER KOSKI	0560: 203E 54	= 'T
0040:		0570: 203F 45	= 'E
0050: 2000	TOS ORG \$2000	0580: 2040 4D	= 'M
0060:		0590: 2041 A2 OE	LDXIM \$OE
0070: 2000 A9 20	LDAIM \$20	0600: 2043 BD 19 20 LOOPB	LDAX \$2019
0080: 2002 A0 08	LDYIM \$08	0610: 2046 9D EC DO	STAX \$DOEC
0090: 2004 A2 00	LDXIM \$00	0620: 2049 CA	DEX
0100:		0630: 204A DO F7	BNE LOOPB
	LOOP STAX \$DOOO	0640: 204C A2 19	LDXIM \$19 LDAX \$2027
0120: 2009 E8	INX	0650: 204E BD 27 20 LOOPC	
0130: 200A DO FA	BNE LOOP	0660: 2051 9D 61 D1	STAX \$D161 DEX
0140: 200C EE 08 20	INC \$2008	0670: 2054 CA 0680: 2055 DO F7	BNE LOOPC
0150: 200F 88	DEY	0690: 2057 A2 40	LDXIM \$40
0160: 2010 DO F4	BNE LOOP	0700: 2059 A9 94	LDAIM \$94
0170: 2012 A9 D0 C180: 2014 8D 08 20	LDAIM \$DO STA \$2008	0710: 205B 9D EF D1 LOOPD	STAX \$D1BF
		0720: 205E CA	DEX
0190: 2017 40 41 20	JMP \$2041 = 'C	0730: 205F DO FA	BNE LOOPD
0200: 201A 43 0210: 201B 48	= 'H	0740: 2061 AD OO FC LOOPE	LDA \$FCOO
0220: 2010 41	= 'A	0750: 2064 4A	LSRA
0220: 2010 41 0230: 201D 40	= 'L	0760: 2065 BO 1E	BCS LOCA
0240: 201E 4C	= 'L	0770: 2067 EA	NOP
0250: 201F 45	= 'E	0780: 2068 A9 02	LDAIM \$02
0260: 2020 4E	= 'N	0790: 206A 8D 00 DF	STA SDFOO
0270: 2021 47	= 'G	0800: 206D AE 00 DF	LDX \$DFCO
0280: 2022 45	= 'E	0810: 2070 DO 20	BNE LOCB
0290: 2023 52	= 'R	0820: 2072 OA	ASLA
0300: 2024 20	= '	0830: 2073 FO EC	BEQ LOOPE
0310: 2025 20	= '	0840: 2075 4C 6A 20	JMP \$206A
0320: 2026 49	= 'I	0850: 2078 AO B9	LDYIM \$B9
0330: 2027 49	= 'I	0860: 207A A2 00	LDXIM \$00
0340: 2028 54	= 'T	0870: 207C C8 LOOPF	INY
0350: 2029 45	= 'E	0880: 207D FO E2	BEQ LOOPE
0360: 202A 52	= 'R	0890: 207F E8	INX DDO LOODE
0370: 202B 4D	= 'M	0900: 2080 FO FA	BEQ LOOPF
0380: 2020 49	= 'I	0910: 2082 4C 7F 20	JMP \$207F LDA \$FCO1
0390: 202D 4E	= 'N	0920: 2085 AD 01 FC LOCA	
0400: 202E 41	= 'A	0930: 2088 29 7F 0940: 208A FO D5	ANDIM \$7F BEQ LOOPE
0410: 202F 4C	= 'L	0940: 2084 FO D5 0950: 208C 20 BC 20	JSR \$20BC
0420: 2030 20		0960: 208F 4C 61 20	JMP \$2061
0430: 2031 4F	= '0	0970: 2092 20 ED FE LOCB	JSR SFEED
0440: 2032 50	= 'P = 'E	0980: 2095 C9 OD	CMPIM \$OD
0450: 2033 45		0990: 2097 FO 09	BEQ LOCD
0460: 2034 52	= 'R = 'A	1000: 2099 8D 01 FC	STA \$FCO1
0470: 2035 41 0480: 2036 54	A = T	1010: 2090 20 BC 20	JSR \$20BC
0490: 2037 49	= 'I	1020: 209F 4C 78 2C	JMP \$2078
0490: 2037 49 0500: 2038 4E	= '1 = 'N	1030: 20A2 8D 01 FC LOCD	STA \$FCO1
0510: 2039 47	= 'C	1040: 20A5 20 BC 20	JSR \$20BC
0520: 203A 20	= '	1050: 20A8 AO OA	LDYIM SOA
0530: 203B 53	= 'S	1060: 20AA AD OO FC LOCE	LDA \$FCOO
	1.20		

1070	20AI					LSRA	
1080:						LSRA	
1090:						BCC	LOCE
1100:						STY	SFCO1
1110:				гC			
1120:		1.000		20		LDAIM	
1130:				20		JSR JMP	\$20BC \$2078
1140:				20		CMPIM	
1150:						BEQ	LOCF
1160:			1			CMPIM	SOA
1170:						BEQ	LOCG
1180:				20		LDX	
1190:						STAX	\$20D8 \$D700
1200:				D		LDAIM	
1210:				77		STAX	\$D740
1220:						INC	\$20D8
1230:				20		LDAIM	
1240:				DT			
1250:	and the second second	100 C 100 C	41	D^7		STAX	\$D741
1250:	Contrandia - 14					RTS BRK	
			20		TOOD		#00
1270:				20	LOCF	LDAIM	
1280:						LDX	\$20D8 \$D740
1290:				D		STAX	
1300:		2		DO		LDAIM	\$87
1310:				D7		STA	\$D740
1320:				~~		LDAIM	
1330:			DS	20		STA	\$2008
1340:			10	DO	TODA	RTS	AD010
1350:					LOCG	LDX	\$D240
1360:			00	D2		STX	\$D200
1370:				20		CLC	400PP
1380:			ED	20		LDA	\$20ED
1390:		1.		00		ADCIM	
1400:	COST 802 700 551		ED			STA	\$20ED
1410:			EE	20		LDA	\$20EE
1420:				~~		ADCIM	\$00
1430:			EE	20		STA	\$20EE
1440:	2103		-	~~		CLC	*****
1450:			FO	20		LDA	\$20FO
1460:			01	~~		ADCIM	\$01
1470:			FO			STA	\$20F0
1480:		AD	F1	20		LDA	\$20F1
1490:				~~		ADCIM	\$00
1500:			F1	20		STA	\$20F1
1510:		AD		20		LDA	\$20EE
1520:		0.000	D7			CMPIM	
1530:			D1	12/12/		BCC	LOCG
1540:			ED	20		LDA	\$20ED
1550:		C9	3 F			CMPIM	\$3F
1560:		EA	.			NOP	
1570:						BCC	LOCG
1580:							\$00
1590:						LDAIM	\$20
1600:	2127	9 D	00	D7	LOOPZ	STAX	\$D700

1610:	212A	E8		
1620:	212B	EO	40	
1630:	212D	90	F8	
1640:	212F	A9	40	
1650:	2131	8D	ED	20
1660:	2134	AG	00	
1670:	2136	8D	FO	20
1680:	2139	A9	D2	
1690:	213B	8D	EE	20
1700:	213E	8D	F1	20
1710:	2141	60		
ID=				

\$40
LOOPZ
\$40
\$20ED
202
\$20F0
\$D2
\$20EE
\$20F1



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Classified Ads

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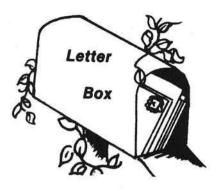
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The following letters are in response to the editorial that appeared in the March issue of Micro. The editorial encouraged readers to write to us about what they'd like to see in a 6516. Here are two of those responses.

Dear Bob,

I just read the March issue, and I am responding to your editorial on the "want list" for a 6516. Here's my list, with the most-wanted features first:

1. Let **all** op-codes use **all** possible addressing modes, so I won't need a wall chart to tell me if this op-code is allowed to use this addressing mode. Haven't you ever written a neat piece of code using, for example, ASLIY (Indirect Indexed), only to find that ASLIY isn't alowed? I may never use INCAY (Absolute Indexed by Y), but I sure would like to know that it's there if I ever want it. In my opinion, this is the best feature of the new 6809: there are no "holes" in the op-code-versusaddress-mode matrix.

2. Change "Zero Page" to "Fast Page", and add the instruction SFP XX (set Fast Page). With the 6502, page zero is prime real estate. With this change, I can turn any page into prime real estate.

3. BRA (Branch Always). This only saves one byte per use (over CLC, BCC), but those bytes do add up.

4. BAS (Branch Always to Subroutine). In other words, a **relative** JSR. This would allow relocatable code without the hassle of subroutine-address look-up tables and zero-page trickery.

5. INA, DEA. Increment and decrement accumulator.

6. PHX, PLX, PHY, PLY. Push and pull X and Y.

7. EAX, EAY, EXY. Exchange A&X, A&Y, X&Y.

8. SSP XX (Set Stack Page). This would make the use of multipe stacks a lot easier.

9. DEL XX (Delay XX Cycles). Better yet, make it DEL XX XX. This would be neater than wait loops, or strings of NOPs and such when equalizing branches. Even better, DEL NN XX..., where NN designates number of following bytes that define delay time.

10. With all of the above, who needs 16 bytes?

Mel Evans Ann Arbor, MI

Dear Dr. Tripp,

I am responding to your question concerning a revised or improved 6502. My first request would be to fill in all those presently used OP codes. I really need more indirect addressing modes like

LDA (\$1234) STA (\$1234) [absolute indirect without index]

I would also like an increment (and decrement) instruction which automatically adds the carry into the next byte. I guess this is a 16 byte instruction.

Of course PHX and PLX would also be helpful to save a few bytes. A new chip would have to be hardware compatible with my present system or I would have no real interest in it.

I heard that serveral years ago MOS Technology had some experimental improved 6502's However, this program ended when they were brought out by Commodore.

> Dr. Morris Midland, MI

I had really expected to receive more suggestions on improvements for the 6502. Does the limited response indicate that you are all **totally** satisified with the 6502 as it is? That **would** suprize me! Even if you only have one small but significant idea, let us know about it. It could make a difference to the future development of the 6502.

μ

AIM 65 File Operations

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AIM BASIC does not have any file access statements. A discussion of this problem and programs to solve it are presented. These programs will greatly enhance the AIM BASIC, and provide some insight into the workings of the AIM. anananan

Christopher J. Flynn

Introduction

By now, most readers of MICRO are familiar with the physical characteristics of the Rockwell AIM 65 microcomputer. The AIM 65 is a computer which comes complete with keyboard, display, and a printer. A few additional ICs will add Microsoft BASIC, a two-pass assembler, and an extra 3K of RAM. All of this can be housed in an attractive case. The result is a truly personal computer. It can be easily moved around the home or office to where the user is. There is no concern about detached video monitors, expansion interfaces, cables, and the like. The AIM is indeed a very versatile computing engine.

This attractiveness of the AIM 65 hardware was the factor that ultimately prompted my wife and me to purchase one. We quickly learned how to operate it. It comes with a one inch thick users manual! Rockwell deserves a lot of credit for not only paying attention to documentation, but also for doing such a good job with it.

Upon contemplating our first home applications, we discovered that not much had been written about the application software capabilities of the AIM. We were happily creating data bases with the very nifty built-in text editor. Our intention was to next use BASIC to perform the desired calculations on the data. This is where we ran into a problem. AIM's BASIC has no file access statements! None of the provided documentation or any other 6502 sources could provide an answer to this dilemma. Did that mean that all that data which we had entered was useless? We will show that the answer to this question is a resounding NO!

We have developed a simple machine language subroutine. This subroutine will allow a BASIC program to read any AIM 65 text file. This includes data entered from the text editor as well as BASIC source program tapes themselves. The subroutine is easy to use. It does some error checking to prevent simple mistakes from ruining your day. It will also tell BASIC when the end of a file has been reached. As a bonus, the subroutine is completely position-independent and ROMable.

Definitions

Before describing our software, we will define a few commonly used terms in AIM 65 context. This will benefit individuals who are just learning to use their AIM's and also MICRO readers who may not be aware of the AIM's capabilities.

File: A file is a collection of data. AIM 65 files may reside on external media such as audio tape or paper tape. AIM 65 audio tape files may, in turn, be in AIM or KIM format. We will be concerned only with AIM 65 format audio tape files.

Each file is given a file name. The file name may be from one to five characters long.

There are two types of AIM 65 audio tape files. One type contains object code data. The other type contains text (or ASCII) data. The subroutine we are presenting will handle only text files.

The AIM 65 has a dual cassette interface. A file may be read (or written) from either drive number 1 or drive number 2. Incidentally, we have found this feature to be very handy.

Block: A block is the unit of information transferred to and from memory and the audio cassette recorder.

All AIM format tape files are blocked. The format of text file blocks is described in the Users Manual. Suffice it to say, each block in any given file will contain the same number of bytes. (The exact block length is a function of the number of leading SYN characters.) Each block, though, will always contain 79 bytes of text data. If necessary, the last block will be padded with zeroes.

Line or Record: A line or record is the unit of information transferred to and from a program and the AIM monitor.

In a text file the lines will naturally contain ASCII data. The maximum line length can vary. The text editor imposes a 60 character limit on lines, while BASIC limits lines to 72 characters. The end of a line, in either case, is marked with a carriage return.

Now here is where it gets tricky. Each block will always contain 79 data bytes. Since the lines can vary in length, a line may be either wholly contained within a block or it may span a block. The machine decides if a line will fit in a block. If not, the line is split in two. This may sound imposing, but don't worry about it. We'll show how this situation is handled later.

End of File: The occurrence of two successive carriage returns on a text file denotes that there are no more lines of data on the file. Upon detection of end of file, we want the BASIC program to stop and not to attempt any more read operations.

Machine Language Subroutine:

"Although Basic is a high level language, it does allow us to communicate with routines that are written in 6502 machine or assembly language. Such routines are known as machine language subroutines."

Appendix F of the BASIC Reference Manual goes into the details on how to make a machine language subroutine and BASIC talk to each other.

Approach

Getting back on track now, the problem we wish to solve is stated as follows:

Develop a capability for making AIM 65 text files accessible to BASIC. One entire line of text should be passed to BASIC at a time. Lastly, BASIC should be informed when an end of file has been detected.

Note that from our earlier definitions, a line may be wholly contained in or may span a block. A key requirement that the subroutine must meet is the reconstruction of text lines when necessary. To satisfy all these requirements both the monitor subroutines and the BASIC USR function will be used.

Two AIM monitor subroutines which we chose for use in the machine language subroutine are:

WHEREI located at \$E848

INALL located at \$E993

These subroutines are described in

the Users Guide. WHEREI asks the user what the current input device will be. Assuming that the user responds with 'T' (for audio tape in AIM format), WHEREI will then ask for the name of the file desired. It will then locate the file on the tape. INALL reads a character from the current input device. If the current input device is an audio tape, INALL will see to the tasks of properly handling lines. INALL will start and stop the tape recorder as necessary in order to obtain a complete line. Thus, two of our requirements are already solved.

Interfacing a machine language subroutine to BASIC is straightforward. The BASIC program simply has to poke the address of the machine language program into memory locations \$04 and \$05. The next step is to invoke the USR function. This will start up the machine language subroutine. The BASIC Reference Manual tells us how to pass a single numeric value to and from BASIC. We will use this feature to pass the line length and end of file indicator to BASIC.

There is one interface problem remaining. That is, how do we pass the text line from the machine language subroutine to BASIC? The USR function limits us to a numeric value. Well, we will be bold and make an assumption. Then we will design the subroutine to fit the assumption. Assume that the BASIC program has defined a character string variable named A\$. Furthermore, assume that the A\$ is 80 bytes long. We can then design the machine language subroutine so that it will locate A\$ in BASIC's memory and store the text data there. If A\$ is guaranteed to be 80 bytes long, we can be sure that text editor and BASIC lines can be read.

There are other approaches to reading these text files. For example, the USR function can be used to call WHEREI. The AIM 65 can then be put in the tape mode. At this point, the BASIC program can issue INPUT statements to read data directly from the tape. This approach is very simple and to the point. However, it suffers from two disadvantages. First of all, since the input device was changed to a tape, the keyboard is deactivated for the entire duration of the file read. This can be nasty, especailly if your program requires some input from the user as it is running. The second disadvantage is that the data on the tape must be in the proper format to be processed by the INPUT statement. This means that there must be commas between values and that string data may need to be enclosed in quotation marks.

At the expense of a machine language subroutine, we have developed a method of reading AIM text files which is completely general. Any text file, including BASIC source programs, can now be read with BASIC. We have addressed the problems mentioned above. The AIM 65 is put in the tape mode only as long as it takes to read one line. The data on the tape can be in any format - you do not have to worry about commas and quotation marks.

Loading the Subroutine

Although our listings show that the subroutine is located at \$7C00, the subroutine is completely position-independent. This means that you can put it anywhere in memory that you like. You will not have to change a single byte of code. Of course, you will have to remember where you put it because BASIC will need to know.

The hex dump in Figure 1 is probably easier to work with when initially entering the machine code. If you prefer to enter the code in instruction format using Figure 2, just be careful of the absolute addresses which appear as branch operands. For ease of future use, you will probably want to store the machine code on tape. Thereafter, the subroutine can be loaded with the 'L' monitor command.

When bringing up BASIC, be sure to respond properly to the MEMORY SIZE question. Respond with the difference of the number of bytes of RAM in your system minus 164 bytes for the subroutine. For example, MEMORY SIZE in a 4K system would be 4096 - 164 or 3932.

Procedure

We hope that the subroutine has been put together so that it is easy

to use. Only three steps are required to read AIM 65 text files:

- 1. Open the file.
- 2. Invoke the USR function.
- 3. Test the USR function return code.

Step 1 - Open the File

A file is opened by zeroing memory location \$F5 (245 decimal). This causes the subroutine to invoke WHEREI in the AIM monitor. In BASIC we open a file as follows:

10 POKE 245,0

If you intend to read more than one file in the same BASIC program, you must open each one of them at the appropriate time with a POKE statement. Only one file can be open at a time.

Step 2 - Invoke the USR Function

One text line or record will be returned to the BASIC program each time the USR function is used. We will illustrate this in BASIC:

> 20 A\$ = "" 30 FOR I = 1 TO 80 40 A\$ = A\$ + "*" 50 NEXT 60 POKE 4,0 70 POKE 5,124 80 L = USR (0)

Lines 20 through 50 set up A\$ as an 80 byte character string in accordance with our design criteria. If the BASIC program does not alter the length of A\$ during subsequent processing, these lines could be moved to the section of the BASIC program that opens the file. The important thing to remember is that the subroutine will insist that A\$ is 80 bytes long — no more or no less.

The contents of A\$ prior to calling the subroutine, however, do not matter. Before giving you any data, the subroutine will always blank out A\$. Thus, you are guaranteed not to encounter any data left over from a previous line.

Lines 60 and 70 are very important! They tell BASIC where the machine language subroutine is located. Line 60 POKEs the low order byte of the address (expressed in decimal) into memory location \$04. Similarly, line 70 POKEs the high order byte of the address into memory location \$05. In our example, the machine language subroutine is located at \$7C00. Make sure you tailor lines 60 and 70 for your system.

If this is the only machine language program that your BASIC program is using, the two POKEs may also be included as part of the file opening logic.

Finally, line 80 invokes the USR function. This causes BASIC to call our machine language program. We are not passing a value to the machine language subroutine. The 0 is just a dummy argument. The machine language subroutine will read the next text line from tape and give it back to us is A\$. BASIC will resume processing with the next statement after line 80.

Step 3 Test the USR Function Return Code

In line 80, the USR function passed a value back to the variable L. We call this value a return code. It can be assigned to any numeric variable - it doesn't have to be L. The value of the return code tells us the status of the read operation.

a. Return code is less than 0

If the return code is negative, this means that an error condition has been detected. Probable error conditions are that A\$ was undefined or not 80 bytes long. (The AIM monitor worries about catching read errors.)

b. Return code is equal to 0

The return code will be set to zero when end of file is reached. No special action is required to "close" the file as it is done automatically.

c. Return code is greater than 0

A successful read operation will be signalled by a return code which is greater than zero. Furthermore, the return code will tell you the actual number of data bytes which were stored in A\$. In other words, it will tell you the line length.

WARNING: Under no circumstances should another read be executed after end of file has been detected. If this should happen, you may have to hit the reset switch to regain control. We might finish our example this way:

90 IF L < 0 THEN STOP 100 IF L = 0 THEN PRINT "DONE":END 110 PRINT LEFT\$(A\$,L) 120 GOTO 80

Lines 90 and 100 terminate the program on an end of file or error condition respectively. Line 110 prints the text line. Line 120 branches back to read the next text line.

Summing It Up

Our sample program is printed in its entirety in Figure 3. Make a couple test files with the text editor. Run the test files through our sample program. You should see the lines of data that you entered printing out one by one. If you encounter any problems, go back and check the machine code carefully. Make sure that you've POKEd \$04 and \$05 with the correct address.

We hope that this capability to read text files adds a new dimension to your computing.

Figure 1

1	1> =	7000	AD	12	A4	48
«	>	7004	A5	75	85	FO
<	>	7008	A5	76	85	F1
<	>	7000	A5	77	C5	FO
<	>	7010	DO	12	A5	78
<	>	7014	C5	F1	DO	00
<	>	7018	AO	FF	A2	FF
<	>	7010	68	8D	12	A4
<	>	7020	8A	60	08	BO
<	>	7024	AO	00	B1	FO
<	>	7028	C9	41	DO	07
<	>	7020	C8	BI	FO	C9
<	>	7030	80	FO	OD	18
<	>	7034	A5	FO	69	07
<	>	7038	85	FO	90	DO
<	>	7030	E6	F1	DO	CC
<	>	7040	AO	02	B4	FO
<	>	7044	99	FO	00	C8
<	>	7048	CO	05	DO	F6
<	>	7040	A4	F2	CO	50
<	>	7050	DO	C6	88	A9

<	>	7654	20	91	F3	88
<	>	7058	10	FB	A5	F5
<	>	7050	DO	08	20	48
<	>	7060	E8	AD	12	A4
<	>	7064	85	F6	AO	00
<	>	7668	A5	F6	8D	12
<	>	7060	A4	20	93	E9
<	>	7070	C9	OA	FO	F9
<	>	7074	C9	OD	DO	OA
<	>	7078	C5	F5	85	F5
<	>	7070	FO	OB	A2	00
<	>	7080	FO	9A	91	F3
<	>	7084	85	F5	C8	DO
<	>	7088	DF	AO	00	AD
<	>	7C8C	34	A4	DO	OA
<	>	7090	AD	00	A8	09
<	>	7094	10	8D	00	A8
<	>	7098	DO	E4	AD	00
<	>	7090	A8	09	20	8 D
<	>	7CAO	00	A8	DO	DA
<						

Subroutine Logic

We've included in this section a technical description of how the machine language subroutine operates. This should give you enough information to modify the subroutine to fit your particular needs.

Figure 4 depicts the logic of the machine language subroutine. The logic is described through the use of Warnier-Orr diagrams. Readers who are not familiar with these diagrams should refer to the December '77, January '78, and March '79 issues of BYTE. Very basically, Warnier-Orr diagrams are interpreted as follows. The sequence in which operations are performed is given by reading from the top of the diagram to the bottom. The hierarchy of functions flows from left to right. As we go through the actual subroutine logic, the power of this design technique will become more apparent.

Figure 5 summarizes the use of zero page variables. These locations are shared with the text editor. However, since the text editor and BASIC do not operate concurrently, there is no conflict.

Upon entry to the subroutine, an AIM monitor variable INFLG is saved on the stack. INFLG tells AIM what the current input device is. Since the subroutine will change the input device to audio tape, we have to be careful here not to lose track of input devices. The next task is to examine BASIC's symbol table to determine if A\$ has been defined as an 80 byte character string according to our design assumptions. In either case, the logic will proceed to a next lower hierarchical level. This is indicated by the next sets of braces to the right. When control is returned back to the first level, IN-FLG is restored from the stack. Most often, this will again put the AIM in the keyboard mode. Finally, the subroutine passes a return code to BASIC. The 16 bit integer return code in registers A,Y (MSB, LSB) is given to BASIC by a JMP indirect to location \$B008 in the BASIC ROM.

Figure 2

K>*=7	000	2		
/40				
	AD	L.DA	A412	Save INFLG
7003				ouro inita
7004			75	Start of BASIC's symbol table
7006				
7008				
7COA				
7000	A5	LDA	77	Reached end of symbol table?
7COE	C5	CMP	FO	наточими и слование и продокти по вознати и на селитерно силонати и при на напати селитерните.
7010	DO	BNE	7024	No
7012	A5	LDA	78	
7014				
7016	DO	BNE	7C24	No
7018	AO	LDY	ØFF	Error exit - set return code to -1
7C1A				
7010				Normal exit
7C1D	8D	STA	A412	Restore INFLG
7C20				
				Return to BASIC
7024				
			(F0),Y	
7C28				Have we found A\$?
			7033	
7020				
			(F0),Y	
7C2F				
			7C40	Detet to want symbol table ontwo
7033				Point to next symbol table entry
7034				
7036				
7038				
7C3A				
7030				
7C3E				Downed Add
7040	AO	LDY	#02	Found A\$
				Get address and length of A\$
			00F0,Y	
7047				
7048				
7C4A				
7C4C	A4	LDY	12	

Assuming A\$ satisfies the design assumptions, the subroutine will set A\$ to blanks. This is done every time the subroutine is called. Next a counter which counts the number of data characters read is zeroed. Then a test is performed to determine if the subroutine is being called for the first time. (NOTE: the success of this test relies on the BASIC program to POKE location \$F5 to 0.) IN-FLG is next restored from a temporary variable at \$F6. The AIM should now be configured to accept input from audio tape. So then the character read routine is called repeatedly until a carriage return is detected and processed.

If A\$ does not meet our design assumptions, the return code is set to -1. This should alert the BASIC program of an error condition.

IF the subroutine is being called for the first time, the AIM subroutine

WHEREI is invoked. WHEREI issues the familiar prompt:

OUT =

Normally the user responds with "T". The AIM monitor will then prompt for the file name and tape drive number. When WHEREI finishes, IN-FLG, which was just set by WHEREI, will be stored in a temporary at \$F6. This completes the initialization sequence.

Figure 3

LIST

10 POKE 245,0 20 AS = "" 30 FOR I = 1 TO 80 40 AS = AS + "*" 50 NEXT 60 POKE 4,0 70 POKE 5,124 80 L = USR(0) 90 IF L < 0 THEN STOP 100 IF L = 0 THEN PRINT "DONE": END 110 PRINT LEFTS(AS,L)

WARNING: Locations 4 and 5 must

be POKEd with the physical address of the machine language subroutine. In this program the subroutine is at \$7C00.

The read character routine calls a lower level read routine until a character other than a line feed is found. The purpose for skipping line feeds, is to facilitate the reading of BASIC source program tapes. (BASIC prefixes each source program line with a line feed.) One of two lower level routines is then invoked depending on whether the character just obtained is a carriage return or not.

The lowest level read character routine is simply an invocation of the subroutine INALL. INALL will obtain a character from the current input device.

If the character obtained is a carriage return, the previously read character is examined. If the current character is not a carriage return, the current character is stored in the next available byte of A\$ (pointed to

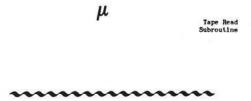
Figure 2 cont.

			Figure	e z cont.
K> *= 7	C4I	2		
/40				
7C4E	CO	CPY	#50	Is A\$ 80 bytes long?
7050	DO	BNE	7018	No, then error
7052	88	DEY		Yes, blank out A\$
7053	A9	LDA	#20	
7055	91	STA	(F3),Y	
7057	88	DEY		
7058	10	BPL	7055	
7C5A	A5	LDA	F5	Is it the first time called?
7050	DO	BNE	7066	
7C5E	20	JSR	E848	WHEREI
7061	AD	LDA	A412	Store new INFLG in a temporary
7664	85	STA	F6	
7066	AO	LDY	#00	
7C68	A5	LDA	F6	Restore INFLG from the temporary
7C6A	8D	STA	A412	variable
7C6D	20	JSR	E993	INALL
7070	C9	CMP	#OA	Ignore line feeds
7072	FO	BEQ	7C6D	
7074	C9	CMP	SOD	Is it a CR?
7076	DO	BNE	7082	No
7078	C5	CMP	F5	Was previous char a CR?
7C7A	85	STA	F5	
7070	FO	BEQ	7 C 8 9	Yes
7C7E	A2	LDX	#00	End of text line
7080	FO	BEO	7010	Return to BASIC
				Store the char in A\$
7084				
7086				
			7068	Now go read the next char
			#00	End of file
			A434	Which tape drive are we using?
			7 C 9 A	· · · · ·
			A800	Turn drive 1 on
7093				
			A800	
			7 C7 E	Exit
			A800	Turn drive 2 on
			#20	
			A800	7-11
7CA2	DO	BNE	7 C 7 E	Exit

by \$F3 and \$F4). The count of the number of characters read is updated.

If the current and previous characters are both carriage returns, end of file has been detected. The proper tape drive is turned back on (INALL turned it off) so the tape can be rewound. Then the return code is set to 0.

If the current character is a carriage return, but the previous character was not, the end of a line has been reached. The return code is set to the count of the number of characters read. Note: the carriage return is neither counted not stored in A\$.



Christopher Flynn became interested in microcomputers when ne assembled a MITS Altair computer kit in 1976. Since then, he has obtained a KIM-1 and an AIM-65. His KIM system interfaces to several S-100 boards by means of a KIMSI Motherboard.

The AIM is his favorite system. It has 32K of RAM and uses a Model 33 teletype for hardcopy output. His software interests include Assembly language and BASIC.

Applications developed on the KIM and AIM range from an interpreter to a home budgeting and accounting system. To support this hobby, Chris is employed by the Fairfax County government as a systems analyst for the county's tax systems.

Christopher's wife, Nancy, has learned to program in BASIC. Their two year old daughter, Becky, when asked what her father's name is, has been known to respond, "6-5-0-2".

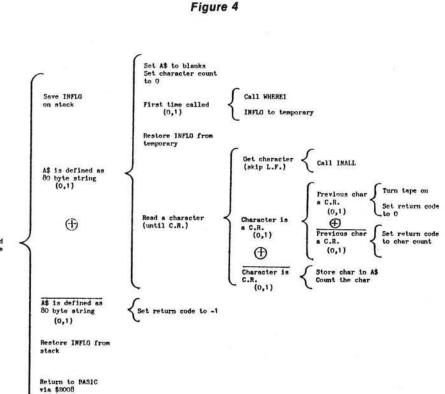


Figure 5

SYMTAB	\$F0,\$F1	Pointer to BASIC symbol table
LEN	\$F2	Length of A\$
APNT	\$F3,\$F4	Pointer to A\$ in BASIC's memory
TEMP	\$F5	First time switch; hold area
TINFLG	\$F6	INFLG hold area

m

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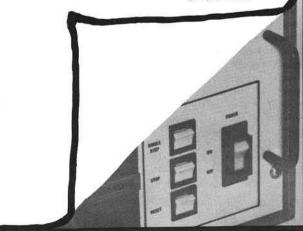


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MICRO Club Circuit

Here is yet another installment of 6502-related clubs. We continue to be encouraged by the terrific response to our request for new clubs. Now we have so many that we can't print them all in a single two-page listing!

If you have registered with us and you are not presented here, do not be dismayed. Next month you will be first on the list! The mail has just been loaded with club information.

Those of you who are listed please take a moment to make sure that the information is correct. Notify us of any errors. Up-dates should be sent to us periodically.

Does your club publish a newsletter? Do you need advertiser's? Want to exchange an ad? If the answer to any of these questions is yes, then let us know!

To become an officially registered club please send for the correct form. This is the only way to get a free one year subscription for your club's library. Have your club listed to increase your membership.

Address any information or requests to:

> **MICRO Club Circuit** P.O. Box 6502 Chelmsford, MA 01824

Western Educational Computing Conference, San Diego, California

November 20, 21

The theme of the seminar/exhibit is "Educational Computing in the '80's" and will feature papers and seminars on the use of computing in higher education for instruction, administration, and research. Luncheon speakers will be Capt. Grace Hopper, USN, and Bernard Luscombe, President, Coastline College.

For further information contact: **Ron Langley Director, Computer Center** California State University 1250 Bellflower Boulevard Long Beach, California

90840

26:68

Texas A&M Micro Computer Club

This club meets every two weeks on Wednesday nights. Conrad G. Walton Jr. is the President of 80 members. He can be contacted at: Box M-9

Aggieland Station, TX 77844

"The club owns 2 8K Pets and one SWTPC 6800 system with Pencom disk. Aim to provide education for the community in the applications and use of micro-computers."

Forth Interest Group

This educational club asserts that their world-wide membership is 950. They meet on the fourth Saturday of the month. They list no contact person but the address for their club is P.O.Box 1105

San Carlos, CA 94070

Apple Information and Data Exchange

Meets on the second Tuesday of each month at: **Computer Corner** 1800 S. Georgia Amarillo, TX 79109 George Johnson is the President of AIDE. Theiraddress is: 5700 Dixon Amarillo, TX 79109 "Mutual aid and sharing of information."

Apple Puget Sound Program

Meets on the second Tuesday of each month. Over 3000 members. Dick Hubert is the President. A.P.P.L.E. Library Exchange. Contact:

Fred Merchant, Sec. 517-11th Avenue East Seattle, WA 98102 "Assists its members in the use and

understanding of the Apple Computer. One time Apple-Cation fee and annual dues."

Madison Pet User's Club

Meets on the first Thursday of the month at 7:30 pm in the Washington Square Building. Membership around 50. Contact: **B.A. Stewart**

MICRO -- The 6502 Journal

501 Willow W. Baraboo, WI 53913 "Exchange Information."

New England Computer Society

Meets on the first Wednesday of the month at the Mitre Corporation Cafeteria in Bedford, MA. Robert Waite is the President over 200 members. Contact:

> David Mitton, Sec. P.O.Box 198

Bedford, Mass. 01730

"General purpose, personal/hobby computing, technical information sharing.'

San Francisco Apple Core

Meets first Saturday of the month. Randy Fields is President. Membership of over 800. Contact:

Randy Fields P.O. Box 4816 San Francisco, CA 94101

Winnipeg Apple Computer Group

Meets on the first Thursday of each month at 7:30 in the Computerland Store. Acting President is Mike Flood. Membership is still growing over 30 currently. Contact Mike at:

5-1730 Taylor

Winnipeg, Manitoba Canada, R3N 0N8

"Increase members knowledge of programming, hardware, and data processing. Newsletter."

Burlington Micro Club

Meets on the last Wednesday of the month at 7:30 pm at various locations. William Morris, President over 25 members. Contat him at:

67 Moxley Drive Hamilton, Ontario Canada, L8T 3Y8 "Membership is open to everyone. Micro user '80, a club newsletter."

6502 Comp-Club

Meets at various places. Members and those interested are notified through the mail as to the monthly arrangements. Robert Wilson is club President. Over 25 members. For current information contact:

R. Wilson Box 6007

Lawrenceville, N.J. 08648 "Purpose: To consumate interest and to further knowledge of 6502 computers."

Erie Apple Crunchers

Rudy A. Guy is President over this newly organized group of 25 avid users. Contact them for more information:

P.O. Box 1575

Erie, PA 16507 "Membership is open to all Apple or Bell & Howell Apple owners or users. Developing a software library and we are willing to exchange software with other individuals or groups."

N.I.C.H.E. Northern Indiana Computer Hobbyist

Meets in the South Bend area on the last Monday of almost every month. Contact:

Eric Bean 927 S 26 Street South Bend, In 46615 "The meetings are open to all computer hobbyists, but is dominated

Apple Byter's Computer Club

Information regarding this club should be requested from S.E. Grove, Pres., Mail Station 33, Bldg R-19

H.E.S.E.A. Hughes Aircraft 2060 Imperial El Sugundo, CA 90245

"A private club for Hughes Employees only but open to guests. Education of members in the use of computers by programmers and others. Buy at group rates, exchange software in public domain, and member of the I.A.C. (international Apple Core) Grow with others in the Greatest Hobby EVER!"

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OSIO

Washington, VA, MD group meets the first Tuesday of each month. Meets at the Walter Johnson High School in Rockville, Md. Contact: Wallace Kendall, Pres. 9002 Dunloggin Road Ellicott City, MD 21043 "Study, advance, and promote the application of computers; publish newsletters; sponsor conferences, workshops, symposia, demonstrations, and publications on computers, etc."

Apples British Columbia Computer Society

Meets first Wednesday of every month at 7:30. Various locations. Gary Little is President for 95 members. Contact him at:

101-2044 West Third Ave Vancouver, B. C. Canada V6J 1L5

"All members are Apple II owners, aim is to discuss software and hardware."

Apple Sac

Meets on the first Tuesday and third Wednesday of each month, with Assembly language classes on the third Tuesday. Bill Norris is president. 80 plus members. Contact:

Jerry Jewell Computerland of Sacramento 1537 Howe Avenue Sacramento, Ca 95825 "Fun. education, social, sharing of

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The MICRO Software Catalog: XXII

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Name:ALGEBRASystem:PET 2001Memory:8K or moreLanguage:BASIC, Machine

Description: A series of 7 programs (on one cassette) designed to assist a student through various levels of the subject. Topics include: Set operations, signed arithmetic, linear equations, factoring, and quadratic equations. An example of each class of problem is given, followed by a changing sequence of problems to be solved by the student. After each problem, as answer is provided to check results. Other Pet software available.

Copies: Price:	New Release \$19.95
Author:	Len Bugel
Available:	TYCOM Associates 68 Velma Avenue
	Pittsfield, MA 01201
Name:	Computer Station Single Disk Copy
System:	Apple II or Apple II Plus
Memory:	32K
Language:	Integer Basic or Ap- plesoft
Hardware:	Apple II, Disk II

Description: Program will copy a complete diskette using an Apple II with only a single disk drive. The program will function properly on an Apple II or Apple II Plus with or without the Applesoft ROM Card or the Language System. It will run with DOS 3.1, DOS 3.2, or DOS 3.2.1 and will run on either a 32K or 48K system. On a 32K system it will take five passes for a full diskette while only three on with 48K. Requires a maximum of 3 passes on a 48K system, does verification, will initialize if desired and is faster than Apple's two disk copy. Price:

Includes: Author: Available: Name:

System: Memory: Language: Hardware: 12 Crossroads Plaza Granite City, IL 62040 AMATEUR RADIO COMMUNICATIONS PACKAGE Apple II, Plus 16K Interger Radcom Plus Card (supplied), Disk II

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Mike Rowe P.O. Box 6502 Chelmsford, MA 01824

> San Diego, CA 92105

Name:	The Creativity Life
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System:	Apple II
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Language:	Applesoft, Machine
Hardware:	Apple II, Disk II

Description: Draw, Write Music, Write Poetry! Draw Circles, elipses, triangles, frames, enclosures, fireworks, squares, etc. (many more!) all at the touch of a key or two (without hitting return). Fill or partially fill any of the above figures to create an infinite variety of figures. Change to and from Regressive & Symmetry Modes. Write Music using your keyboard like a piano. Watch your notes be named and written on a cleff. Easily change pitches and durations. Write a poem. Choose 1, 2, or 3 forms, save and play later! MUCH MORE!!

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	P.O.Box 30161 MCC
	Eugene, OR 97403
Name:	GAF Software Utili-
	ty Packages 1 & 2
System:	Apple II, Plus
Memory:	32K
Language:	Integer, Applesoft
Hardware:	Apple with Disk II

Description: A collection of useful utility programs. Utility 1: File Compare, a program that allows comparing of two versions of a program and reporting all differences to your

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Price:	\$30.00 each
	\$50.00 both
Author:	Gary A. Foote
Available:	GAF Software
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Name:	LCMOD for Pascal
System:	Apple
Hardware:	Apple Language
	System

Description: Allows DIRECT entry of upper/lower case into the Pascal Editor using the Paymar LCA. Uses the ESC key for a shift key and the ESC key is now a Control Q to prevent accidental deletion of text. Also provides generation of left and right curly brackets for comment delimiters and an underline for VARs, program names and file names.

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	ware 7270 Culpepper Drive
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Name:	MAG Files
System:	Apple
Hardware:	Disk II

Description: Having trouble keeping track of all those magazine articles you read? Here is the answer. Enter them once and use the search modules to find them again either by title or subject code. Requires Applesoft II.

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Name:	
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Bad Buy Diskette Apple **Disk II**

Description: Of course it is a bad buy. If you had issues 2 through 11 of the Southeastern Software NEWSLETTER, you could type these programs in yourself. They are a mix of Integer, Applesoft II and assembly language programs and utilities.

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Description: Provides 21 digit precision for Applesoft programs. Arithmetic expressions, as well as INPUT and PRINT are supported. Applesoft subroutines for the standard math functions are included. Nearly standard syntax is used, with the ampersand feature. Efficient and compact, only 2048 bytes. Loads itself beneath your Applesoft prog. Works with Applesoft ROM card, with Applesoft in the Language System, or with RAM Applesoft.

Copies:	25
Price:	\$50.00
Includes:	Diskette, Reference Manual
Author:	Bob Sander- Cederlof
Available:	S-C Software P.O.Box 5537 Richardson, TX 75080
Name: System: Memory: Language: Hardware:	Letter Perfect Apple II, Plus Min. 32K Machine Apple II, Plus/ 32K min/ Dan Paymar
Description:	Lower Case.

Description: A character orientated word processor. It supports proportional spacing and is capable of working with any printer type. It is user orientated and menu driven. Complete documentation. Supports: global and local searches, complete formating, full ASC II character set with lower case on video display, headers, footers, page numbering, complete formating within body of text, top margin, and much more! Full cursor control.

Author:	Kenneth Leonhardi
Available:	LJK Enterprises,
	Inc.
	P.O.Box 10827
	St. Louis,MO 63129
Name:	Gus's Disk Utility
System:	Apple II
Memory:	16K, 32K, 48K
Language:	Machine
Hardware:	Apple II, Disk II

Description: Program is designed to be an easy to use aid to working with the Apple II DOS 3.1 or DOS 3.2. Restore those accidentially deleted files, remove DOS from your diskette for more room on your data only disks, read/write to any sector, print file attributes (catalogs your disk and allows to choose any file on the diskette to give you file type, track sector list, the sector lists which contains your program), prints binary program parameters, and will map the free sectors of your diskette. Allows individual byte or sectors to be changed or transfered to another diskette.

Copies:	Just released \$45.00
Price: Author:	Ralph D. Gustafson
Available:	Rainy City Software 4360 SW Parkview Portland, OR 97225
Name:	Disk Apple II Report
System:	Apple II Or Apple II Plus
Memory:	32K
Language:	Applesoft II
Hardware:	Disk II, optional printer
	and lower case adapter

Description: A program which composes reports, articles, letters and other documents, utilizing text files generated by the "DOS Text Editor". Text may be input in free form format, without regard to line length or pagination. Retrieves the data from

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Includes:	Diskette, user manual, and documentation		
Author:	Robert Stein		
Available:	Services Unique, Inc. 2441 Rolling View Dr. Dayton, Ohio 45431		
Name:	Disk Text Editor- Edit II		
System:	Apple II or Apple II Plus		
Memory:	Minimum 24K		
Language:	Applesoft BASIC		
Hardware:	Apple, disk and op- tional printer and lower case adapter.		

Description: An improved version of the DOS Text Editor, designed to create and facilitate changes to disk files, reports, lists, etc. Also supports the cassette as a file device. Includes 35 commands. String commands allow searching, changing, and listing of single records or blocks of records for a specified word or phrase. User input. File commands merge input from various files, parts of files and text buffers. Handles full upper and lower case ouput to print devices. Works with DART.

Copies:	Over 200 of Edit-I	ava
Price:	Cassette \$19.95 Diskette \$23.95	Co
Includes:	Shipping \$1.95 User manual and documentation	Inc
Author: Available:	Robert A Stein, Jr. Apple Computer Stores or Services Unique, Inc.	Aut Ava
	2441 Rolling View Dr. Dayton, OH 45431	Na

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Applesoft
1 Disk Drive

Description: This program was written to speed up the process of writing advanced business program. It works as a data management system, but also writes disk statements as permanent line number, if requested. Supports 20 fields per entry, searching or sorting by any field, generating reports, packing numbers to increase disk space, plus many more. Use for inventory, checks, phone bumbers, etc. Simple to use with instructions.

Price:	\$29.95		
Copies:	Just released		
Includes:	Diskette,		
	instructions, examples		
Author:	Wilford Niepraschk		
Available:	Wilford Niepraschk		
	5921 Thurston Avenue		
	Virginia Beach, Va		
	23455		
Name:	Visible Memory		
Hame.	Routines		
System:	8K PET		
Memory:	2K		
Language:	Machine Language		
Hardware:	8K PET, MTU Visible		
	Memory Board		

Description: Machine language software easily accessable by BASIC. Package includes clear screen, plota-point, line draw, and ROSE plotting programs. Other programs available to run with VM Routines: VM LISS-3D space Art, VM Sprirals, Hi-resolution spirals, VM 3D Plots, same 3D images as seen in many ads. More coming. Send SASE for list of these and other programs. Copies of MTU user's Notes ailable.

opies: ice:	Just released \$7.95 for VM Routines
cludes:	Cassette, Documenta- tion
uthor:	Russell A. Grokett, Jr.
vailable:	Pet Library 401 Monument Road
	Jacksonville, FL 32211
ame:	PSA/1

System: Apple II, Plus Memory: 16K Language: **Applesoft Basic** Hardware: Apple II (Printer, opt) Description: A cassette-based introduction to computer scheduling. Using critical-path scheduling techniques, it allows the user to define a project, input time estimates for each job in the project, and then compute schedules for each job. Computes the earliest and latest each job can be started, finished, in order to meet deadlines. Also schedules delays without harm to other jobs. Displayed on video.

Copies: Price: Includes: Author: Available:	New Release \$25.00 (WA add 5 %) Cassette, User Manual Don Taylor Express Marketing 21866 Clear Creek Road P.O.Box 1736/MSC Poulsbo, WA 98370		
Name:	Files		
System:	Apple II 3.2 or 3.2.1 DOS		
Memory:	32K min.		
Language:	Applesoft		
Hardware:	Disk necessary, Printer optional		

Description: File is a modular File utility program which is designed to allow the user to build files, add to existing files, correct records, delete, lock, unlock, insert records, move records, delete records, find records, sort, append files together. rename and save files, and view file data.

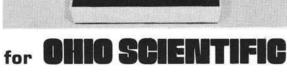
Copies:	Just released		
Price:	\$49.95		
Includes:	Disk and manual		
Author:	Marc Goldfarb 55 Pardee Place		
	New Haven, Conn.		
	06515		

While we have been lenient in the past regarding the length of the entries in the Software Catalog, we must now insist that future entries be kept as brief as possible. We think that twelve to fifteen lines in the "description" part of the entry should keep it about right. The other parts, as long as needed.

We now have so many entries backed up, that we feel this policy is only fair to give everyone 'equal time'. We will be fored to edit, or return any entries that we judge too long. Mike Rowe







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This amazing program was written by a professional software consultant to TRW Space Systems and is being introduced by the publishers of Computers and Gambling Magazine. "PHD-1" is a large complex basic program requiring a full 16K. It is carefully human factored for easy use. PHD-1 is a comprehensive horse racing system for spotting overlays in thoroughbred sprint races (less than 1 mile). You simply sit down with your computer and the Racing Form the night before the race and answer 5 or 6 questions about each horse's past performance. Your computer then accurately predicts the win probability and odds-line for each horse allowing you to spot overlaid horses while at the track. The users manual contains a complete explanation of overlay bet-ting.

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6502 Bibliography: Part XXII

Continuing bibliography of 6502 related material

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Micklus, Lance and Summers, Murray, "Dog Star Adventure," pg. 36-48. Rescue the Princess Leya.

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Howerton, Christopher, "Grandapple Clock," pg. 104-107. Now your Apple can tick, chime, and keep time.

Carpenter, Chuck, "Apple-Cart," pg. 134-137.

Discusses Keyword search, the MOD function, New Apple products, etc.

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Discusses short utility routines, a programming for formatting numbers, etc.

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Utility routine.

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Discusses New Pet Products, Axiom Printers, Programming Ideas and Tips.

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Customize your PET.

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Dr. William R. Dial 438 Roslyn Avenue Akron, OH 44320

Lightning-fast number crunching.

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Construct this counter for your PET cassette and locate files quickly and accurately.

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The Selectric finds another home.

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Here is all you need to make your OSI Model 600 board run twice as fast as it normally does.

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How to use the ONERR GOTO instruction on the Apple.

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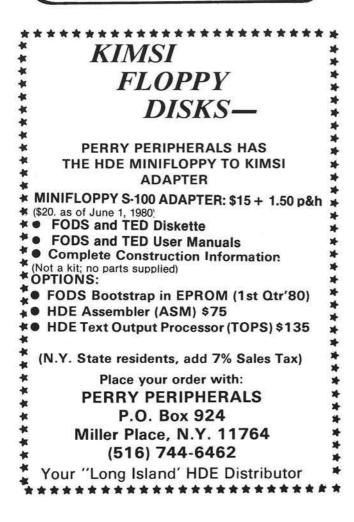
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